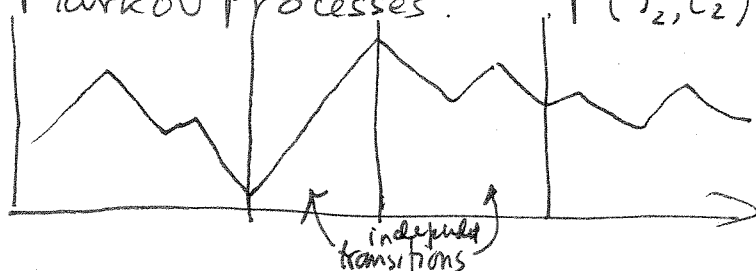


Stochastic Processes

Time dependent random variable examples.

Markov Processes: $P(y_2, t_2) = \int dy_1 P(y_2, t_2 | y_1, t_1) P(y_1, t_1)$



If prob. distr. at future totally determined by the y at present.

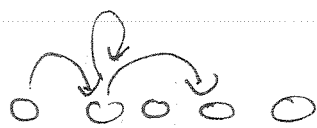
$$t_1 < t_2 < t_3$$

$$P(y_3, t_3 | y_2, t_2; y_1, t_1) = P(y_3, t_3 | y_2, t_2)$$

Simplest example: Markov chain

Y has M realizations. $y(1) \dots y(M)$

$$P(n, s+1) = \sum_m Q_{nm}(s) P(m, s)$$



Q Transition matrix

Note that $\sum_n Q_{nm}(s) = 1$

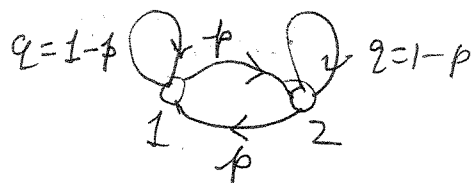


Example already seen: ~~rand~~ Biased random walk

$$\begin{pmatrix} 0 & q & 0 & 0 & \dots \\ p & 0 & q & 0 & \dots \\ 0 & p & 0 & q & \dots \\ 0 & 0 & p & 0 & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

Matrix notation $IP(s+1) = Q IP(s) \Rightarrow IP(s) = Q^s IP(0)$

Let us take an even simpler example



$$Q = \begin{pmatrix} q & p \\ p & q \end{pmatrix}$$

Let us start with a state
say $P(1) = 1$ $P(2) = 0$

$$\underline{P}(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$P(s) = ?$$

$$Q^s P(0)$$

Note that Q has two eigenvectors $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$

$$Q \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} p+q \\ p+q \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow \text{eigenvalue } \lambda = 1$$

$$Q \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} q-p \\ p-q \end{pmatrix} = (q-p) \begin{pmatrix} 1 \\ -1 \end{pmatrix} \Rightarrow \text{eigenvalue } \lambda = q-p = 1-2p$$

Note that $|\lambda| < 1$

$$P(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

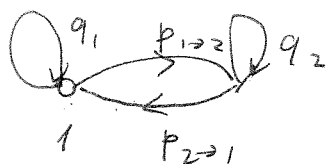
$$Q^s P(0) = \frac{Q^s}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \frac{Q^s}{2} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} + (1-2p)^s \begin{pmatrix} \frac{1}{2} \\ -\frac{1}{2} \end{pmatrix}$$

As $s \rightarrow \infty$ $(1-2p)^s \rightarrow 0$, as long as $p \neq 0, 1$

So $P(s) \rightarrow \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$ as $s \rightarrow \infty$

The convergence is determined by how small $|1-2p|$ is.
~~the~~ Is $s \gg \frac{1}{\ln |1-2p|}$ then $|1-2p|^s \ll 1$

~~What~~ What if the system was
asymmetric?



$$Q = \begin{pmatrix} q_1 & p_{2 \rightarrow 1} \\ p_{1 \rightarrow 2} & q_2 \end{pmatrix}$$

We could once more ask for the eigenvalues and eigenvectors. ~~We~~ We could do it by brute force. But let us do it ~~with~~ with less sweat

