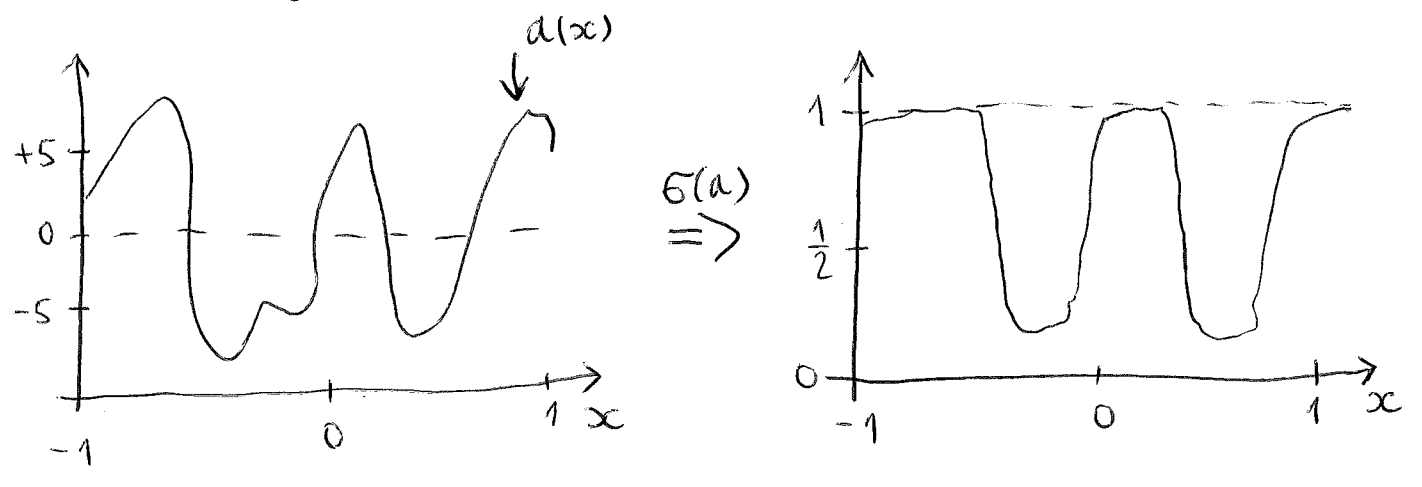


# Gaussian processes for classification

Consider  $K=2$ , s.t.  $t \in \{0, 1\}$ .

Idea: define a gaussian process over  $d(\vec{x})$  & then use  $y = \sigma(a)$  to obtain a non-gaussian stochastic process over functions  $y(\vec{x})$ , s.t.  $y(\vec{x}) \in (0, 1)$ ,  $\forall x$ .

For example, in the 1D case



Recall that  $p(t|a) = \sigma(a)^t (1 - \sigma(a))^{1-t}$ .

Training dataset:  $\vec{x}_1 \dots \vec{x}_N \Rightarrow \vec{t} = t_1 \dots t_N$

also,  $\vec{x}_{N+1} \Rightarrow t_{N+1}$

We need predictive distr'n  $p(t_{N+1} | \vec{t})$

Define  $\vec{a}_{N+1} = \overbrace{a(\vec{x}_1) \dots a(\vec{x}_{N+1})}$ , then

$$p(\vec{a}_{N+1}) \stackrel{\uparrow}{=} \mathcal{N}(\vec{a}_{N+1} | \vec{0}, C_{N+1}), \text{ where}$$

$$C_{N+1, nm} = C_{N+1}(\vec{x}_n, \vec{x}_m) =$$

$$= \underbrace{k(\vec{x}_n, \vec{x}_m)}_{\substack{\text{pos. semidefinite} \\ \text{kernel f'n}}} + \underbrace{\delta_{nm}}_{\substack{\text{small pos. const} \\ -1-}}$$

In general, the kernel f'n  $k(\vec{x}, \vec{x}')$  depends on hyperparameters  $\vec{\theta}$ .

Since  $K=2$ , we <sup>can</sup> focus on  $p(t_{N+1}=1 | \vec{t}_N)$   
 since  $p(t_{N+1}=0 | \vec{t}_N) = 1 - p(t_{N+1}=1 | \vec{t}_N)$ .

