

Strong Lens Modeling (III): Advanced Techniques

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Data
Model
Basic results
Priors: SPS
Priors: H_0

HE0435

Statistics
Smooth models
Few-clump models
Pop'n models

Extended Sources

Linear mapping
Lensing operator
Regularization
Reconstruction
Examples

Free-form Models

Multipole
Multipole/Taylor
Mass pixels

Other

Goals

point sources + parametric lens models

- ▶ composite models
- ▶ astrophysical priors
- ▶ substructure
- ▶ statistical techniques

extended sources

free-form lens models

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Case studies

What can you do with advanced analyses of point sources and parametric lens models?

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- ▶ sophisticated composite models
- ▶ use of astrophysical priors
- ▶ MCMC

HE 0435–1223

- ▶ substructure
- ▶ statistical methods
- ▶ nested sampling

(work led by Ross Fadely)

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Fadely et al. 2010ApJ...711..246F

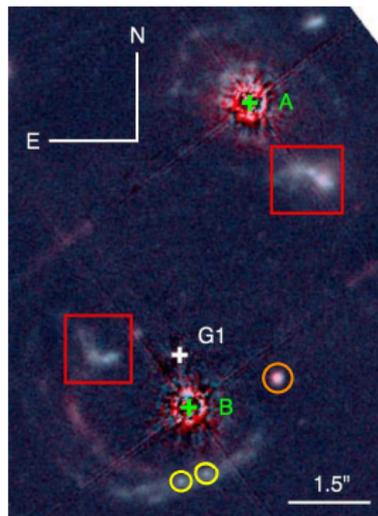
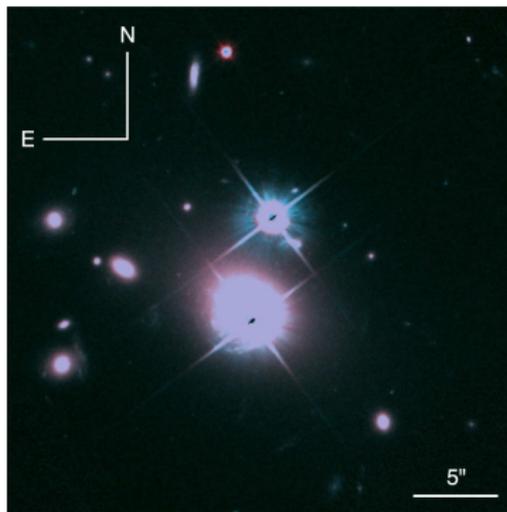


Figure: (Left) Central 30'' of combined HST F606W and F814W images. (Right) Close-up of the strong lensing region, after the main lensing galaxy and quasar images have been subtracted.

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Lensed features

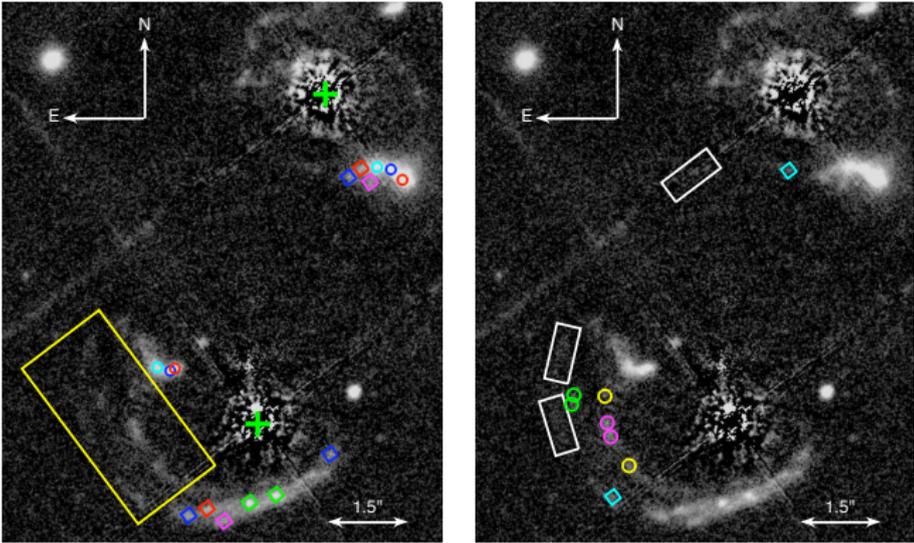


Figure: Sets of multiple images — all told, 30 images of 14 sources.

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Properties of main lens galaxy

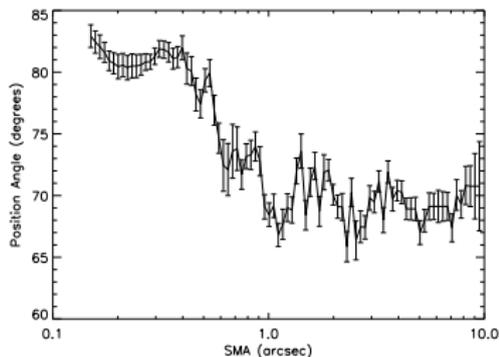
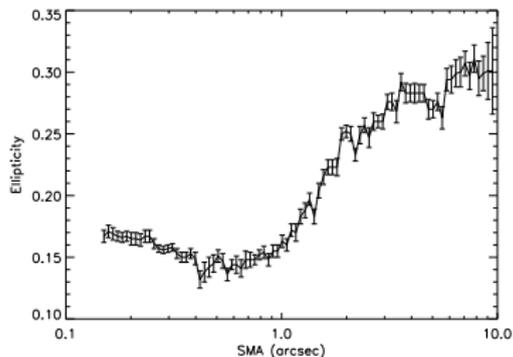


Figure: Ellipticity and position angle of galaxy isophotes.

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Components of mass model

Stellar component: observed light distribution

- ▶ stellar mass-to-light ratio Υ

Dark matter halo: NFW or softened power law

- ▶ normalization
- ▶ scale radius
- ▶ ellipticity and position angle

Environment: cluster surrounding main lens galaxy

$$\begin{aligned}\phi_{\text{env}}(r, \theta) = & \frac{\kappa_c}{2} r^2 + \frac{\gamma}{2} r^2 \cos 2(\theta - \theta_\gamma) \\ & + \frac{\sigma}{4} r^3 \cos(\theta - \theta_\sigma) + \frac{\delta}{6} r^3 \cos 3(\theta - \theta_\delta) + \dots\end{aligned}$$

- ▶ shear (γ, θ_γ) , higher-order terms $(\sigma, \theta_\sigma, \delta, \theta_\delta)$
- ▶ mass sheet κ_c constrained with separate weak lensing analysis

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Searching parameter space

Full set of parameters:

- ▶ 11 mass model parameters — searched explicitly (MCMC)
- ▶ 28 source position parameters — optimized analytically
- ▶ H_0 from time delay

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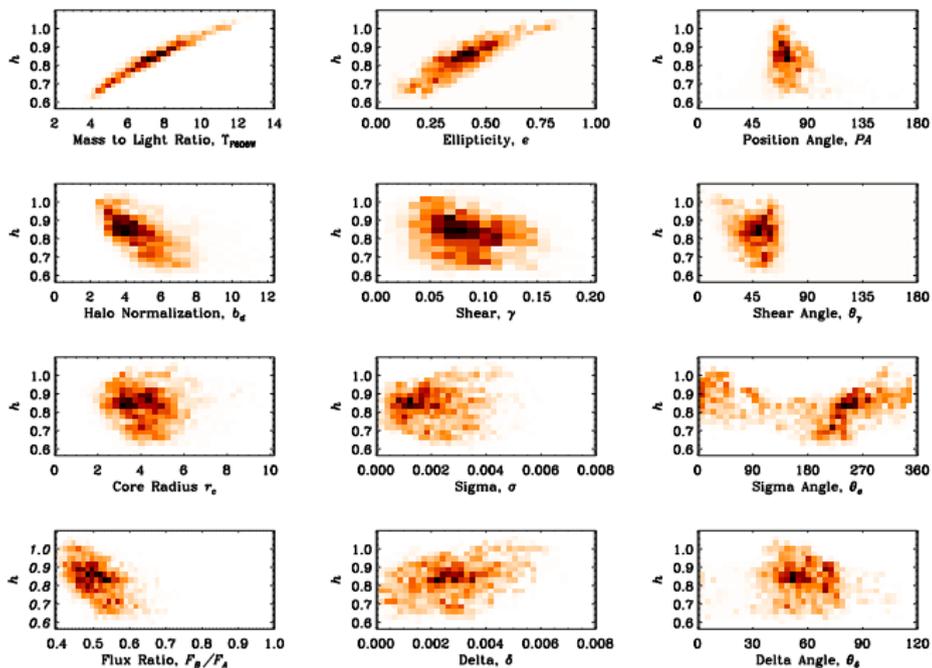
Multipole/Taylor