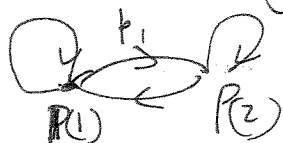
Note $\mathbb{1}^T Q = (1 \ 1) \begin{pmatrix} q_1 & p_{2 \rightarrow 1} \\ p_{1 \rightarrow 2} & q_2 \end{pmatrix} = (q_1 + p_{1 \rightarrow 2} \quad q_2 + p_{2 \rightarrow 1}) = \mathbb{1}^T$

So $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ is ~~an~~ ^a left eigenvector as a consequence of prob conserv. The corresponding eigenvalue is 1

We know that the trace $Q = \text{sum of eigenvalues}$

$$1 + \lambda_- = q_1 + q_2 \Rightarrow \lambda_- = 1 - p_{1 \rightarrow 2} p_{2 \rightarrow 1}, \text{ Once more } |1 - \lambda_-|$$

The right eigenvector corresponding to eigenvalue 1 is easy to figure out



$P(1)$ ~~would~~ would not change if loss $p_{2 \rightarrow 1} P(1)$ equals gain $p_{1 \rightarrow 2} P(2)$. So $\frac{P(1)}{P(2)} = \frac{p_{2 \rightarrow 1}}{p_{1 \rightarrow 2}} \Rightarrow P(1) = \frac{P(1)}{P(1) + P(2)} = \frac{p_{2 \rightarrow 1}}{p_{2 \rightarrow 1} + p_{1 \rightarrow 2}}$

$$P(s) \rightarrow \begin{pmatrix} \frac{p_{2 \rightarrow 1}}{p_{2 \rightarrow 1} + p_{1 \rightarrow 2}} \\ \frac{p_{1 \rightarrow 2}}{p_{2 \rightarrow 1} + p_{1 \rightarrow 2}} \end{pmatrix}$$

An example of detailed balance at work.

The timescale of convergence given by $1 / \log \left(\frac{1}{1 - p_{1 \rightarrow 2} p_{2 \rightarrow 1}} \right)$

~~that~~ ^{always} that we find one eigenvector with eigenvalue one in ^{the} consequence of probability conservation. The fact that all other eigenvalues turn out to be of smaller magnitude is the consequence of Perron Frobenius theorem

Def: Matrix is ^{called} positive (non-negative) means all entries are ≥ 0 (non-negative)
Often denoted as $A > 0$ ($A \geq 0$)

Def: A ~~matrix~~ ^{called} Matrix is ~~regular~~ ^{regular} if $A^k > 0$ for $k \geq 1$

Perron-Frobenius Thm for regular matrices
For a non-negative regular matrix A

- (a) There is an eigenvalue λ_{PF} of A that is real and positive with positive left and right eigenvectors (called the PF eigenvectors)
- (b) For any other eigenvalue $|\lambda| < \lambda_{PF}$
- (c) The eigenvalue λ_{PF} is simple, i.e. has multiplicity one and corresponds to 1×1 Jordan block.

If one drops the regularity condition and only has $A \geq 0$
Other λ 's case s.t. $|\lambda| < \lambda_{PF}$
 λ_{PF} is real and nonneg with eigenvectors that are non negative (λ_{PF} need not be unique)

Irregular example



$$Q = \begin{pmatrix} q & 0 \\ p & 1 \end{pmatrix}$$

If we have a matrix like Q , which satisfies $Q \geq 0$ and $\mathbb{1}^T Q = \mathbb{1}^T$, Q is called a stochastic matrix.

Note that if v_{PF} is a right PF eigenvector then $Q v_{PF} = \lambda_{PF} v_{PF}$

$$\text{But } (\mathbb{1}^T Q) v_{PF} = \mathbb{1}^T v_{PF}$$

$$\mathbb{1}^T (Q v_{PF}) = \lambda_{PF} \mathbb{1}^T v_{PF}$$

⊗ Since $v_{PF} \neq 0$ and $v_{PF} \geq 0$ $\mathbb{1}^T v_{PF} \neq 0$
 $\Rightarrow \boxed{\lambda_{PF} = 1}$