Then

$$p(t_{N+1}=1 | \vec{t}_N) = \int da_{N+1} \overbrace{p(t_{N+1}=1 | a_{N+1})}^{\sigma(a_{N+1})} \times \underbrace{p(a_{N+1} | \vec{t}_N)}_{\text{non-gaussian, need an approx'n}}$$

predictive distr'n

Use Jayplace:

$$p(a_{N+1} | \vec{t}_N) = \int d\vec{a}_N p(a_{N+1}, \vec{a}_N | \vec{t}_N) =$$

$$\stackrel{\uparrow}{=} \int d\vec{a}_N \frac{p(\vec{t}_N | a_{N+1}, \vec{a}_N) p(a_{N+1}, \vec{a}_N)}{p(\vec{t}_N)} =$$

Bayes theorem

$$= \frac{1}{p(\vec{t}_N)} \int d\vec{a}_N \underbrace{p(\vec{t}_N | \vec{a}_N)}_{\text{does not depend on } a_{N+1}} p(a_{N+1} | \vec{a}_N) p(\vec{a}_N) \stackrel{\downarrow}{=} \text{Bayes again}$$

$$= \int d\vec{a}_N \underbrace{p(a_{N+1} | \vec{a}_N)}_{\text{gaussian}} \underbrace{p(\vec{a}_N | \vec{t}_N)}_{\text{non-gaussian}}$$

Just as with regression,

$$p(a_{N+1} | \vec{a}_N) = \mathcal{N}(a_{N+1} | \vec{k}^T \mathbf{C}_N^{-1} \vec{a}_N, c - \vec{k}^T \mathbf{C}_N^{-1} \vec{k}).$$

Now, use Laplace on  $p(\vec{a}_N | \vec{t}_N)$ :

go back to  $p(\vec{a}_N | \vec{t}_N) = \frac{p(\vec{t}_N | \vec{a}_N) p(\vec{a}_N)}{p(\vec{t}_N)}$ , where

$p(\vec{a}_N) = \mathcal{N}(\vec{a}_N | \vec{0}, C_N)$  and

$$p(\vec{t}_N | \vec{a}_N) = \prod_{n=1}^N \sigma(a_n)^{t_n} (1 - \sigma(a_n))^{1-t_n} = \prod_{n=1}^N e^{a_n t_n} \sigma(-a_n)$$

$$\frac{\sigma(a)^t (1 - \sigma(a))^{1-t}}{(1 + e^{-a})^t} = \frac{e^{a(t-1)}}{1 + e^{-a}} = \frac{e^{-a}}{1 + e^{-a}} e^{at}$$

$$\left( \frac{e^{-a}}{1 + e^{-a}} \right)^{1-t} = \frac{1}{\sigma(-a)}$$

Then  $\log p(\vec{a}_N | \vec{t}_N) = \log p(\vec{a}_N) + \log p(\vec{t}_N | \vec{a}_N) - \log p(\vec{t}_N)$

$$= -\frac{1}{2} \vec{a}_N^T C_N^{-1} \vec{a}_N - \frac{N}{2} \log(2\pi) - \frac{1}{2} \log |C_N| + \vec{t}_N^T \vec{a}_N - \sum_{n=1}^N \log(1 + e^{a_n}) - \log p(\vec{t}_N)$$

$\Psi(\vec{a}_N)$

$$\nabla_{\vec{a}} \log p(\vec{a}_N | \vec{t}_N) = \nabla_{\vec{a}} \Psi(\vec{a}_N) = \vec{t}_N - C_N^{-1} \vec{a}_N - \vec{\sigma}_N$$

$$\frac{\partial}{\partial a_i} \sum_{n=1}^N \log(1 + e^{a_n}) = \sum_n \frac{1}{1 + e^{a_n}} e^{a_n} \delta_{ni} = \frac{e^{a_i}}{1 + e^{a_i}} = \sigma(a_i)$$

Here,  $\vec{\sigma}_N = \underline{\sigma(a_1) \dots \sigma(a_N)}$

$$\nabla_{\vec{a}} \Psi(\vec{a}_N) = 0 \Rightarrow \underbrace{\vec{\sigma}_N + C_N^{-1} \vec{a}_N}_{\text{nonlinear in } a_i} = \vec{t}_N$$

Need to find the solution by e.g.

Newton-Raphson method:

$$\nabla_{\vec{a}} \nabla_{\vec{a}} \Psi(\vec{a}_N) = -C_N^{-1} - W_N$$

$$\frac{\partial}{\partial a_j} \sigma(a_i) = \sigma(a_i) (1 - \sigma(a_i)) \delta_{ij}$$

$$W_N = \begin{pmatrix} \sigma(a_1)(1-\sigma(a_1)) & & 0 \\ & \ddots & \\ 0 & & \sigma(a_N)(1-\sigma(a_N)) \end{pmatrix}$$

↑  
pos. def.

$C_N$  pos. def.  $\Rightarrow C_N^{-1}$  pos. def., yielding

Hessian  $A = -\nabla_{\vec{a}} \nabla_{\vec{a}} \Psi = W_N + C_N^{-1}$  pos. def.

That means that  $\log p(\vec{a}_N | \vec{t}_N)$  is concave everywhere  $\rightarrow$  there is a single global maximum, so NR should work very well.