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Basic results

Softened power law halo with isothermal profile ($\alpha = 1$)



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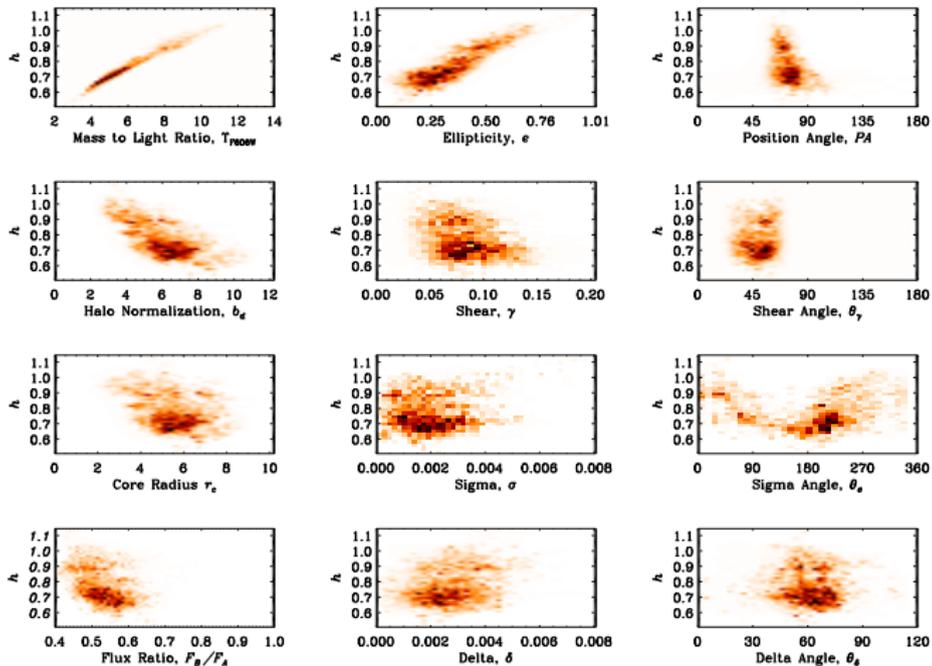
Multipole/Taylor

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Basic results

Softened power law halo with steeper profile ($\alpha = 0.5$)



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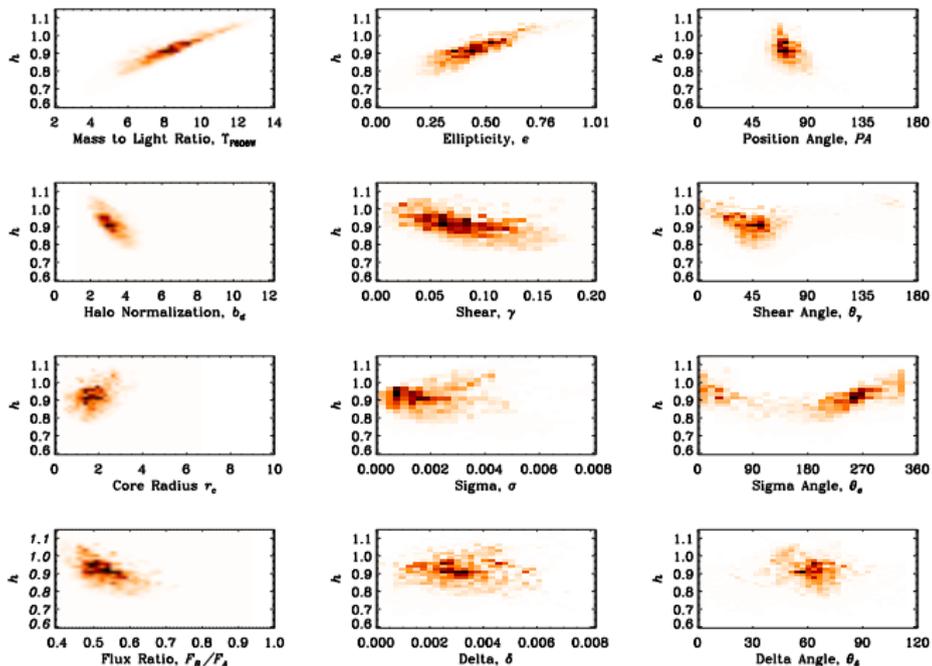
Multipole/Taylor

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Basic results

Softened power law halo with shallower profile ($\alpha = 1.5$)



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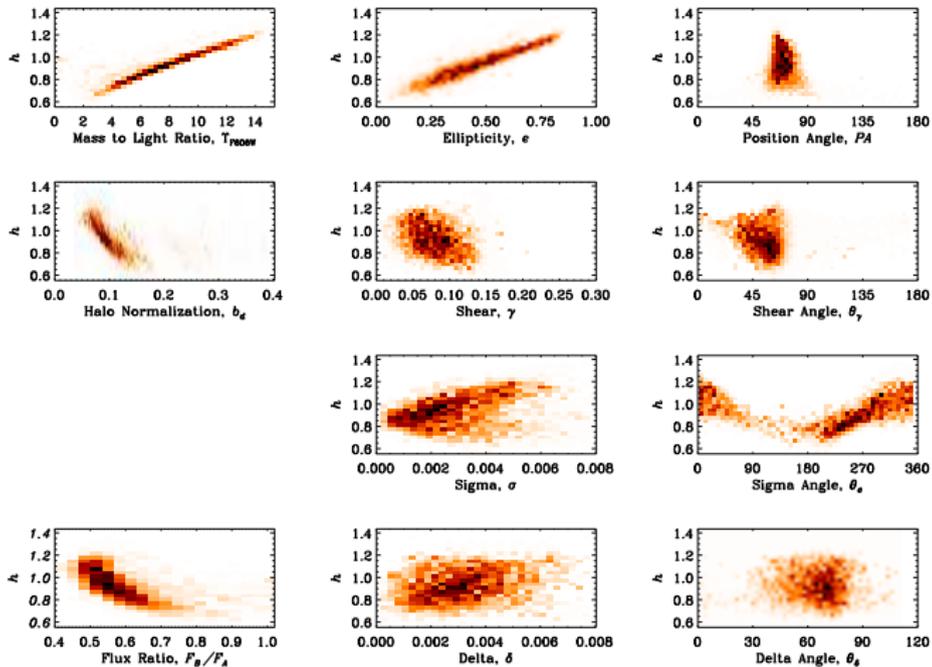
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Basic results

NFW halo



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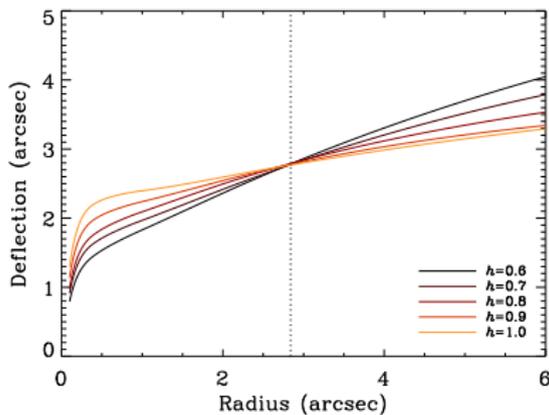
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Density profile

Deflection curve, $\alpha(r) \propto M(r)/r$ — 2-d analog of rotation curve

Trade-off between stars and dark matter changes density profile



Rising deflection curve \Rightarrow density profile shallower than isothermal.
Due to massive cluster around lens?

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Additional information – priors

Stellar mass-to-light ratio is not totally unknown.

Can predict it using [Stellar Population Synthesis \(SPS\)](#) models.

- ▶ generate a population of stars at some time
- ▶ stellar evolution models → predict how pop'n evolves
- ▶ stellar atmospheres → predict spectrum as a function of time
- ▶ include star formation history → predict galaxy spectrum

e.g., Bruzual & Charlot 2003MNRAS.344.1000B; Maraston et al. 2009MNRAS.394L.107M; Conroy et al. 2009ApJ...699..486C

Fit SPS models to observed galaxy **colors**, constrain Υ .

Note: analysis depends on H_0 through time vs. redshift.

