

Linear models for classification Lecture 6

\vec{x} → C_k , $k=1, \dots, K$
input, D dims ↑
discrete classes

Input space divided into decision regions by decision surfaces.

For ex., $\vec{t} = (0, 1, 0, 0, 0)$
target variables $K=5$ classes, target variable indicates class 2

Classification approaches:

① Discriminant function: directly assigns \vec{x} to a class, e.g. for 2 classes $y(\vec{x}) \geq 0 \Leftrightarrow C_1$, $y(\vec{x}) < 0 \Leftrightarrow C_2$.

② Probabilistic approach:

$$\text{use } p(C_k | \vec{x}) = \frac{p(\vec{x} | C_k) p(C_k)}{p(\vec{x})}$$

Bayesian framework

Previously, we focused on $y(\vec{x}) = \vec{w}^T \vec{\phi}(\vec{x}) + w_0$
explicit bias term

Now we will consider $y(\vec{x}) = f(\vec{w}^T \vec{x} + w_0)$
or, more generally, $y(\vec{x}) = f(\vec{w}^T \vec{\phi}(\vec{x}) + w_0)$ non-linear activation f'n

Decision surfaces are given by

$$\vec{w}^T \vec{x} + w_0 = \text{const}, \text{ linear f's of } \vec{x}$$

Discriminant functions

① Two classes

Consider $y(\vec{x}) = \vec{w}^T \vec{x} + w_0$ [linear discriminant]

$$\begin{cases} y(\vec{x}) \geq 0 \Rightarrow C_1 \\ y(\vec{x}) < 0 \Rightarrow C_2 \end{cases}$$

$y(\vec{x}) = 0 \Leftrightarrow$ decision boundary (DB)

Consider $\vec{x}_A, \vec{x}_B \in \text{DB}$

$$y(\vec{x}_A) = y(\vec{x}_B) = 0 \Rightarrow \vec{w}^T (\underbrace{\vec{x}_A - \vec{x}_B}_{\substack{\text{lies on } (D-1) \\ \text{dim'd DB}}}) = 0$$

So, $\vec{w} \perp \text{DB} \Rightarrow \vec{n} = \frac{\vec{w}}{\|\vec{w}\|}$ is a unit vector $\perp \text{DB}$

Similarly, if $\vec{x} \in \text{DB}$,

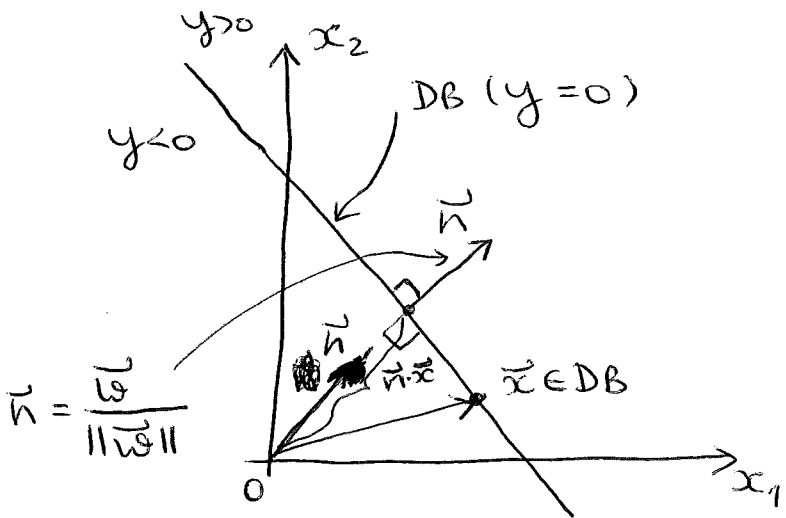
$$y(\vec{x}) = \vec{w}^T \vec{x} + w_0 = 0, \text{ or}$$

$$\underbrace{\frac{\vec{w}^T \vec{x}}{\|\vec{w}\|}} = -\frac{w_0}{\|\vec{w}\|}$$