Specifically,

$$\vec{a}_N^{\text{new}} = \vec{a}_N^{\text{old}} + A^{-1} \underbrace{\nabla_{\vec{a}} \log p(\vec{a}_N | \vec{t}_N)}_{\nabla_{\vec{a}} \Psi(\vec{a}_N)} =$$

$$= \vec{a}_N^{\text{old}} + \underbrace{(W_N + C_N^{-1})^{-1}}_{C_N(C_N W_N + C_N C_N^{-1})^{-1} = C_N(\mathbb{I} + W_N C_N)^{-1}} [\vec{t}_N - \vec{b}_N - C_N^{-1} \vec{a}_N^{\text{old}}] \ominus$$

$$\ominus C_N(\mathbb{I} + W_N C_N)^{-1} [\vec{t}_N - \vec{b}_N + (\mathbb{I} + W_N C_N) C_N^{-1} \vec{a}_N^{\text{old}} - C_N^{-1} \vec{a}_N^{\text{old}}] \ominus$$

$$\textcircled{E} C_N (\mathbb{I} + W_N C_N)^{-1} [\bar{t}_N - \bar{b}_N + W_N \bar{a}_N^{\text{old}}].$$

Iterate to convergence  $\Rightarrow$  find  $\bar{a}_N^*$  s.t.

$$\nabla_{\bar{a}} \Psi(\bar{a}_N) \Big|_{\bar{a}_N^*} = \vec{0} \Rightarrow \underbrace{\bar{a}_N^* = C_N (\bar{t}_N - \bar{b}_N)}_{\text{non-linear eq'n in } \bar{a}_N^*}$$

$$\text{Now, } H = -\nabla_{\bar{a}} \nabla_{\bar{a}} \Psi(\bar{a}_N) \Big|_{\bar{a}_N^*} = W_N \Big|_{\bar{a}_N^*} + C_N^{-1} \Big|_{\bar{a}_N^*}.$$

Finally, Laplace:

$$p(\bar{a}_N | \bar{t}_N) \Rightarrow q(\bar{a}_N) = \mathcal{N}(\bar{a}_N | \bar{a}_N^*, H^{-1}).$$

$$\text{So, } p(a_{N+1} | \bar{t}_N) = \int d\bar{a}_N \mathcal{N}(a_{N+1} | \bar{k}^T C_N^{-1} \bar{a}_N, c - \bar{k}^T C_N^{-1} \bar{k}) \times \mathcal{N}(\bar{a}_N | \bar{a}_N^*, H^{-1})$$

$$(2.115): p(\bar{y}) = \int d\bar{x} p(\bar{y} | \bar{x}) p(\bar{x}) =$$

$$= \int d\bar{x} \mathcal{N}(\bar{y} | A\bar{x} + \bar{b}, L^{-1}) \mathcal{N}(\bar{x} | \bar{\mu}, \Lambda^{-1}) =$$

$$= \mathcal{N}(\bar{y} | A\bar{\mu} + \bar{b}, L^{-1} + A\Lambda^{-1}A^T)$$

$$\begin{cases} \bar{y} \rightarrow a_{N+1} \\ \bar{x} \rightarrow \bar{a}_N \end{cases} \Rightarrow \begin{cases} A\bar{x} + \bar{b} \rightarrow \bar{k}^T C_N^{-1} \bar{a}_N \left[ \begin{array}{l} A \rightarrow \bar{k}^T C_N^{-1} \\ \bar{b} \rightarrow 0 \end{array} \right], L^{-1} \rightarrow c - \bar{k}^T C_N^{-1} \bar{k} \\ \bar{\mu} = \bar{a}_N^*, \Lambda^{-1} = H^{-1} \end{cases}$$

gives vector of length N

$$p(a_{N+1} | \bar{t}_N) = \mathcal{N}(a_{N+1} | \bar{k}^T C_N^{-1} \bar{a}_N^*, c - \bar{k}^T C_N^{-1} \bar{k} + \bar{k}^T C_N^{-1} H^{-1} C_N^{-1} \bar{k})$$

$$\bar{k}^T C_N^{-1} \bar{a}_N^* = \bar{k}^T (\bar{t}_N - \bar{b}_N),$$

$$C_N (\bar{t}_N - \bar{b}_N)$$

$$C - \bar{k}^T [C_N^{-1} - C_N^{-1} (W_N + C_N^{-1})^{-1} C_N^{-1}] \bar{k} =$$

~~$$C - \bar{k}^T [C_N^{-1} - C_N^{-1} (W_N + C_N^{-1})^{-1} C_N^{-1}] \bar{k} =$$~~

$$= C - \bar{k}^T [C_N^{-1} - C_N^{-1} (W_N C_N + \mathbb{I})^{-1}] \bar{k} =$$

$$= C - \bar{k}^T [(C_N^{-1} \otimes (W_N C_N + \mathbb{I}) - C_N^{-1}) (W_N C_N + \mathbb{I})^{-1}] \bar{k} =$$

$$= C - \bar{k}^T [W_N (W_N C_N + \mathbb{I})^{-1}] \bar{k} = C - \bar{k}^T (C_N + W_N^{-1})^{-1} \bar{k}.$$

$$\exists \mathcal{N}(a_{N+1} | \underbrace{\bar{k}^T (\bar{t}_N - \bar{b}_N)}_{\mu}, \underbrace{C - \bar{k}^T (C_N + W_N^{-1})^{-1} \bar{k}}_{\sigma^2}).$$