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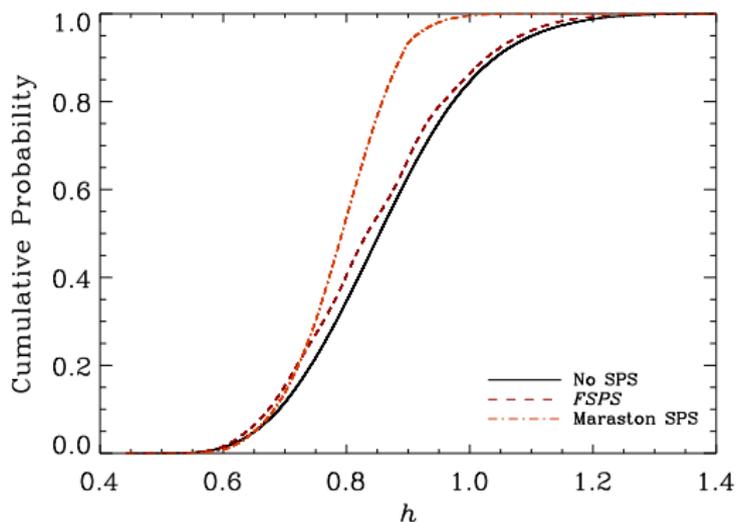
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Combined constraints on H_0



SPS constraints $\rightarrow H_0 = 79.3^{+6.7}_{-8.5} \text{ km s}^{-1} \text{ Mpc}^{-1}$ (68% CL)

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Priors on H_0

Instead of trying to recover H_0 , we could place priors from independent measurements.

Distance ladder (Riess et al. 2009ApJ...699..539R):

$$H_0 = 74.2 \pm 3.6 \text{ km s}^{-1} \text{ Mpc}^{-1}$$

WMAP5+SNe+BAO (Komatsu et al. 2009ApJS..180..330K):

$$H_0 = 70.5 \pm 1.3 \text{ km s}^{-1} \text{ Mpc}^{-1}$$

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Stellar mass-to-light ratio

From lensing, using priors on H_0 :

$$\Upsilon = 5.5_{-0.5}^{+0.9} \quad (\text{distance ladder priors})$$

$$\Upsilon = 5.5_{-0.3}^{+0.2} \quad (\text{WMAP5+SNe+BAO priors})$$

SPS models:

$$\Upsilon = 5.9 \pm 1.9$$

Use lensing to constrain stellar populations?!

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Statistics: Comparing models

Bayesian evidence allows objective model comparison, even with different numbers of parameters.

$$Z(M) = \int \mathcal{L}(d|\mathbf{q}, M) P(\mathbf{q}, M) d\mathbf{q}$$

Compare two models via Z_2/Z_1 or $\log_{10}(Z_2/Z_1) = \Delta \log_{10}(Z)$.

Jeffreys (1961) scale:

$\Delta \log_{10}(Z)$	Significance
0–0.5	Barely worth mentioning
0.5–1.0	Substantial
1.0–1.5	Strong
1.5–2.0	Very strong
> 2.0	Decisive

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HE0435: Smooth mass models

parameters

- ▶ main galaxy: mass, position, e/PA , core radius, profile (7)
- ▶ neighbor galaxy: mass, position, e/PA (5)
- ▶ rest of environment: shear/ PA (2)
- ▶ source: position, flux (3)

data

- ▶ images: positions, fluxes (12)
- ▶ main galaxy: position (2)
- ▶ neighbor galaxy: position (2)

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HE0435: Smooth mass models

16 constraints, 17 parameters — but best $\chi^2 = 24.6$ (!)

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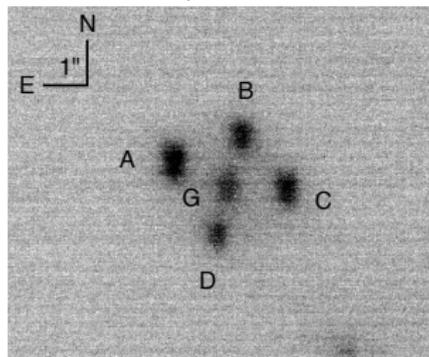
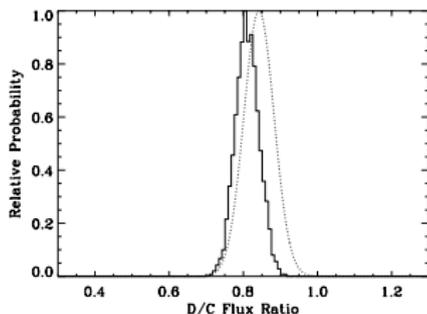
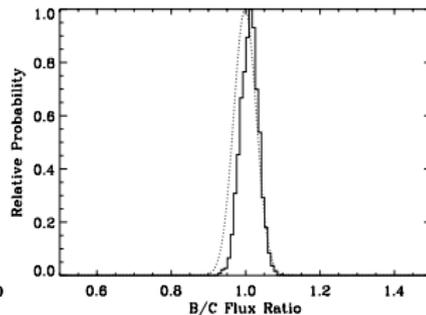
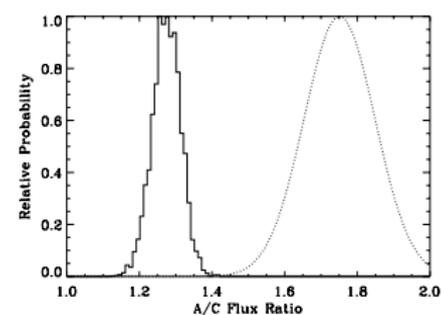
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16 constraints, 17 parameters — but best $\chi^2 = 24.6$ (!)



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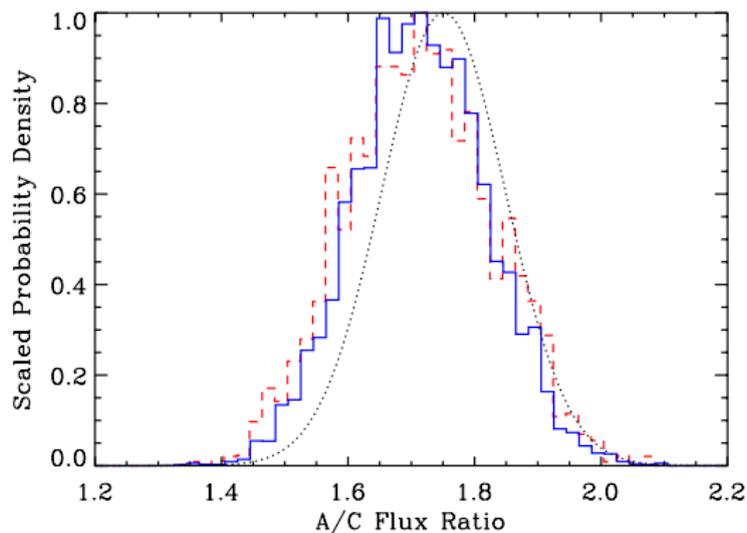
Other

With mass clump(s)

Add one clump near image A.

Add three clumps near images A, B, D.

Clumps are truncated isothermal spheres.



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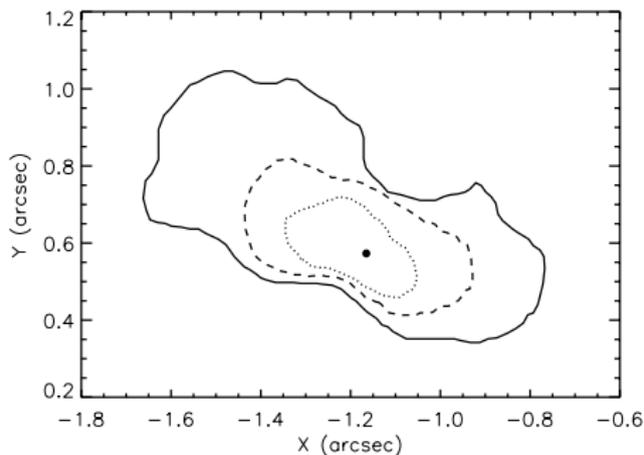
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Other

Position of clump A

95% confidence limits

- ▶ dotted: $M < 10^6 M_{\odot}$
- ▶ dashed: $M < 10^7 M_{\odot}$
- ▶ solid: $M < 10^8 M_{\odot}$



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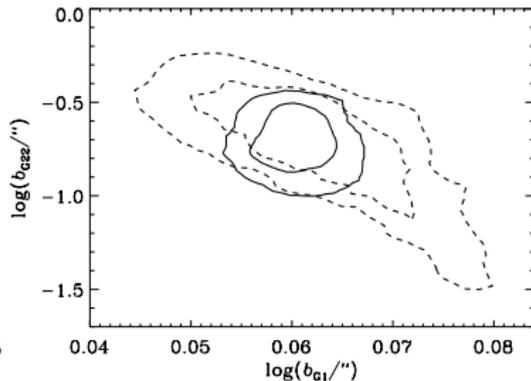
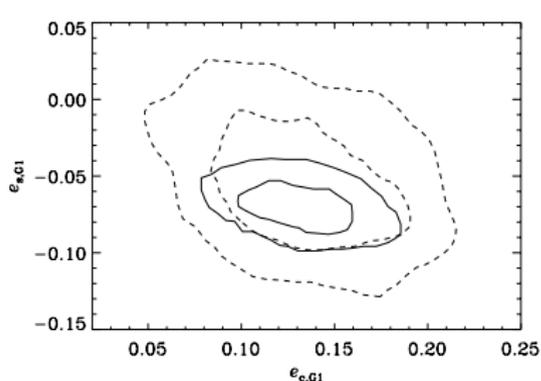
Mass pixels