" $\vec{n} \cdot \vec{x}$ = normal distance from the origin to DB

So, w_0 determines the location of DB

$$D=2$$



Moreover, for any \vec{x}

$$\vec{x} = \underbrace{\vec{x}_{\parallel DB}}_{\perp DB} + r \vec{n}$$

Then

$$\underbrace{\vec{w}^T \vec{x} + w_0}_{y(\vec{x})} = \vec{w}^T \vec{x}_{\parallel DB} + r \frac{\overbrace{\vec{w}^T \cdot \vec{w}}^{\|\vec{w}\|^2}}{\|\vec{w}\|} + w_0, \text{ or}$$

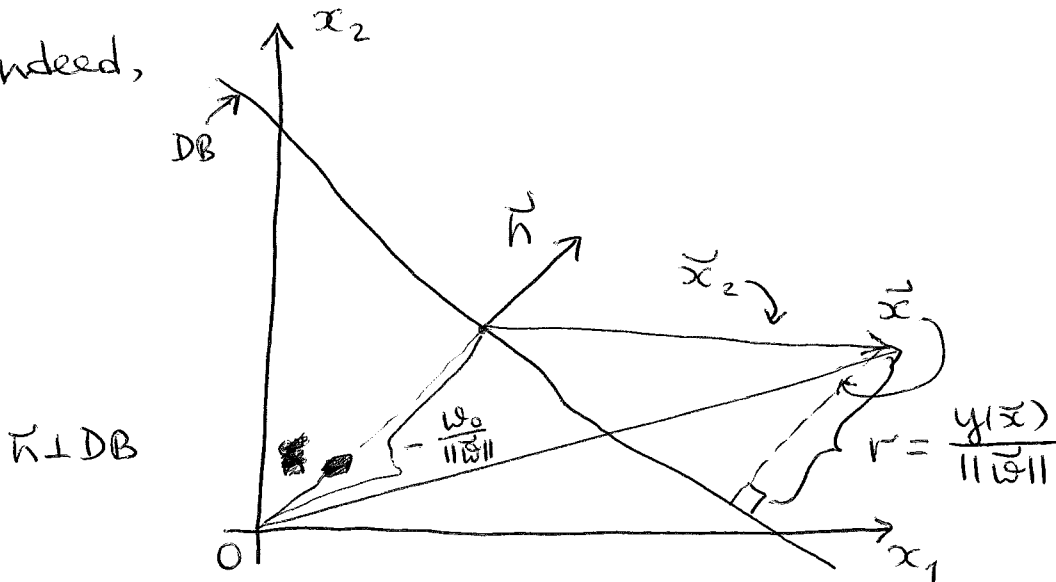
$$y(\vec{x}) = r \|\vec{w}\| \Rightarrow r = \frac{y(\vec{x})}{\|\vec{w}\|}$$

↑
perpendicular distance
from \vec{x} to DB

Here, we used

$$\vec{w}^T \cdot \vec{x}_{\parallel DB} + w_0 = 0$$

Indeed,



Then

$$-\frac{\bar{n}}{\|\bar{w}\|} \bar{w}_0 + \underbrace{\bar{x}_2}_{\substack{= \\ \bar{x}_{2, \parallel DB} + \bar{x}_{2, \perp DB}}} = \bar{x}$$

