

1. Ans: for any arbitrary state:
See page 115 of Griffiths
2. Ans: for any stationary state but not for any arbitrary state: See page 26 of Griffiths.
3. Ans: the same as #1, which is
for any arbitrary state
: see Griffiths, page 115.
4. No. Because $H = \frac{p^2}{2m} + V(x)$, $[x, p] = ik$, x and H does not commute. Any non-commuting observables cannot share the same eigen state.

$$5. |\psi_a\rangle = |\psi_1\rangle + 2|\psi_2\rangle = \begin{pmatrix} 1 \\ 2i \end{pmatrix}$$

$$|\psi_b\rangle = i|\psi_1\rangle + |\psi_2\rangle = \begin{pmatrix} i \\ 1 \end{pmatrix}$$

$$, |\psi_{b_n}\rangle = \frac{|\psi_b\rangle}{\|\psi_b\|}$$

$$\psi_x = \psi_a - \psi_b'$$

$$|\psi_i'\rangle = |\psi_{b_n}\rangle \cdot \langle \psi_{b_n} | \psi_a \rangle$$

$$= \frac{1}{\|\psi_b\|^2} |\psi_b\rangle \langle \psi_b | \psi_a \rangle$$

$$\langle \psi_b | \psi_a \rangle = (-i, 1) \begin{pmatrix} 1 \\ 2i \end{pmatrix} = -i + 2i = i$$

$$\|\psi_b\|^2 = (-i, 1) \begin{pmatrix} i \\ 1 \end{pmatrix} = 2$$

$$\therefore |\psi_b\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}$$

$$\begin{aligned}\psi_x &= \begin{pmatrix} 1 \\ 2i \end{pmatrix} - \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix} = \begin{pmatrix} 1 \\ 2i \end{pmatrix} - \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{i}{\sqrt{2}} \end{pmatrix} \\ &= \begin{pmatrix} 1 + \frac{1}{\sqrt{2}} \\ 2i - \frac{i}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} \frac{3}{\sqrt{2}} \\ \frac{3i}{\sqrt{2}} \end{pmatrix} = \frac{3}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}\end{aligned}$$

$$\therefore \psi_{x \text{ norm}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}$$

check $\langle \psi_{x \text{ norm}} | \psi_b \rangle = (1-i)\begin{pmatrix} 1 \\ i \end{pmatrix}$

$$= 1 - i = 0$$

$\therefore \psi_{x \text{ norm}}$ is orthogonal
to ψ_b

6. Spatial part: $\psi_{321} \Rightarrow n=3, l=2, m=1$
Spin part: $s=\frac{1}{2}, m=-\frac{1}{2}$

$$(a) L^2 \Rightarrow \hbar^2 l(l+1) = \hbar^2 \cdot 2 \cdot 3 = 6\hbar^2$$

$$(b) J = |l+s| \dots (l-s)$$

$$\Rightarrow 2 + \frac{1}{2} = \frac{5}{2} \quad \text{or} \quad 2 - \frac{1}{2} = \frac{3}{2}$$

$$m_J = m_s + m_s = 1 - \frac{1}{2} = \frac{1}{2}$$

7. $\mathcal{Y} = A \sin \theta \cos \phi = \frac{A}{2} \sin \theta (e^{i\phi} + e^{-i\phi})$

$$\text{Now } \mathcal{Y}_1 = -\sqrt{\frac{3}{8\pi}} \sin \theta e^{i\phi}$$

$$Y_1^{-1} = \sqrt{\frac{3}{8\pi}} \sin\theta e^{i\phi}$$

$$\Rightarrow Y = \frac{A}{\sqrt{2}} \cdot \left(-\sqrt{\frac{8\pi}{3}} Y_1^1 + \sqrt{\frac{8\pi}{3}} Y_1^{-1} \right) \\ = -\sqrt{\frac{2\pi}{3}} A (Y_1^1 - Y_1^{-1})$$