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Posterior parameter constraints

68% and 95% confidence intervals

- ▶ solid: smooth model
- ▶ dashed: + clump A



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Statistical significance of clump(s)

Use nested sampling to compute Bayesian evidence and compare different models.

model	$\Delta \log_{10}(Z)$
smooth	$\equiv 0$
clump A	3.83 ± 0.12
clumps AD	3.90 ± 0.13
clumps AB	4.46 ± 0.12
clumps ABD	4.35 ± 0.13

Decisive evidence for a clump near image A.

$$\log_{10}(M_{\text{ein}}^A) = 7.65_{-0.84}^{+0.87} \quad \log_{10}(M_{\text{tot}}^A) = 9.31_{-0.42}^{+0.44}$$

Intriguing evidence for a second clump near image B.

$$\log_{10}(M_{\text{ein}}^B) = 6.55_{-1.51}^{+1.01} \quad \log_{10}(M_{\text{tot}}^B) = 8.76_{-0.77}^{+0.50}$$

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Full population of clumps

It seems unlikely that the lens galaxy contains one or two clumps that are (almost) perfectly aligned with the quasar images.

More likely: they are “special” representatives of a larger pop'n.

Try to constrain the population directly

- ▶ assume truncated isothermal spheres with mass function

$$\frac{dN}{dm} \propto m^{-1.9}, \quad m \in 10^7 - 10^{10} M_{\odot}$$

- ▶ see whether models make sense, constrain $\kappa_s = \Sigma_s / \Sigma_{\text{crit}}$

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Statistical inference

Parameters

- ▶ q = smooth model
- ▶ s = substructure *population* (abundance, mass function, etc.)
- ▶ c = individual clumps (position, mass, etc.)

Most interested in marginalized posterior for **substructure population parameters**:

$$P(s) \propto \int \mathcal{L}(c, q) P(c|s) P(s, q) dc dq$$

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Monte Carlo techniques

Need to evaluate

$$P(s) \propto \int \mathcal{L}(c, q) P(c|s) P(s, q) dc dq$$

We can't do the c integral explicitly!

Use Monte Carlo integration: let c_j be a realization of the clump population, drawn from $P(c|s)$. Then

$$P(s) \propto \sum_j \int \mathcal{L}(c_j, q) P(s, q) dq$$

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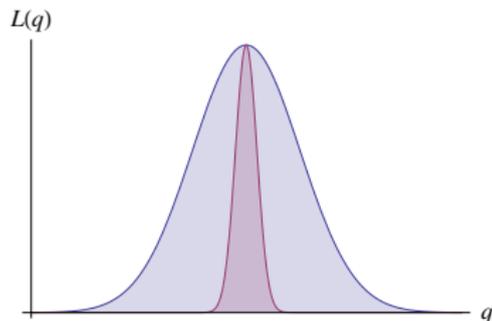
Marginalizing vs. optimizing

$$P(s) \propto \sum_j \int \mathcal{L}(c_j, q) P(s, q) dq$$

For each c_j , what do we do with q ?

- ▶ Marginalize = do the integral, find the **area**
- ▶ Optimize = just find the **peak**

They are not necessarily equivalent!



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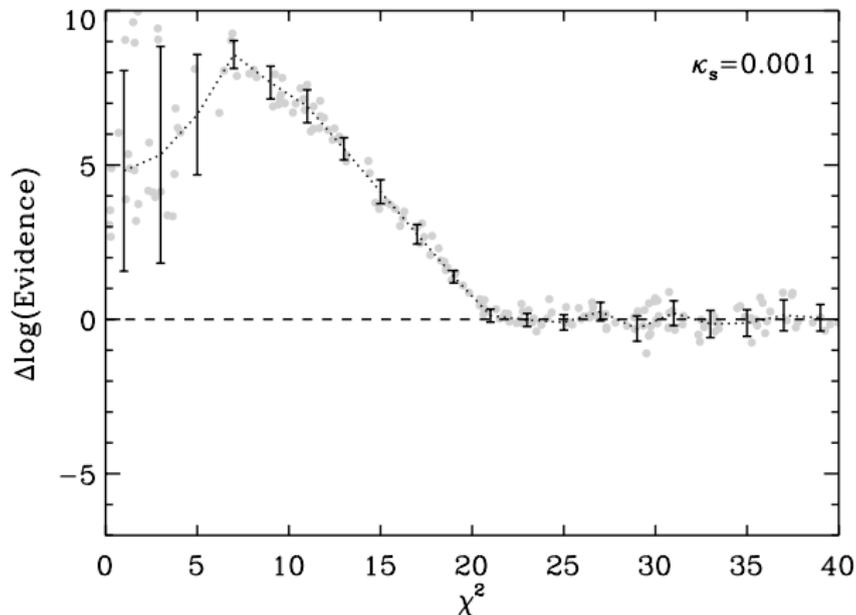
Multipole/Taylor

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Marginalizing vs. optimizing

Each point is one realization of clump pop'n; $\mathcal{L}_{\text{peak}} = e^{-\chi^2/2}$



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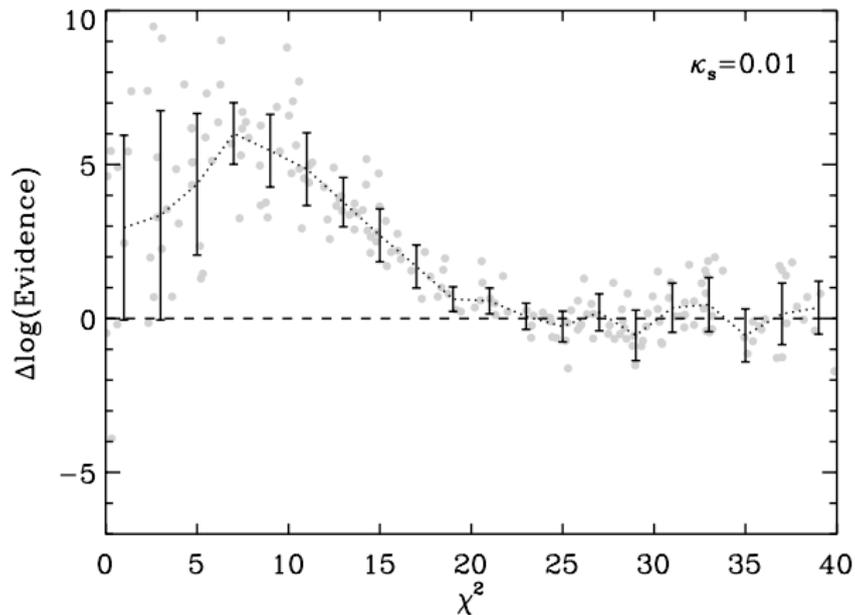
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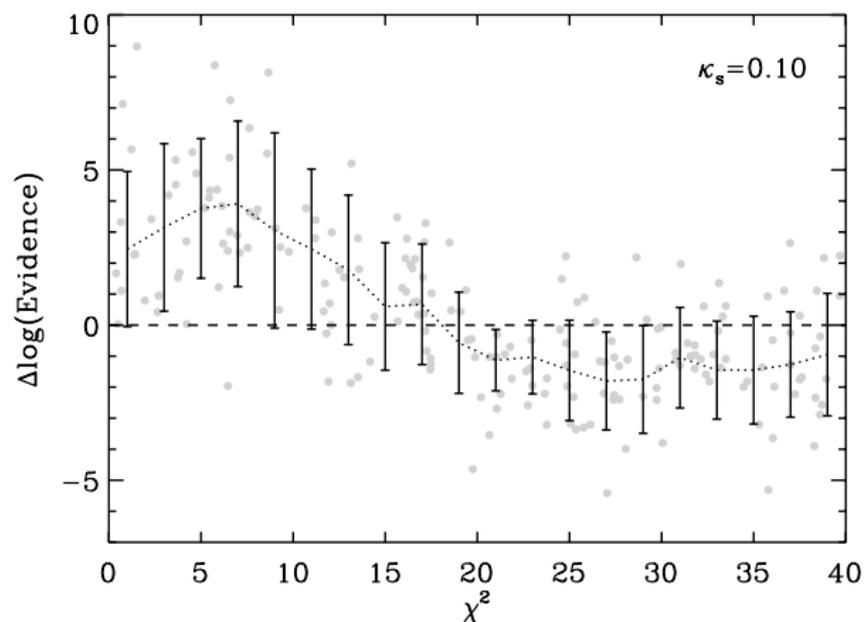
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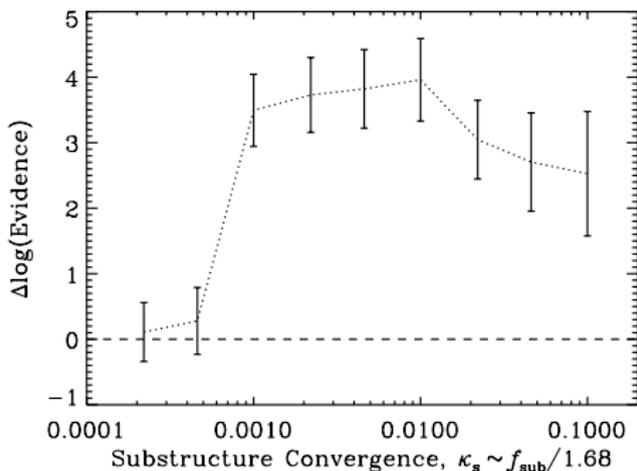
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Results