Finally,

$$p(t_{N+1} = 1 | \bar{t}_N) = \int da_{N+1} \mathcal{B}(a_{N+1}) \mathcal{N}(a_{N+1} | \mu, \sigma^2) \approx$$

$$\approx \mathcal{B}(\kappa(\sigma^2) \mu), \text{ where}$$

$$\kappa(\sigma^2) = \frac{1}{\sqrt{1 + \frac{\kappa \sigma^2}{8}}}.$$

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What about hyperprms  $\vec{\theta}$ ?

Maximize  $p(\vec{t}_N | \vec{\theta}) \Rightarrow \vec{\theta}_{ML}$

Use  $p(\vec{t}_N | \vec{\theta}) = \int d\vec{a}_N p(\vec{t}_N | \vec{a}_N) p(\vec{a}_N | \vec{\theta})$ ,

apply Laplace:  $\int d\vec{z} f(\vec{z}) \approx f(\vec{z}_0) \frac{(2\pi)^{M/2}}{|A|^{1/2}}$

$\llcorner$   $M$  dim

depends on  $\vec{\theta}$

$$\log p(\vec{t}_N | \vec{\theta}) \approx \underbrace{\log p(\vec{t}_N | \vec{a}_N^*)}_{\Psi(\vec{a}_N^*)} + \underbrace{\log p(\vec{a}_N^* | \vec{\theta})}_{\text{depends on } \vec{\theta}} +$$

$$+ \frac{N}{2} \log(2\pi) - \frac{1}{2} \log |W_N + C_N^{-1}|$$

$\underbrace{\hspace{10em}}_{\text{depends on } \vec{\theta}}$

To maximize this, we need to find

$$\frac{\partial \log p(\vec{t}_N | \vec{\theta})}{\partial \theta_j} \quad \bullet \quad \text{in terms of } \frac{\partial C_N}{\partial \theta_j} \quad \& \quad \frac{\partial \vec{a}_N^*}{\partial \theta_j}$$

Note that  $\begin{cases} C_N = C_N(\vec{\theta}), \\ \vec{a}_N^* = \vec{a}_N(\vec{\theta}). \end{cases}$

$$\text{Recall that } \begin{cases} p(\vec{t}_N | \vec{a}_N^*) = \prod_{n=1}^N e^{a_n^* t_n} \sigma(-a_n^*), \\ p(\vec{a}_N^* | \vec{\theta}) = \mathcal{N}(\vec{a}_N^* | \vec{0}, C_N) \end{cases}$$

Finally, note that

$$\frac{\partial \vec{a}_N^*}{\partial \theta_j} = \frac{\partial C_N}{\partial \theta_j} (\vec{t}_N - \vec{b}_N) - C_N \underbrace{\frac{\partial \vec{b}_N}{\partial \theta_j}}_{\text{vector with elements}}$$
, or

$$\frac{\partial \sigma(a_n^*)}{\partial \theta_j} = \underbrace{\sigma(a_n^*) (1 - \sigma(a_n^*))}_{W_N, nn} \frac{\partial a_n^*}{\partial \theta_j}$$

$$\frac{\partial \vec{b}_N}{\partial \theta_j} = W_N \frac{\partial \vec{a}_N^*}{\partial \theta_j}$$

$$\frac{\partial \vec{a}_N^*}{\partial \theta_j} = \frac{\partial C_N}{\partial \theta_j} (\vec{t}_N - \vec{b}_N)$$
, or

$$(\mathbb{I} + C_N W_N)$$

$$\frac{\partial \vec{a}_N^*}{\partial \theta_j} = (\mathbb{I} + \underbrace{W_N C_N}_{C_N W_N})^{-1} \frac{\partial C_N}{\partial \theta_j} (\vec{t}_N - \vec{b}_N)$$

so  $\frac{\partial \vec{a}_N^*}{\partial \theta_j}$  can be expressed through  $\frac{\partial C_N}{\partial \theta_j}$

with  $\frac{\partial \log p(\vec{t}_N | \vec{\theta})}{\partial \theta_j}$  available, can use e.g. conjugate gradient to maximize  $\log p(\vec{t}_N | \vec{\theta})$  & find  $\vec{\theta}_{ML}$ .