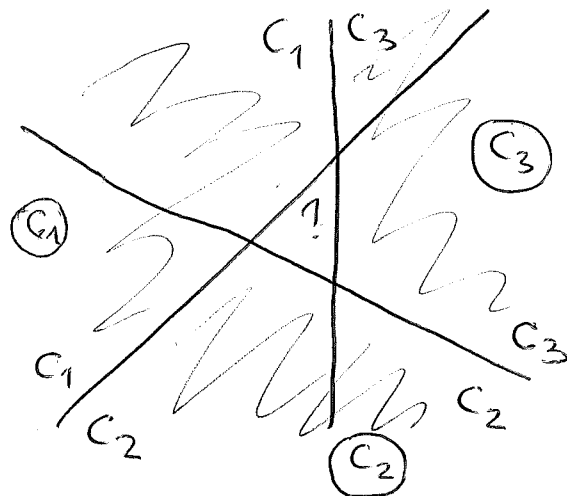
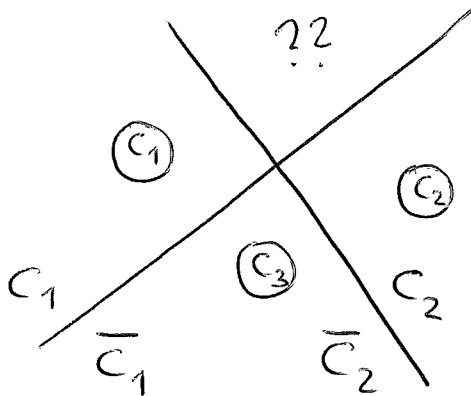
$$\bar{w}^T \cdot \bar{x} = - \underbrace{\frac{\bar{w}^T \cdot \bar{w}}{\|\bar{w}\|^2}}_{=1} \bar{w}_0 + \underbrace{\bar{w}^T \cdot \bar{x}_{2, \parallel DB}}_{=0} + \bar{n} \underbrace{\frac{\bar{w}^T \cdot \bar{w}}{\|\bar{w}\|}}_{\|\bar{w}\|}, \text{ or}$$

$$\underbrace{\bar{w}^T \cdot \bar{x} + \bar{w}_0}_{y(\bar{x})} = \bar{n} \|\bar{w}\|, \text{ as before.}$$

② Multiple classes

Consider $K > 2$ classes.

Difficulties in generalizing from the $K=2$ case:



majority vote among discriminant f 's

Rather, consider a single K -class discriminant:

$$y_k(\bar{x}) = \bar{w}_k^T \cdot \bar{x} + \bar{w}_{k,0}$$

Assign a point to C_k if $y_k(\bar{x}) > y_j(\bar{x}), \forall j \neq k.$

DBs are then given by $y_k(\vec{x}) = y_j(\vec{x})$, s.t.

$$(\vec{w}_k - \vec{w}_j)^T \cdot \vec{x} + (w_{k,0} - w_{j,0}) = 0$$

Now, consider $\vec{x}_A, \vec{x}_B \in C_k$
 line connecting \vec{x}_A & \vec{x}_B

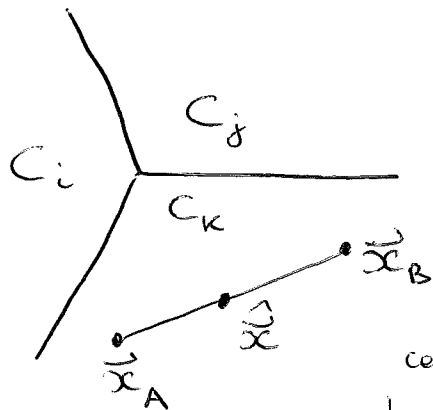
$$\hat{\vec{x}} = \lambda \vec{x}_A + (1-\lambda) \vec{x}_B \quad 0 \leq \lambda \leq 1$$

∥∥ linearity of discriminant f's

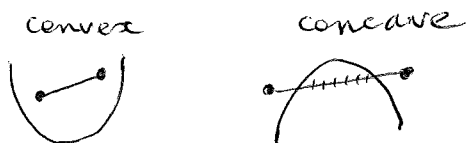
$$y_k(\hat{\vec{x}}) = \lambda \underbrace{y_k(\vec{x}_A)}_{> y_j(\vec{x}_A), \forall j \neq k} + (1-\lambda) \underbrace{y_k(\vec{x}_B)}_{> y_j(\vec{x}_B), \forall j \neq k}$$

$$y_k(\hat{\vec{x}}) > y_j(\hat{\vec{x}}), \forall j \neq k$$

So, $\hat{\vec{x}} \in C_k$ as well.