Because $\langle Y_1^1 | Y_1^1 \rangle = 1$, $\langle Y_1^{-1} | Y_1^{-1} \rangle = 1$

$$\Rightarrow \langle Y | Y \rangle = 1 \Rightarrow \frac{2\pi}{3} A^2 (1+1) = 1$$

$$\Rightarrow A^2 = \frac{3}{4\pi} \Rightarrow A = \underbrace{\sqrt{\frac{3}{4\pi}}}_{\text{---}}$$

$$\Rightarrow Y = -\frac{1}{\sqrt{2}} (Y_1^1 - Y_1^{-1})$$

\hookrightarrow / $Y_e^m \Rightarrow$ so $l=1$, 100%
 $m=1, 50\%$
 $m=-1, 50\%$

$$8.(a) H = -q B_0 \vec{S}_z = -\frac{\hbar}{2} q B_0 S_z \\ = -\frac{\hbar}{2} q B_0 \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

\hookrightarrow / $S_x \Rightarrow \frac{\hbar}{2}$ means the state should be
the corresponding eigenstate

$$S_x \begin{pmatrix} a \\ b \end{pmatrix} = \frac{\hbar}{2} \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 0 \Rightarrow a = b$$

i.e. The eigenstate should be $\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$$\Rightarrow X(0) = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

(c) Because $X(0) = \frac{1}{\sqrt{2}} \left[\begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right]$

and $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$ is the eigenstate of the Hamiltonian with $E_1 = -\frac{\hbar}{2}\alpha B_0$

and $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ is that for $E_2 = \frac{\hbar}{2}\alpha B_0$

$$X(t) = \frac{1}{\sqrt{2}} \left[\begin{pmatrix} 1 \\ 0 \end{pmatrix} e^{-i\frac{E_1}{\hbar}t} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} e^{i\frac{E_2}{\hbar}t} \right]$$

$$= \frac{1}{\sqrt{2}} \begin{pmatrix} e^{-i\frac{\alpha B_0}{2}t} \\ e^{i\frac{\alpha B_0}{2}t} \end{pmatrix}$$

(d) $\langle \xi_x \rangle = \langle X(t) | \xi_x | X(t) \rangle$

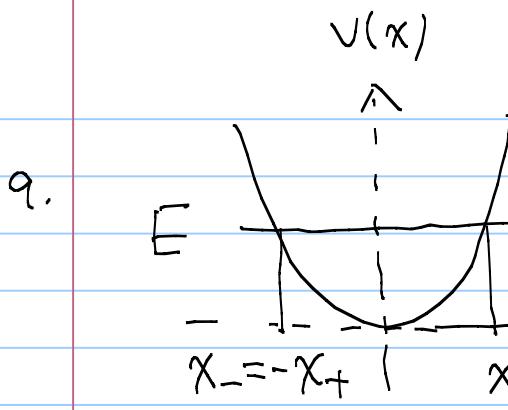
$$= \frac{1}{2} (e^{-i\frac{\alpha B_0}{2}t} e^{i\frac{\alpha B_0}{2}t}) \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} e^{-i\frac{\alpha B_0}{2}t} \\ e^{i\frac{\alpha B_0}{2}t} \end{pmatrix}$$

$$= \frac{\hbar}{4} \left(e^{-\frac{i\alpha B_0 t}{2}} \quad e^{\frac{i\alpha B_0 t}{2}} \right) \left(e^{-\frac{i\alpha B_0 t}{2}} \quad e^{\frac{i\alpha B_0 t}{2}} \right)$$

$$= \frac{\hbar}{4} \left(e^{-i\alpha B_0 t} + e^{i\alpha B_0 t} \right)$$

$$= \underline{\frac{\hbar}{2} \cos(\alpha B_0 t)}$$



$$V(x) = \frac{1}{2} m\omega^2 x^2$$

9.

