

# Physics 507 Homework Solution #12

1. If we use polar coordinates, the potential energy is  $U = -K/r$ , the kinetic energy is  $T = \frac{1}{2}\mu v^2 = \frac{1}{2}\mu(\dot{r}^2 + r^2\dot{\theta}^2)$ . The momenta conjugate to  $r$  and  $\theta$  are then  $p_r = \mu\dot{r}$  and  $p_\theta = \mu r^2\dot{\theta}$  respectively, and as the Lagrangian has no explicit time dependence and  $\theta$  is an ignorable coordinate, the Hamiltonian  $H = p_r^2/2m + p_\theta^2/2mr^2 + K/r$  and  $p_\theta$  are conserved, *i.e.* are integrals of the motion. Note  $p_\theta$  is the angular momentum about the  $z$ -axis, *i.e.* perpendicular to the plane.

a) Thus  $F_1 = H$  and  $F_2 = p_\theta$  are two integrals of the motion.

b) As  $\theta$  does not appear in  $H$ ,  $[H, p_\theta] = 0$ , and the two are in involution.

c) For a given  $\vec{f} = (E, L)$ , the manifold  $\mathcal{M}_{\vec{f}}$  consists of all points in phase space consistent with that  $E$  and  $p_\theta = L$ . As the semi-major axis and ellipticity of the elliptical orbit is determined by  $E$  and  $L$ ,  $\mathcal{M}_{\vec{f}}$  has all points possible for all such ellipses. Thus its projection onto coordinate space is an annulus with perigee and apogee  $r_p$  and  $r_a$  as the radii. The momentum  $p_r$  is given, modulo sign, by  $\sqrt{2m(E - U(r))}$ , so our invariant torus really is a torus. The remaining momentum,  $p_\theta$ , is a constant. We may choose  $\eta_0$  any point on it, so let  $\eta_0 = (r_a, 0, 0)$

The other points in  $\eta \in \mathcal{M}_{\vec{f}}$  are generated by the canonical transformation  $g^{\vec{f}}$ , *i.e.*  $\eta = g^{\vec{f}}(\eta_0)$ . The parameters  $t_1, t_2$  give the parameters by which the generators  $F_1 = H$  and  $F_2 = p_\theta$  have been applied. The momentum as a generator generates a translation in the conjugate coordinate, so  $\eta = (r, \theta, p_r) = g^{0, t_2}(\eta_0) = (r_a, t_2, 0)$ , while the generator  $H$  moves the phase space point forwards in time according to the standard newtonian laws. Thus if we solved the Kepler problem for  $\vec{r}(0) = r_a\hat{e}_x$ ,  $p_r(0) = 0$ ,  $p_\theta = L$ , the solution  $(r(t), \theta(t), p_r(t))$  is the value  $\eta = g^{t, 0}(\eta_0)$ .

d) Clearly  $\theta \rightarrow \theta + 2\pi$  brings us back to the same point in phase space, so there is a periodicity under  $t_2 \rightarrow t_2 + 2\pi$ . We also know the dynamical motion is periodic with period  $T = \pi K \sqrt{\mu/2} (-E)^{-3/2}$ , so this is the period of  $t_1$ . Thus the  $\vec{e}_i$  are  $(0, 2\pi)$  and  $(T, 0)$  respectively,  $A$  is diagonal with elements  $T/2\pi$  and 1, and the frequencies  $\omega_i = (A^{-1})_{i1} = (2\pi/T, 0)$ .

e) The relation  $\omega_2 = 0$  is a relation among the frequencies, which is there independent of the values  $\vec{f}$  of the integrals of the motion, so we have here a degenerate system.

2. Using polar coordinates,

$$H = \frac{p_r^2}{2m} + \frac{p_\theta^2}{2mr^2} + U(r),$$

for which  $\theta$  is an ignorable coordinate and thus  $p_\theta = L$  is an integral of the

motion (and conserved). Thus  $F_1 = H$  and  $F_2 = p_\theta$  are the integrals of the motion in involution required for our problem to be an integrable system.

The invariant torus is the region of phase space for which  $H(r, \theta, p_r, p_\theta) = E$ ,  $p_\theta = L$ . (In terms of the general discussion,  $\vec{f} = (E, L)$ .) As  $\theta$  does not enter these constraints, the torus is the cartesian product of the one-dimensional solution of

$$E = \frac{p_r^2}{2m} + \frac{L^2}{2mr^2} + U(r)$$

with the unit circle for  $\theta$ . For negative  $E$  the system is bound, and the motion  $r(t)$  is periodic, with some period  $\tau_r$ , with  $r$  confined to the region  $r \in [r_{\min}, r_{\max}]$ . The evolution of  $\theta$  is also determined simply by  $\dot{\theta} = L/mr^2$ . Notice  $\dot{\theta}$  is not constant, but it never changes sign.

The action of  $p_\theta$  on  $\mathcal{M}_{\vec{f}}$  is particularly simple, as  $D_{p_\theta} = -\partial/\partial\theta$ , and has no effect on  $r$  or  $p_r$ .  $D_H$ , on the other hand, generates the dynamical motion expected from Newton's equations, so that  $r$ ,  $p_r$ , and  $\theta$  all vary with time  $t_1$ . Suppose we chose  $\eta_0$  to be the point  $(r = r_{\max}, p_\theta = 0, \theta = 0)$ . The action of  $t_1 H$  on this point,

$$g^{t_1 H}(\eta_0) = (r(t_1), p_r(t_1), \theta(t_1)),$$

so given any point  $\eta = (r, p_r, \theta)$  on  $\mathcal{M}_{\vec{f}}$ , we can find a  $t_1 \in [-\tau_r/2, \tau_r/2]$  determined by the magnitude of  $r$  and the sign of  $p_r$ . Then to make  $\eta = g^{t_1 H + t_2 p_\theta}(\eta_0)$ , we need only to choose  $t_2 = \theta - \theta(t_1)$ .