Recall: $dN/dm \propto m^{-1.9}$ for $m \in 10^7 - 10^{10} M_{\odot}$



$\Rightarrow f_{\text{sub}} > 0.00077$ at Einstein radius

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Extended source lenses: Arcs and rings

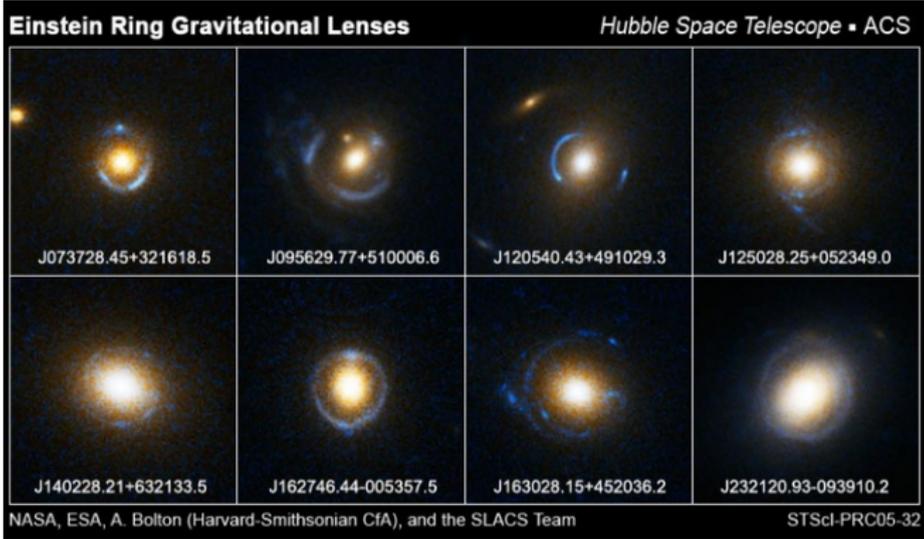


Figure: Arcs and rings from SLACS (<http://www.slacs.org>).

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Source reconstruction

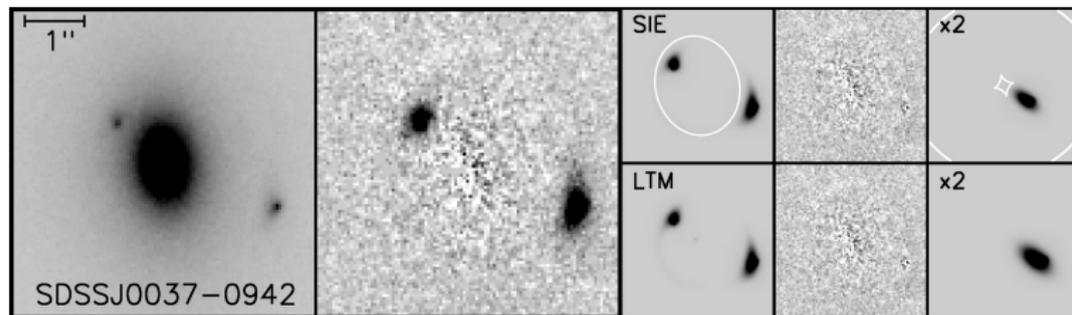


Figure: Example of source reconstruction in a SLACS lens (Bolton et al. 2008ApJ...682..964B)

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Source reconstruction

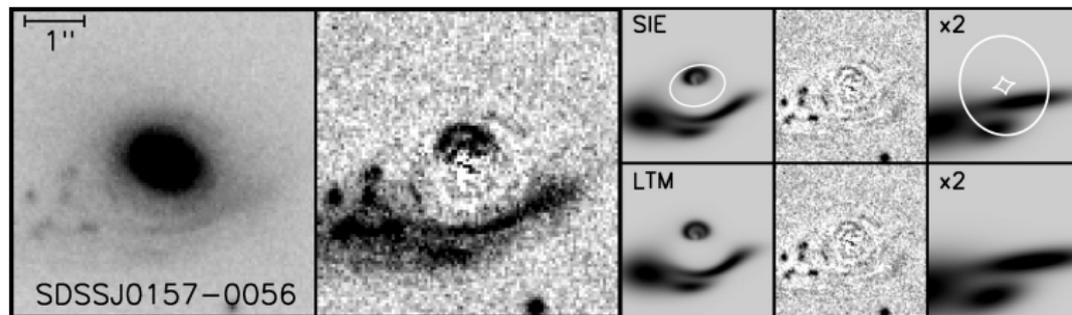


Figure: Example of source reconstruction in a SLACS lens (Bolton et al. 2008ApJ...682..964B)

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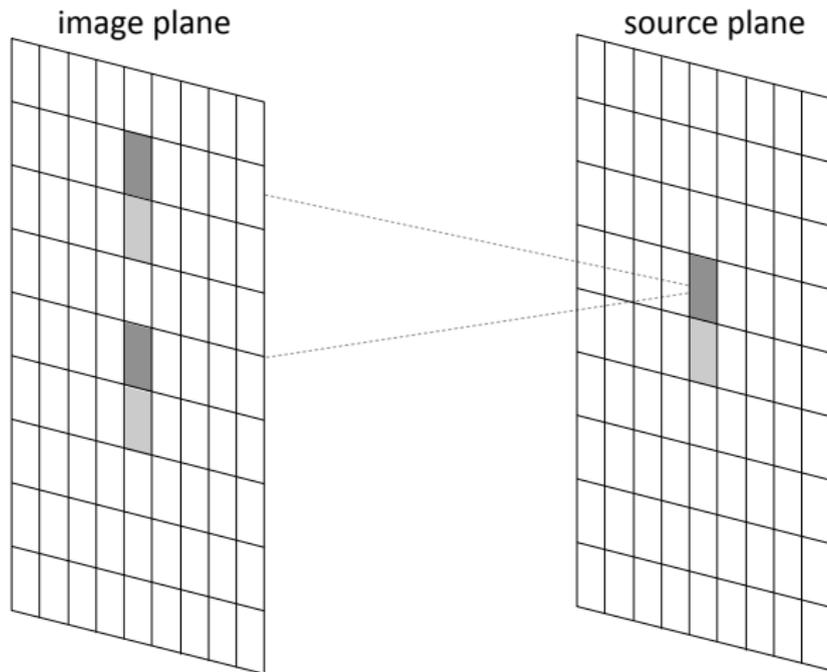
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Lensing conserves surface brightness



$$\mathbf{d} = \mathbf{L}\mathbf{s}$$

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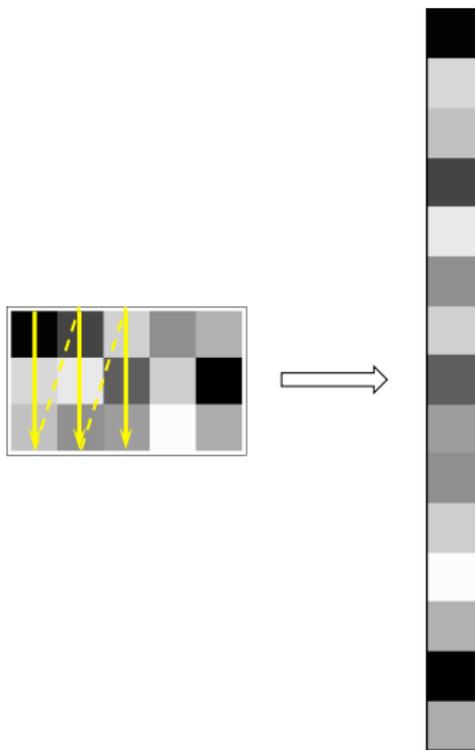
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“Unfold” 2-d image into vector