$$E = \frac{1}{2} m\omega^2 x_+^2 \Rightarrow x_+ = \sqrt{\frac{2E}{m\omega^2}}$$

$$\int_{x_-}^{x_+} k(x) dx = (n - \frac{1}{2})\pi, \quad k(x) = \frac{\sqrt{2m(E - V(x))}}{\hbar}$$

$$\Rightarrow \frac{\sqrt{2mE}}{\hbar} \int_{-x_+}^{x_+} \sqrt{1 - \frac{m\omega^2}{2E} x^2} dx = (n - \frac{1}{2})\pi$$

$$\Rightarrow \sqrt{\frac{m\omega^2}{2E}} x = y \Rightarrow \sqrt{\frac{m\omega^2}{2E}} dx = dy$$

$$\Rightarrow \frac{\sqrt{2mE}}{\hbar} \cdot \sqrt{\frac{2E}{m\omega^2}} \int_{-1}^1 \sqrt{1-y^2} dy = (n - \frac{1}{2})\pi$$

$$\Rightarrow 2 \underbrace{\frac{\sqrt{2mE}}{\hbar} \sqrt{\frac{2E}{m\omega^2}}}_{=} \int_0^1 \sqrt{1-y^2} dy = (n - \frac{1}{2})\pi$$

4. $\frac{E}{\hbar\omega}$ $y = \sin\theta \Rightarrow 1-y^2 = 1-\sin^2\theta = \cos^2\theta$
 $dy = \cos\theta d\theta$

$$\Rightarrow \int_0^{\frac{\pi}{2}} \cos\theta d\theta = \frac{\hbar\omega}{4E} (n - \frac{1}{2})\pi$$

$$\Rightarrow \int_0^{\frac{\pi}{2}} \frac{\cos 2\theta + 1}{2} d\theta = \frac{1}{2} \left[\frac{\sin 2\theta}{2} + \theta \right]_0^{\frac{\pi}{2}}$$

$$\Rightarrow \frac{\pi}{4} = \frac{\hbar\omega}{4E} (n - \frac{1}{2})\pi$$

$$\Rightarrow E = \hbar\omega (n - \frac{1}{2}), \quad n = 1, 2, \dots$$

$$10, \quad V(x) = -\alpha \delta(x)$$

$$E_{gs} \leq \langle \psi | H | \psi \rangle \equiv \langle H \rangle$$

$$H = \frac{p^2}{2m} + V(x) = -\frac{\hbar^2}{2m} \frac{d^2}{dx^2} - \alpha \delta(x)$$

let's first normalize the wave function

$$\psi(x) = A e^{-bx^2}$$

$$\begin{aligned} \langle \psi | \psi \rangle &= A^2 \int_{-\infty}^{\infty} e^{-2bx^2} dx \\ &= A^2 \cdot \sqrt{\frac{\pi}{2b}} \Rightarrow A = \left(\frac{2b}{\pi}\right)^{\frac{1}{4}} \end{aligned}$$

$$\langle H \rangle = \langle T \rangle + \langle V \rangle$$

$$\begin{aligned} \langle T \rangle &= -\frac{\hbar^2}{2m} \int_{-\infty}^{\infty} \psi^* \frac{d^2}{dx^2} \psi dx \\ &= -\frac{\hbar^2}{2m} A^2 \int_{-\infty}^{\infty} e^{-2bx^2} \frac{d^2}{dx^2} e^{-bx^2} dx \\ &= + \frac{\hbar^2}{2m} \cdot \sqrt{\frac{2b}{\pi}} \cdot \sqrt{\frac{\pi b}{2}} \\ &= \frac{\hbar^2}{2m} b \end{aligned}$$

$$\begin{aligned} \langle V \rangle &= -\alpha A^2 \int_{-\infty}^{\infty} e^{-2bx^2} \delta(x) dx \\ &= -\alpha \sqrt{\frac{2b}{\pi}} \cdot e^0 = -\alpha \sqrt{\frac{2b}{\pi}} \end{aligned}$$