Since \vec{x}_A, \vec{x}_B are arbitrary, C_k is singly connected & convex, $\forall k$.



Least squares for classification

Consider a problem with K classes, s.t. \vec{t} are K -dim unit vectors.

$$y_k(\vec{x}) = \vec{w}_k^T \vec{x} + w_{k,0} \Rightarrow \tilde{y}(\vec{x}) = \tilde{w}^T \tilde{x}$$

K (classes)

$$\tilde{w} = \left(\begin{array}{c} w_{k,0} \\ w_{k,1} \\ \vdots \\ w_{k,D} \end{array} \right) \left. \vphantom{\begin{array}{c} w_{k,0} \\ w_{k,1} \\ \vdots \\ w_{k,D} \end{array}} \right\} \begin{array}{l} D+1 \text{ (parms)} \\ \text{or} \\ \text{\# entries in } \tilde{x} \end{array}$$

k th column

$$\tilde{x} = (1, \vec{x})^T$$

"x₀"

Training set: $\{\vec{x}_n, \vec{t}_n\} \quad n=1, \dots, N$

Define $T = \left(\begin{array}{cccc} t_{n,0} & t_{n,1} & \dots & t_{n,K+1} \end{array} \right) \left. \vphantom{\begin{array}{cccc} t_{n,0} & t_{n,1} & \dots & t_{n,K+1} \end{array}} \right\} N$

\vec{t}_n is the n th row of T

$$\tilde{X} = \left(\begin{array}{cccc} x_{n,0} & \dots & \dots & x_{n,D} \end{array} \right) \left. \vphantom{\begin{array}{cccc} x_{n,0} & \dots & \dots & x_{n,D} \end{array}} \right\} N$$

$D+1$

\tilde{x}_n is the n th row of \tilde{X}

$\tilde{X} \tilde{w}$ is an $N \times K$ matrix like T

\uparrow \uparrow
 $\#$ rows $\#$ columns

Then $E(\tilde{W}) = \frac{1}{2} \text{Tr} \{ (\tilde{X}\tilde{W} - T)^T (\tilde{X}\tilde{W} - T) \}$.

Indeed,

$$E(\tilde{W}) = \frac{1}{2} \sum_{k=1}^K \sum_{n=1}^N \left(\underbrace{(\tilde{X}\tilde{W})_{nk}}_{\sum_{j=0}^D \tilde{X}_{nj} \tilde{W}_{jk}} - t_{nk} \right)^2 \quad \textcircled{=}$$

$$\sum_{j=0}^D \tilde{X}_{nj} \tilde{W}_{jk} = \sum_{j=0}^D \tilde{x}_{n,j} \omega_{k,j} =$$

$$\textcircled{=} \frac{1}{2} \sum_{k=1}^K \sum_{n=1}^N \left(\sum_{j=0}^D \omega_{k,j} \tilde{x}_{n,j} - t_{nk} \right)^2$$

$$= \omega_{k,0} + \tilde{\omega}_k^T \cdot \tilde{x}$$

Then

$$\frac{\partial E}{\partial \omega_{k,j}} = \frac{1}{2} \sum_n \left[\sum_{j'} \omega_{k,j'} \tilde{x}_{n,j'} - t_{nk} \right] \tilde{x}_{n,j} = 0, \quad \forall k, j$$

$$\underbrace{(\tilde{X}^T \tilde{X})}_{(D+1) \times (D+1)} \underbrace{\tilde{W}}_{(D+1) \times K} = \underbrace{\tilde{X}^T T}_{(D+1) \times K}$$