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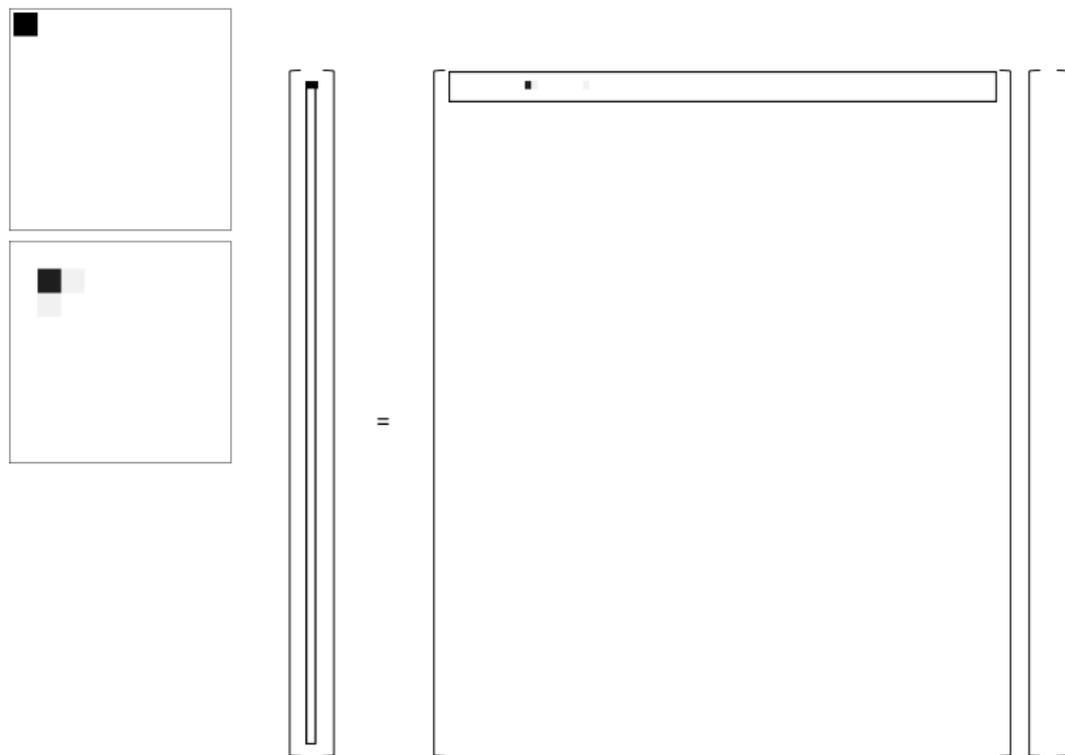
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Constructing the lensing operator



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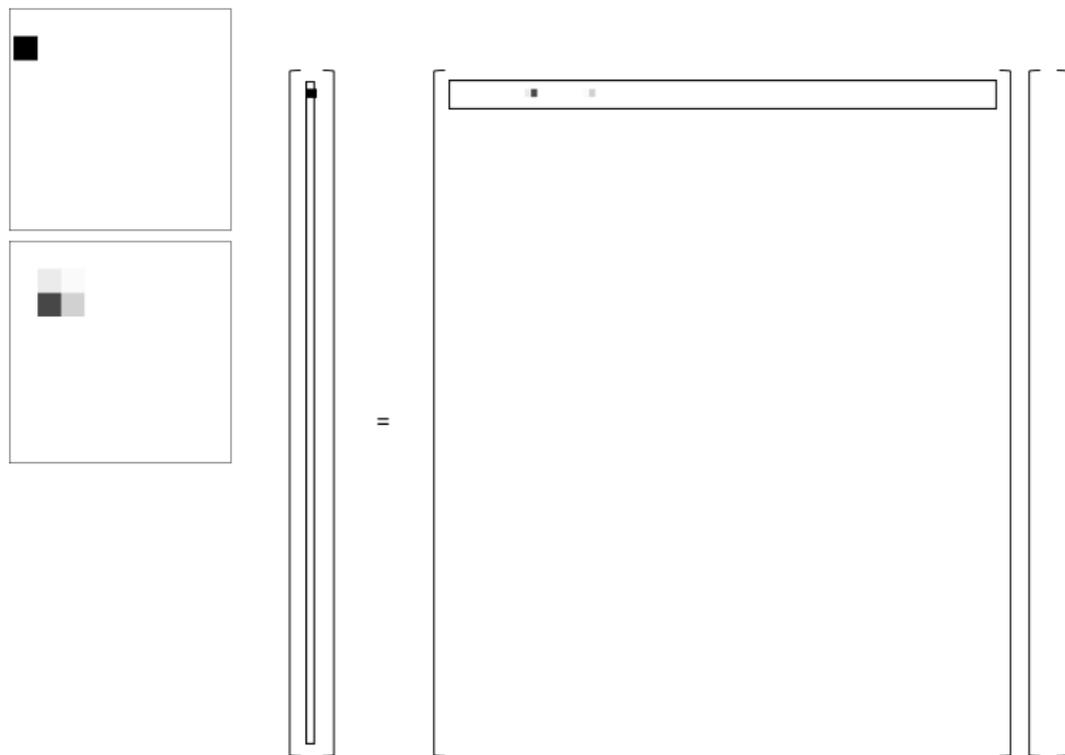
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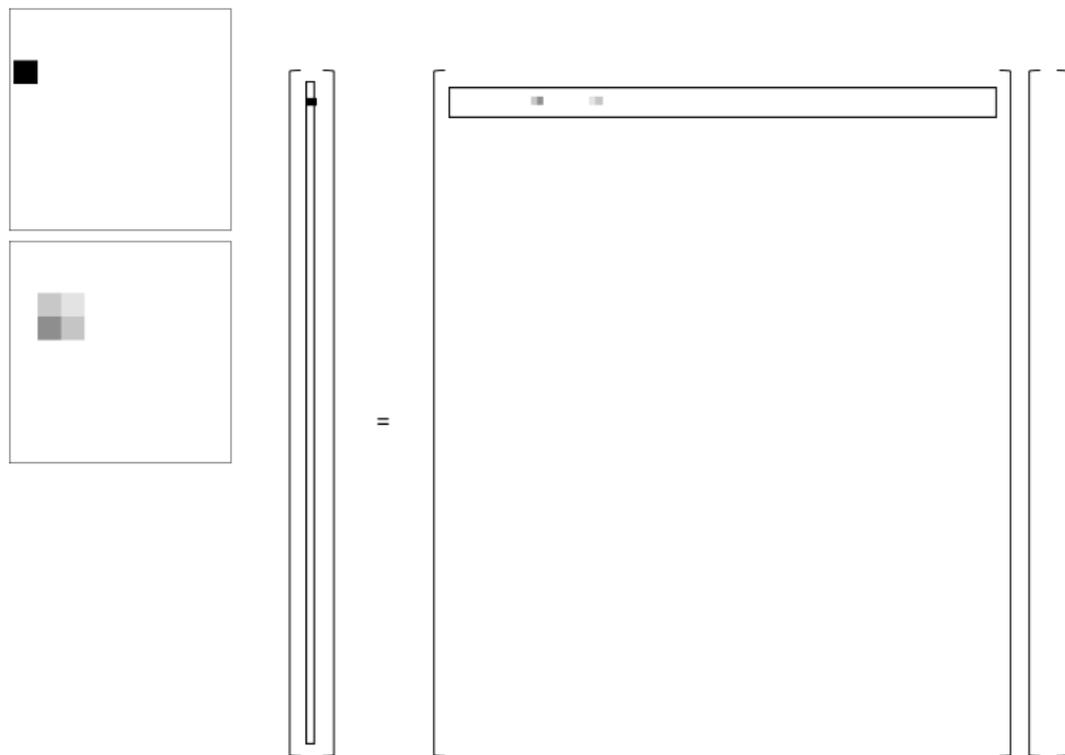
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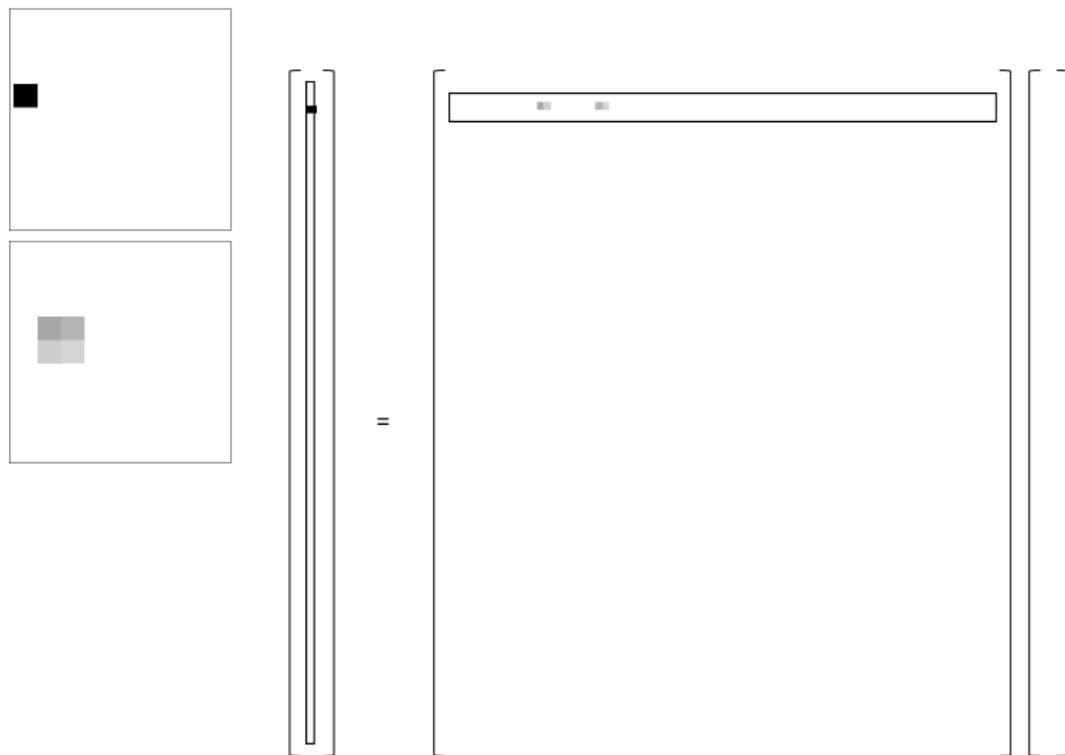
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Pixelated sources