$$\therefore \langle H \rangle = \frac{\chi^2}{2m} b - \alpha \sqrt{\frac{2b}{\pi}}$$

$$\Rightarrow \frac{\partial \langle H \rangle}{\partial b} = 0 = \frac{\chi^2}{2m} - \alpha \sqrt{\frac{2}{\pi}} \cdot \frac{1}{2} b^{-\frac{1}{2}}$$

$$= \frac{\chi^2}{2m} - \alpha \sqrt{\frac{1}{2\pi}} b^{-\frac{1}{2}}$$

$$\Rightarrow b^{-\frac{1}{2}} = \alpha \sqrt{\frac{1}{2\pi}} \cdot \frac{2m}{\chi^2} = \alpha \sqrt{\frac{2}{\pi}} \cdot \frac{m}{\chi^2}$$

$$\Rightarrow b = \frac{m^2 \alpha^2}{\chi^4} \frac{2}{\pi}$$

$$\therefore H_{\min} = \frac{\chi^2}{2m} b \left(1 - \alpha \sqrt{\frac{2}{\pi}} \cdot \frac{2m}{\chi^2} \cdot b^{-\frac{1}{2}} \right)$$

$$\alpha \sqrt{\frac{2}{\pi}} \frac{2m}{\chi^2} \cdot b^{-\frac{1}{2}} = \alpha \sqrt{\frac{2}{\pi}} \frac{2m}{\chi^2} \cdot \alpha \sqrt{\frac{2}{\pi}} \cdot \frac{\chi^2}{2m}$$

$$= 2$$

$$\therefore H_{\min} = \frac{\chi^2}{2m} \cdot b (1-2)$$

$$= -\frac{\chi^2}{2m} b = -\frac{\chi^2}{2m} \left(\frac{m^2 \alpha^2}{\chi^4} \frac{2}{\pi} \right)$$

$$= -\frac{m \alpha^2}{\chi^2 \pi}$$

$$11. (a) \psi(x, y) = \frac{2}{a} \sin\left(\frac{n_x \pi}{a} x\right) \sin\left(\frac{n_y \pi}{a} y\right)$$

\Rightarrow 1st excited states are $(n_x, n_y) = (1, 2)$
or $(2, 1)$

$$\text{So } \psi_a \equiv \psi_{1,2} = \frac{2}{a} \sin\left(\frac{\pi}{a} x\right) \sin\left(\frac{2\pi}{a} y\right)$$

$$\psi_b \equiv \psi_{2,1} = \frac{2}{a} \sin\left(\frac{2\pi}{a} x\right) \sin\left(\frac{\pi}{a} y\right)$$

$$\text{with } E = \frac{\hbar^2}{2m} \left(\frac{\pi^2}{a^2} + \frac{4\pi^2}{a^2} \right) \\ = \frac{\hbar^2}{2m} \frac{5\pi^2}{a^2}$$

(b)

$$H_{aa} = \left(\frac{2}{a}\right)^2 \int_0^a \int_0^a \sin^2\left(\frac{\pi}{a} x\right) \sin^2\left(\frac{2\pi}{a} y\right)$$

$$\cdot a^2 V_0 \delta(x - \frac{a}{4}) \delta(y - \frac{a}{2})$$

$$dx dy$$

$$= 4V_0 \sin^2\left(\frac{\pi}{4}\right) \sin^2\left(\frac{\pi}{2}\right)$$

$$= 2V_0$$

$$H_{bb} = 4V_0 \sin^2\left(\frac{\pi}{2}\right) \sin^2\left(\frac{\pi}{4}\right)$$

$$= 2V_0$$

$$H_{ab} = \left(\frac{2}{a}\right)^2 \iint \sin\left(\frac{\pi}{a} x\right) \sin\left(\frac{2\pi}{a} y\right) \\ \sin\left(\frac{2\pi}{a} x\right) \sin\left(\frac{\pi}{a} y\right) \dots dx dy$$