What does ~~regularity~~ ^{regularity} mean in the context of stochastic processes? $Q_{ij}^k > 0$ means there is a nonzero probability of transition from j to i in k steps. Thus regularity just means that if we take a large enough number of steps then every state i could be accessed from every other state j in that. Note that for every pair i, j , there should be a path of the same length k .
 Irregular stochastic matrices.



or

For simplicity we focus on the case where the ~~right~~ ^{right} eigenvectors each span the N dimensional vector space

Any $P(0) = \sum \alpha_i u_i$ right eigenvector

$$P(s) = \sum \alpha_i \lambda_i^s u_i = \sum \alpha_i \lambda_i^s u_i$$

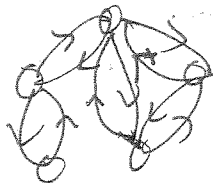
$$= \alpha_{PF} u_{PF} + \sum_{\lambda \neq \lambda_{PF}} \lambda_i^s u_i$$

$|\lambda_i| < \lambda_{PF} = 1$ for regular Q

So finally $P(s) \rightarrow \alpha_{PF} u_{PF} = P_{ST}$
 the stationary probability distribution.
 If u_{PF} is normalized so that $\mathbf{1}^T u_{PF} = \sum u_{PF}(i) = 1$
 then $\alpha_{PF} = 1$ $u_{PF} = P_{ST}$

Thus, if we have a finite number of states and have a regular transition matrix, we are guaranteed, in the long term, to the stationary state. Also the stationary state is unique.

This observation could be utilized to do sampling from a probability distribution: Invent a stochastic process s.t. the stationary distrⁿ is the intended one. Let us invent a transition matrix Q s.t.
 $Q_{nm} P(m) = Q_{nm} P(n)$
 along with the condition that Q is regular.

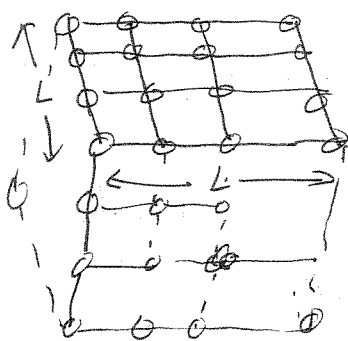


[Roughly meaning you could go from any state to any other state by these moves]

Why do you need this? ~~100%~~ If we know $P(n)$ why can't we just calculate $\sum_{n=1}^M Q(n) P(n)$ for any average?

The answer is that often in Stat mech we are dealing with problems where M is exponential in the size of the system (or number of particles or spins -

Example: Particles on a lattice



L^d sites

N particles $N \ll L^d$

$(N)^{L^d}$ or $L^d C_N$
depending upon howd core or not

Spins on a lattice

$$S_i = \pm 1$$



$$2^{L^d}$$



$$L \sim 10^8 \left(= \frac{1 \text{ cm}}{1 \text{ \AA}} \right)$$

$$L^2 \sim 10^{12}$$

$$L^3 \sim 10^{24}$$

(close to Avogadro's #)

Even $2^{(10^8)}$ is huge!



Allowed moves:

Particle hopping,
Spin flips -

Note that $\frac{Q_{nm}}{Q_{mn}} = \frac{P(n)}{P(m)}$ is satisfied

by Q even if $Q_{nm} \rightarrow \lambda_{nm} Q_{nm}$ where λ_{nm} is symmetric. We need to make a choice!

One such choice leads to Metropolis's algorithm

If $m \rightarrow n$ is an allowed move, take it with probability $\min(1, \frac{P(n)}{P(m)})$.

Convergence time is supposed to be finite, However as $N \rightarrow \infty$, it could tend to infinity.

Continuous time version of ^{Markov} Stochastic Process: Master equation

$$\frac{d}{dt} P(t) = W P(t)$$

$$Q = I + \Delta t W$$

$$\text{More explicitly } \frac{dP(m,t)}{dt} = \sum_n W_{mn} P(n,t)$$

Note that $W_{mn} \geq 0$ for $m \neq n$, but $W_{nn} \leq 0$ so that $\sum_m W_{mn} = 0$

One could show that W always has a zero eigenvalue and, under appropriate conditions, all other eigenvalues ~~are~~ have a neg. real part.