pure surface brightness map:

$$\mathbf{d} = \mathbf{L}_0 \mathbf{s}$$

with PSF:

$$\mathbf{d} = \mathbf{L} \mathbf{s} \quad \text{where} \quad \mathbf{L} = \mathbf{B} \mathbf{L}_0$$

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goodness of fit:

$$\chi_{\text{img}}^2 = (\mathbf{L} \mathbf{s} - \mathbf{d}^{\text{obs}})^t \mathbf{S}_d^{-1} (\mathbf{L} \mathbf{s} - \mathbf{d}^{\text{obs}})$$

in general, more parameters than constraints, so a large family of solutions

many of the solutions may be unphysical (e.g., lots of negative flux) or merely implausible (e.g., spikes or weird shapes)

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Regularization

goal: penalize models that are unrealistic

- ▶ penalize spikes

$$\chi_{\text{reg}}^2 \sim \sum s_j^2 = \mathbf{s}^t \mathbf{s}$$

- ▶ penalize large gradients: finite differencing $\rightarrow \mathbf{v} = \mathbf{H}_v \mathbf{s}$ so

$$\chi_{\text{reg}}^2 \sim \mathbf{v}^t \mathbf{v} \sim \mathbf{s}^t \mathbf{H}_v^t \mathbf{H}_v \mathbf{s}$$

- ▶ penalize large curvature: again finite differencing \rightarrow

$$\chi_{\text{reg}}^2 \sim \mathbf{s}^t \mathbf{H}_a^t \mathbf{H}_a \mathbf{s}$$

all told, use penalty function of the form

$$\chi_{\text{reg}}^2 \sim \mathbf{s}^t \mathbf{H}^t \mathbf{H} \mathbf{s}$$

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with quadratic regularization, full χ^2 is

$$\chi^2 = (\mathbf{L} \mathbf{s} - \mathbf{d}^{\text{obs}})^t \mathbf{S}_d^{-1} (\mathbf{L} \mathbf{s} - \mathbf{d}^{\text{obs}}) + \lambda_s \mathbf{s}^t \mathbf{H}^t \mathbf{H} \mathbf{s}$$

where λ_s controls the strength of the regularization:

- ▶ low $\lambda \rightarrow$ more emphasis on fit quality
- ▶ high $\lambda \rightarrow$ more emphasis on regularization

optimal source found analytically — solve $\nabla_s \chi^2 = 0$ or

$$(\mathbf{L}^t \mathbf{S}_d^{-1} \mathbf{L} + \lambda_s \mathbf{H}^t \mathbf{H}) \mathbf{s} = \mathbf{L}^t \mathbf{S}_d^{-1} \mathbf{d}^{\text{obs}}$$

(Warren & Dye 2003; Dye & Warren 2005; Treu & Koopmans 2004; Koopmans 2005; Suyu et al. 2006; Vegetti & Koopmans 2009; coming "soon" to lensmodel)

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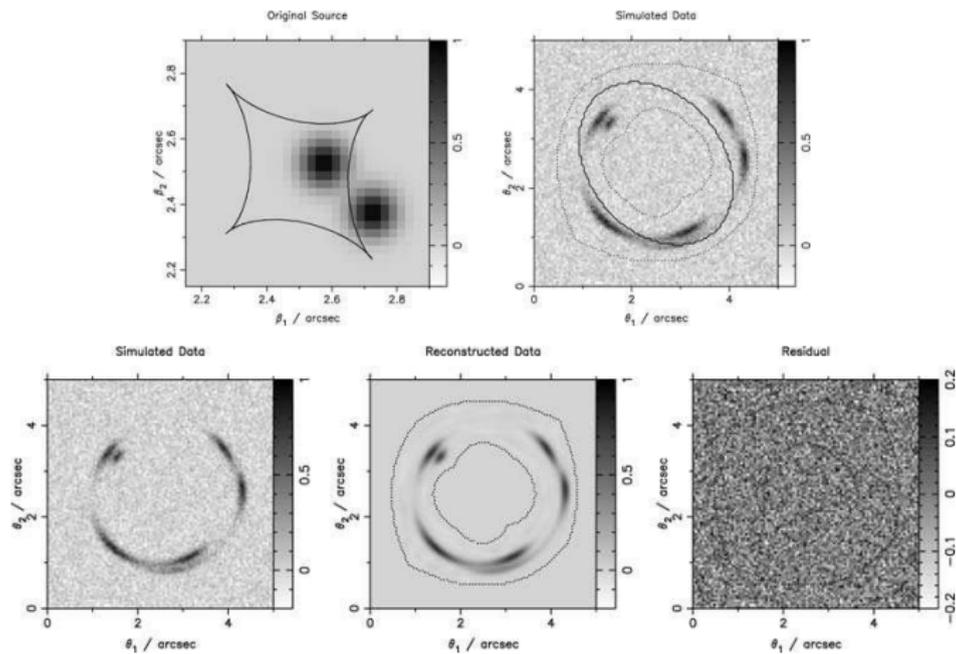
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Test case

Suyu et al. 2006MNRAS.371..983S



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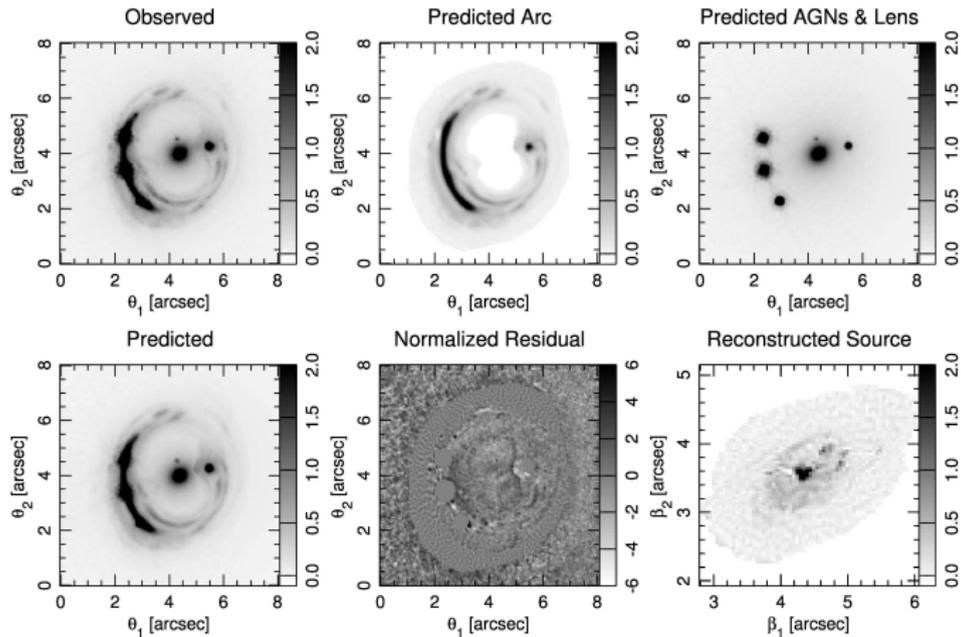
Multipole/Taylor