$$= 4V_0 \sin\left(\frac{\pi}{4}\right) \sin\left(\frac{\pi}{2}\right) \\ \sin\left(\frac{\pi}{2}\right) \sin\left(\frac{\pi}{4}\right) \\ = 2V_0$$

$$H'_{ba} = 2V_0$$

$$\therefore H' = 2V_0 \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

Let's solve for the eigenvalues,

$$H' \psi = 2V_0 \cdot \lambda \psi$$

$$\Rightarrow \begin{vmatrix} -\lambda & 1 \\ 1 & -\lambda \end{vmatrix} = 0 \Rightarrow (-\lambda)^2 - 1 = 0$$

$$\Rightarrow (\lambda - 1)(\lambda + 1) = 0$$

$$\therefore \lambda = 2 \text{ or } 0$$

So the 1st order corrections will be

$$4V_0 \text{ and } 0$$

\therefore The new energies are

$$\frac{\hbar^2}{2m} \frac{5\pi^2}{a^2} + 4V_0$$

$$\text{and } \frac{\hbar^2}{2m} \frac{5\pi^2}{a^2}$$

$$12. \quad H'(t) = -g \vec{E} \cdot \vec{r} = e E(t) z$$

Because

$$\begin{aligned} P_{i \rightarrow f}(t) &= |C_f(t)|^2 \\ &= \frac{1}{\hbar^2} \left| \int_0^t H'_{fi} e^{i \frac{E_f - E_i}{\hbar} t} dt \right|^2 \end{aligned}$$

If $H'_{fi}(t)$ is zero, then that transition does not occur, i.e. forbidden.

$$\text{Because } H'_{fz}(t) = e E(t) \langle f | z | i \rangle$$

$$\text{with } |i\rangle = |100\rangle$$

$$|f\rangle = \begin{cases} |200\rangle \\ |21\pm 1\rangle \\ |210\rangle \end{cases}$$

$$\{_0 \langle 200 | z | 100 \rangle$$

$$= \langle R_{20}|r|R_{10} \rangle \langle Y_0^\circ | \cos\theta | Y_0^\circ \rangle$$

$$\langle Y_1^\circ | \cos\theta | Y_0^\circ \rangle = \frac{1}{4\pi} \iint_0^\pi \cos\theta \sin\theta d\phi$$

$$= -\frac{1}{4\pi} \int_{0=0}^{\pi} \cos\theta d\cos\theta \cdot 2\pi$$

$$= \frac{1}{2\pi} \int_{-1}^1 x dx = 0 \Rightarrow \text{forbidden}$$

For $\langle 210 | z | 100 \rangle$

We need to consider $\langle r_1^0 | \cos\theta | r_0^0 \rangle$

$$\propto \iint_{\theta, \phi} \cos^2 \theta \sin \theta d\theta d\phi$$

$$\begin{aligned} & \propto - \int_{\theta=0}^{\pi} \cos^2 \theta d\cos \theta = \int_{x=\cos \theta=-1}^1 x^2 dx \\ & = \frac{2}{3} \neq 0 \rightarrow \text{allowed} \end{aligned}$$

For $\langle 21\pm 1 | z | 100 \rangle$

We need to consider

$\langle r_1^{\pm 1} | \cos\theta | r_0^0 \rangle$

$$\propto \iint \sin \theta e^{\pm i\phi} \cos \theta \sin \theta d\theta d\phi$$

$$= \int_{\theta=0}^{\pi} \sin^2 \theta \cos \theta d\theta \int_0^{2\pi} e^{\pm i\phi} d\phi$$

$$\begin{aligned} & \propto \int_0^{\pi} x^2 dx \cdot \frac{e^{\pm 2\pi i}}{\pm i} \\ & = 0 \Rightarrow \text{forbidden} \end{aligned}$$

\therefore transitions from $|100\rangle$ to $|100\rangle$ and $|21\pm 1\rangle$ are forbidden.