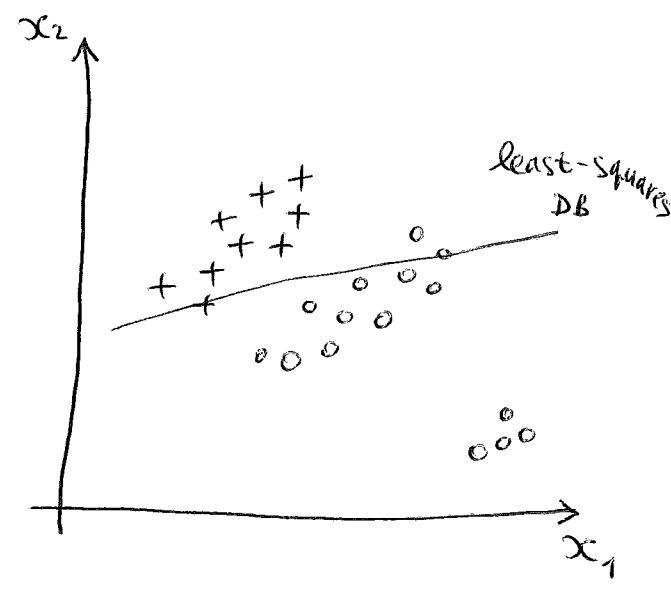
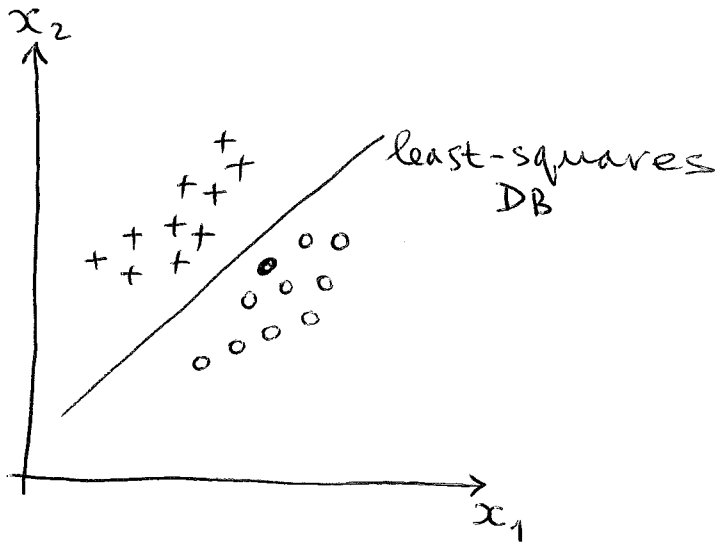
$$(D+1) \times K$$

Finally, $\tilde{W} = \underbrace{(\tilde{X}^T \tilde{X})^{-1}}_{\text{"}\tilde{X}^+ \text{ pseudo-inverse of } X}$ $\tilde{X}^T T$

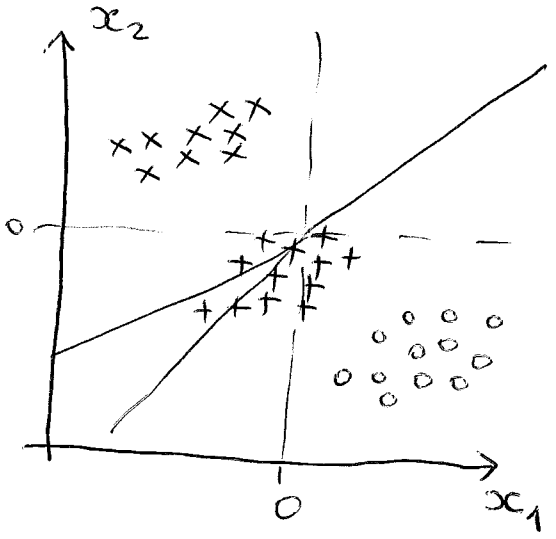
$$\tilde{y}(\tilde{x}) = \tilde{W}^T \tilde{x} = T^T (\tilde{X}^+)^T \tilde{x}$$

This is a closed-form solution which however is sensitive to outliers.

Ex.



And may even fail completely:



poor prediction

Indeed, least-squares assumes gaussian distr'n of $\vec{\epsilon}$'s, and binary target vectors often have non-gaussian distributions.