The generator  $p_\theta$  clearly brings  $\eta_0$  back to itself for  $t_2 = 2\pi$ . The action of  $H$  is more complicated — to get back to the same  $(r, p_r)$  we need  $t_1 = \tau_r$ , but that changes  $\theta$  by some angle  $\Delta\theta = \theta(\tau_r)$ . This is undone by  $t_2 = -\Delta\theta$ . Thus the generators of the unit cell are  $\vec{e}_1 = (\tau_r, -\Delta\theta)$  and  $\vec{e}_2 = (0, 2\pi)$ .

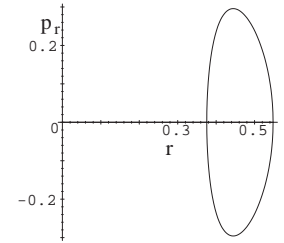


Fig. 1. The cross section of the invariant torus for a given value of  $\theta$ . This is for  $U(r) = -K/r^{3/2}$ , with  $m=1, L=1, K=1, E=-0.8$ .

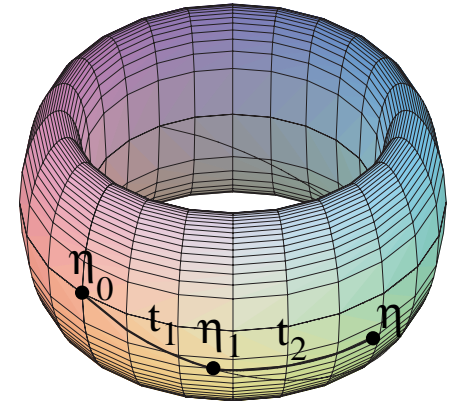


Fig. 2. The invariant torus. The point  $\eta_0$  flows under the generator  $t_1 H$  to  $\eta_1$ , and then under  $t_2 p_\theta$  to  $\eta$ .

Then as  $2\pi A_{ji} = (\vec{e}_i)_j$ ,

$$A = \begin{pmatrix} \frac{\tau_r}{2\pi} & 0 \\ -\frac{\Delta\theta}{2\pi} & 1 \end{pmatrix}, \quad A^{-1} = \begin{pmatrix} \frac{2\pi}{\tau_r} & 0 \\ \frac{\Delta\theta}{\tau_r} & 1 \end{pmatrix}.$$

Defining the  $\phi_i$  by  $\vec{t} = \sum_j \phi_j \vec{e}_j / 2\pi$ , ( $t_i = \sum_j A_{ij} \phi_j$ ,  $\vec{\phi} = A^{-1} \cdot \vec{t}$ ), so

$$\omega_i = (A^{-1})_{i1} = \left( \frac{2\pi}{\tau_r}, \frac{\Delta\theta}{\tau_r} \right).$$

We see in particular that  $\delta\phi_2 = \delta t_2 + \Delta\theta\delta t_1/\tau_r$  is not just the  $\delta t_2$  generated by  $p_\theta$ , for the Hamiltonian  $F_1$  does make  $\theta$  flow.

The Hamiltonian produces a flow spiraling around the torus, while  $p_\theta$  produces only a rotation about the  $p_r$  axis. The ratio of the frequencies is  $\omega_2/\omega_1 = \Delta\theta/2\pi$ , so there will be a relation among the frequencies if  $\Delta\theta/2\pi$  is rational. For example, we show the trajectories (of hamiltonian motion) for two different energies, with  $\Delta\theta = 0.70597.. \times 2\pi$  and  $\Delta\theta = \frac{2}{3} \times 2\pi$ .

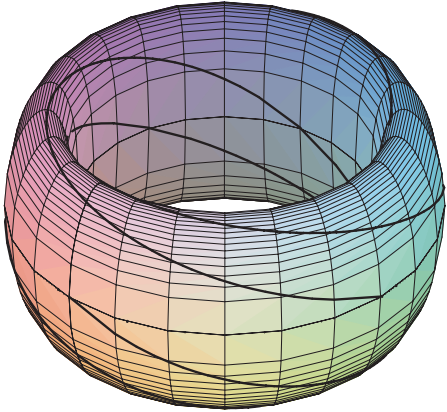


Fig. 3. Hamiltonian flow in the situation of Fig. 1, with  $E = -0.8$ .

Each invariant torus corresponds to a given value of  $E$  and  $p_\theta$ . For different  $E$  the tori are nested inside one another, as shown. In the case pictured here, corresponding to an attractive central force  $F = -Kr^{-5/2}$ , the ratio of the periods depends on the energy. In particular, Fig. 3 fits between the the torus with  $E = -0.82$  and the torus (half cut away here) with  $E = -0.75$ , and both are inside of the torus shown in Fig. 4.

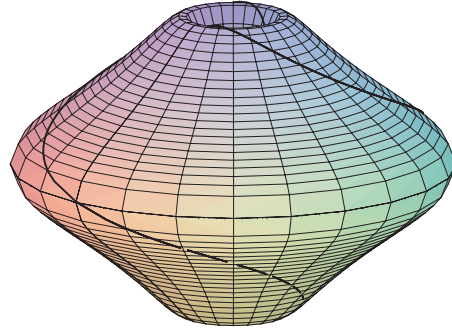


Fig. 4. With the energy changed to  $E = -0.24$ ,  $\Delta\theta = 4\pi/3$ , so there is a relation among the frequencies with  $k_1 = 2, k_2 = -3$ .