Mass pixels

Other

RX J1131–1231

Suyu et al. arXiv:1208.6010



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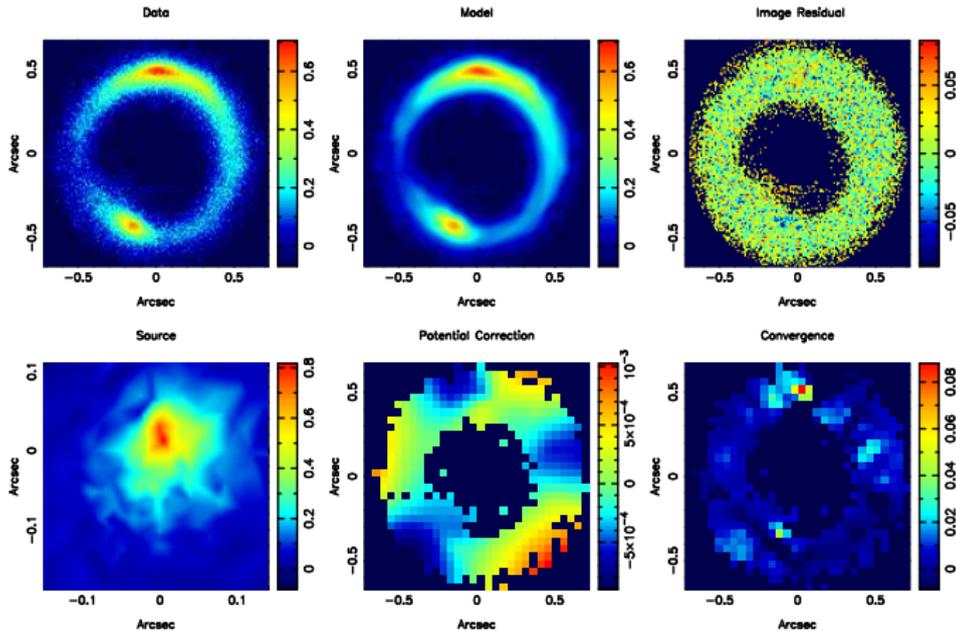
Multipole/Taylor

Mass pixels

Other

B1938+666

Vegetti et al. 2012Natur.481..341V



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Free-form mass models

expand potential or mass in terms of some basis functions

$$\phi(\mathbf{x}) = \sum_{\nu} a_{\nu} f_{\nu}(\mathbf{x})$$

parametric vs. non-parametric?

better: over- vs. under-constrained

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Constraint equations

theory:

$$\begin{aligned}\mathbf{u} &= \mathbf{x} - \nabla\phi(\mathbf{x}) \\ \Delta t_{ij} &= t_0 \left[\frac{1}{2} (|\mathbf{x}_i - \mathbf{u}|^2 - |\mathbf{x}_j - \mathbf{u}|^2) - \phi(\mathbf{x}_i) + \phi(\mathbf{x}_j) \right] \\ &= t_0 \left[\frac{1}{2} (|\mathbf{x}_i|^2 - |\mathbf{x}_j|^2) - (\mathbf{x}_i - \mathbf{x}_j) \cdot \mathbf{u} - \phi(\mathbf{x}_i) + \phi(\mathbf{x}_j) \right]\end{aligned}$$

constraints from positions and time delays are linear in a_ν , \mathbf{u}^{mod} , and t_0^{-1} :

$$\begin{aligned}\sum_{\nu} a_{\nu} \nabla f_{\nu}(\mathbf{x}_i^{\text{obs}}) + \mathbf{u}^{\text{mod}} &= \mathbf{x}_i^{\text{obs}} \\ \left\{ \sum_{\nu} a_{\nu} [f_{\nu}(\mathbf{x}_i^{\text{obs}}) - f_{\nu}(\mathbf{x}_j^{\text{obs}})] + \right. \\ \left. (\mathbf{x}_i^{\text{obs}} - \mathbf{x}_j^{\text{obs}}) \cdot \mathbf{u}^{\text{mod}} + t_0^{-1} \Delta t_{ij}^{\text{obs}} \right\} &= \frac{1}{2} (|\mathbf{x}_i|^2 - |\mathbf{x}_j|^2)\end{aligned}$$

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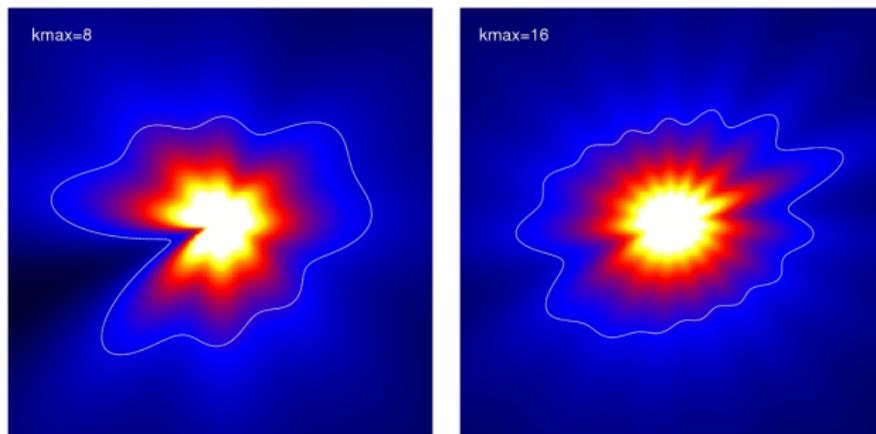
Other

Multipole models

assume isothermal profile but allow general angular structure

$$\phi_{\text{gal}}(r, \theta) = r \sum_{m=0}^{m_{\text{max}}} (a_m \cos m\theta + b_m \sin m\theta)$$

apply to a lens with anomalous flux ratios:



(Congdon & CRK 2005; also see Evans & Witt 2003; Yoo et al. 2005, 2006)

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Multipole/Taylor models

generalize radial profile — images are often “near” Einstein radius, so do Taylor series expansion in $r - r_0$ (or equivalently $r/r_0 - 1$):

$$\phi(r, \theta) = \sum_{m=0}^{m_{\max}} \sum_{n=0}^{n_{\max}} \left(\frac{r}{r_0} - 1 \right)^n (a_{mn} \cos m\theta + b_{mn} \sin m\theta)$$

Trotter et al. 2000ApJ...535..671T apply to MG J0414+0534

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Pixelated mass maps

mass pixels — “pixelens” (Saha & Williams 2000, 2004, etc.)

many free parameters — need priors:

- ▶ all pixel densities must be non-negative
- ▶ density gradient must point within 45° of lens center
- ▶ no pixel value may exceed the average of its neighbors by more than a factor of two (except for central pixel)
- ▶ projected density profile must be steeper than $r^{-1/2}$
- ▶ if desired, mass map may be required to have inversion symmetry

these eliminate models that are grossly unphysical, but are not especially restrictive

- ▶ non-negative Σ does not automatically imply non-negative ρ
- ▶ no check on number of images
- ▶ shapes may still be implausible

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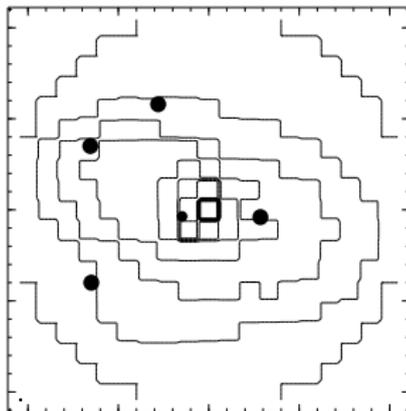
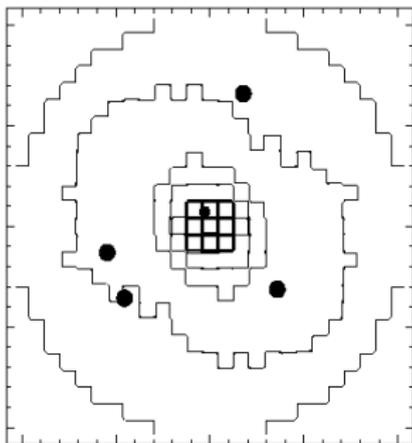
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examples from Saha & Williams 2004AJ....127.2604S

these show *average* solutions; can also explore range of solutions



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other effects I have not gone into...

- ▶ pixelated potential corrections

(Suyu et al. 2009, 2010, 2012; Koopmans 2005; Vegetti et al. 2009, 2010, 2012)

- ▶ complicated environments

(Wong et al. 2011)

- ▶ line-of-sight effects (multi-plane lensing)

(Wong et al. 2011; Suyu et al. 2012)

Bottom line: “precision lensing” is hard work, but we are learning how to do it!

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