

Lecture 6

Regularization

MLE can overfit the training data.

Ex. $\vec{\theta} = (\theta_h, 1 - \theta_h)$
 $\uparrow$ heads in coin tosses

$$\mathcal{D} = \underbrace{\{h, h, h\}}_{N=3} \Rightarrow \theta_h^* = \frac{3}{3} = 1$$

Now, $\text{Ber}(y|\vec{\theta}^*)$ will predict no tails $\Rightarrow$ the model does not generalize

To prevent overfitting, one uses regularization:

$$\mathcal{J}(\vec{\theta}; \lambda) = + \sum_{n=1}^N \log p(\tilde{y}_n | \tilde{x}_n, \vec{\theta}) + \underbrace{\lambda C(\vec{\theta})}_{\text{complexity penalty}}$$

If $\lambda=1$ and $C(\vec{\theta}) = \underbrace{\log p(\vec{\theta})}_{\text{prior}}$, we have

$$\mathcal{J}(\vec{\theta}; \lambda) = \sum_{n=1}^N \log p(\tilde{y}_n | \tilde{x}_n, \vec{\theta}) + \log p(\vec{\theta}) =$$

$$= \log p(\mathcal{D} | \vec{\theta}) + \log p(\vec{\theta}) = \log p(\vec{\theta} | \mathcal{D}) + \text{const}$$

MAP estimate: $\vec{\theta}_{\text{MAP}} = \underset{\vec{\theta}}{\text{argmax}} \log p(\vec{\theta} | \mathcal{D})$

Ex. Coin tossing:

use $p(\theta) = \text{Beta}(\theta | a, b)$, where

$$\text{Beta}(\theta | a, b) = \frac{1}{B(a, b)} \theta^{a-1} (1-\theta)^{b-1} \text{ is}$$

the beta distribution.

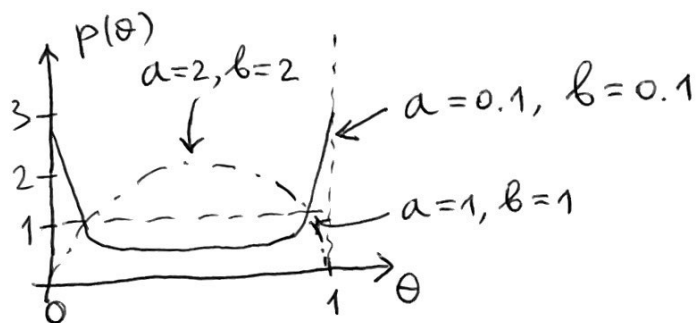
Here, $B(a, b) = \frac{\Gamma(a) \Gamma(b)}{\Gamma(a+b)}$ is the

beta function, and

$$\Gamma(a) = \int_0^\infty dx x^{a-1} e^{-x}.$$

↑
gamma function

Note that $a, b > 0$; if $a=b=1$, the beta distribution is uniform.



$$\underbrace{E[\theta]}_{\text{mean}} = \frac{a}{a+b}$$

—○—
We need to maximize

$$\log p(D | \theta) + \log p(\theta) \Rightarrow \text{maximize}$$

$$\Rightarrow \underbrace{N_1}_{\# \text{ heads}} \log \theta + \underbrace{N_0}_{\# \text{ tails}} \log(1-\theta) + (a-1) \log \theta + (b-1) \log(1-\theta).$$

$$N = N_0 + N_1$$

$$\frac{\partial}{\partial \theta} \log p(\theta | \mathcal{D}) \Big|_{\theta_{\text{MAP}}} = \frac{N_1 + (a-1)}{\theta_{\text{MAP}}} - \frac{N_0 + (b-1)}{1 - \theta_{\text{MAP}}} = 0, \quad \text{or}$$

$$[N_1 + (a-1)](1 - \theta_{\text{MAP}}) = [N_0 + (b-1)]\theta_{\text{MAP}},$$

$$\theta_{\text{MAP}} = \frac{N_1 + (a-1)}{N + a + b - 2}.$$

we might set $a = b = 2 \Rightarrow \theta_{\text{MAP}} = \frac{N_1 + 1}{N + 2}$
"add one smoothing"

Exc. Regression:

use zero-mean gaussian for $p(\vec{w})$:

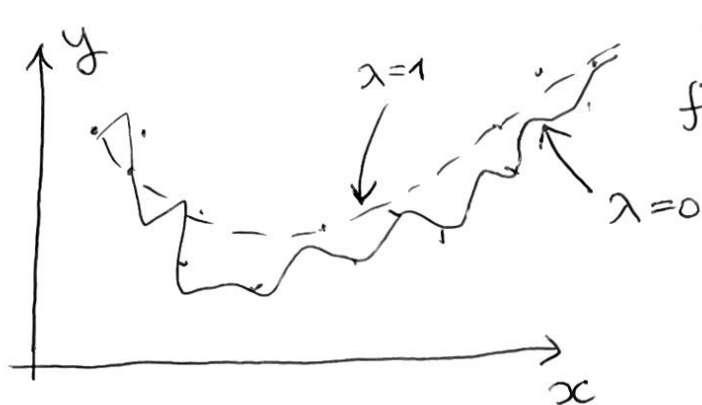
$$\begin{aligned} \text{maximize} \quad & \underbrace{\log p(\mathcal{D} | \vec{w})}_{\substack{\uparrow \\ \frac{1}{2} \times \text{precision prm;} \\ \log p(\vec{w}) = \\ = -\lambda |\vec{w}|^2 + \\ + \text{const}(\vec{w})}} - \lambda |\vec{w}|^2 \quad \text{wrt } \vec{w} \\ & - \frac{1}{2\sigma^2} \sum_{i=1}^N (y_i - f(\vec{x}_i; \vec{w}, b))^2 + \end{aligned}$$

$$|\vec{w}|^2 = \sum_{d=1}^D w_d^2 \quad \vec{x} \in \mathbb{R}^D$$

Linear regression:

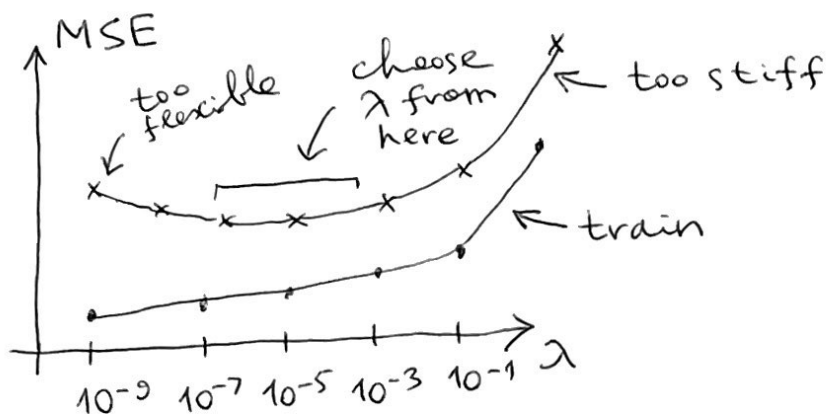
$$f(\vec{x}; \vec{w}, b) = \sum_{d=1}^D w_d x_d + b.$$

Choice of λ :



Here,

$$f(x; \vec{w}, b) = \sum_{d=1}^{14} w_d x^d + b$$



Bayesian statistics

$$p(\vec{\theta} | \mathcal{D}) = \frac{p(\mathcal{D} | \vec{\theta}) p(\vec{\theta})}{\int d\vec{\theta}' p(\mathcal{D} | \vec{\theta}') p(\vec{\theta}')} p(\mathcal{D}), \text{ marginal likelihood}$$

$\uparrow$ posterior $\downarrow$ likelihood $\leftarrow$ prior

Supervised: $\mathcal{D} = \{(\vec{x}_n, \vec{y}_n)\}_{n=1}^N$

Unsupervised: $\mathcal{D} = \{\vec{y}_n\}_{n=1}^N$

Once we have $p(\vec{\theta} | \mathcal{D})$, we can compute the predictive distribution

$$p(\vec{y}|\vec{x}, \mathcal{D}) = \int d\vec{\theta} p(\vec{y}|\vec{x}, \vec{\theta}) p(\vec{\theta}|\mathcal{D}).$$

↑
supervised case

For example, if $p(\vec{\theta}|\mathcal{D}) = \delta(\vec{\theta} - \vec{\theta}_{\text{MAP}})$,

$$p(\vec{y}|\vec{x}, \mathcal{D}) = \underbrace{p(\vec{y}|\vec{x}, \vec{\theta}_{\text{MAP}})}_{\text{a single model predominates}}$$

Conjugate priors: priors that are parameterized similarly to the likelihood.

Exc. $\begin{cases} p(\mathcal{D}|\theta) = \theta^{N_1}(1-\theta)^{N_0} & \text{likelihood} \\ p(\theta) = \text{Beta}(\theta|a,b) = \frac{1}{B(a,b)} \theta^{a-1}(1-\theta)^{b-1} & \text{prior} \end{cases}$

Then $p(\theta|\mathcal{D}) = \text{Beta}(\theta|a+N_1, b+N_0)$.

In particular, $E[\theta] = \frac{a+N_1}{\underbrace{a+b}_{\tilde{N} = \text{equiv. sample size}} + \underbrace{N_1+N_0}_{N = \text{sample size}}}$

One can write $m = \frac{a}{\tilde{N}}$ θ^*, MLE

$$E[\theta] = \frac{\tilde{N} \frac{a}{\tilde{N}} + N \frac{N_1}{N}}{N + \tilde{N}} = \underbrace{\frac{\tilde{N}}{N + \tilde{N}}}_{\lambda} m + \frac{N}{N + \tilde{N}} \frac{N_1}{N} = \lambda m + (1-\lambda) \theta^*$$

as $N \uparrow$, $\lambda \downarrow$ and $\underbrace{E[\theta]}_{\text{posterior mean}} \rightarrow \theta^*$.

Predictive distribution:

$$p(y=1|\mathcal{D}) = \int_0^1 d\theta \underbrace{p(y=1|\theta)}_{\theta} p(\theta|\mathcal{D}) = E[\theta|\mathcal{D}] = \\ = \frac{N_1 + a}{N + a + b}.$$

If $a=b=1$ (uniform prior), we have:

$$p(y=1|\mathcal{D}) = \frac{N_1 + 1}{N + 2} \quad \nwarrow \text{pseudocounts}$$