

# Oscillations

Time invariant system

Equilibrium  $Q_i = -\left(\frac{\partial V}{\partial q_i}\right) = 0$

$$\Rightarrow \frac{d}{dt} \left( \frac{\partial T}{\partial q_i} \right) = 0$$



Stable equilibrium: small perturbation produces small bounded motion around the rest position.

Motion in the vicinity of  $\blacksquare$  of a stable equilibrium.

$$q_i = q_{0i} + \eta_i$$

$$V(q_1, \dots, q_n) = V(q_{01} + \eta_1, \dots, q_{0n} + \eta_n)$$

$$= V(q_{01}, \dots, q_{0n}) + \left(\frac{\partial V}{\partial q_i}\right)_0 \eta_i$$

$$+ \frac{1}{2} \sum \left(\frac{\partial^2 V}{\partial q_i \partial q_j}\right)_0 \eta_i \eta_j + \dots$$

[summation convention!]

$$\left(\frac{\partial V}{\partial q_i}\right)_0 = 0 \quad \text{if } q_{0i} \rightarrow \text{eqm}$$

Drop the constant and stop at the lead term

$$V = \frac{1}{2} \left( \frac{\partial^2 V}{\partial q_i \partial q_j} \right)_0 \eta_i \eta_j$$

$$= \frac{1}{2} V_{ij} \eta_i \eta_j$$

$V_{ij}$  is a <sup>constant</sup> symmetric matrix.

In time invariant systems,

$$T = \frac{1}{2} m_{ij}(q_1, \dots, q_n) \dot{q}_i \dot{q}_j$$

$$m_{ij}(q_1, \dots, q_n) = m_i(q_{01}, \dots, q_{0n})$$

$$+ \left( \frac{\partial m_{ij}}{\partial q_k} \right)_0 \eta_k + \dots$$

$$\dot{q}_i = \dot{q}_j$$

T has terms like  $\frac{1}{2} (m_{ij})_0 \dot{q}_i \dot{q}_j + O(\eta \dot{q}_i \dot{q}_j)$

we want to keep only second order terms in  $\eta_i$ .  $(m_{ij})_0 \rightarrow T_{ij}$ , a constant symmetric matrix again

$$T = \frac{1}{2} T_{ij} \eta_i \eta_j$$

$$L = \frac{1}{2} (T_{ij}\dot{\eta}_i\dot{\eta}_j + V_{ij}\eta_i\eta_j)$$

Equation of motion

$$T_{ij}\ddot{\eta}_i + V_{ij}\eta_j = 0$$

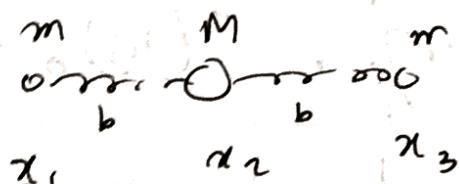
~~For~~ In many problems

$$T_{ij} (= T_i \delta_{ij}) \text{ No sum over } i.$$

$$T_i \ddot{\eta}_i + V_{ij}\eta_j = 0, \text{ for } i = 1, 2, 3$$

Before we go on, let us look at an example that we will return to soon.

Linear triatomic molecule with symmetry



$$T = \frac{1}{2} (m_1 \dot{x}_1^2 + M \dot{x}_2^2 + m_3 \dot{x}_3^2)$$

$$V = \frac{k}{2} (x_2 - x_1 - b)^2 + \frac{k}{2} (x_3 - x_2 - b)^2$$

$$\eta_i = x_i - x_{0i}$$

At equilibrium

$$x_{02} - x_{01} = b = x_{03} - x_{02}$$

$$\begin{aligned} V &= \frac{k}{2} \{ (\eta_2 - \eta_1)^2 + (\eta_3 - \eta_2)^2 \} \\ &= \frac{k}{2} [ \eta_1^2 + 2\eta_2^2 + \eta_3^2 \\ &\quad - 2\eta_1\eta_2 - 2\eta_2\eta_3 ] \end{aligned}$$

$$V_{ij} \rightarrow V = \begin{pmatrix} k & -k & 0 \\ -k & 2k & -k \\ 0 & -k & k \end{pmatrix}$$

$$T = \frac{1}{2} (m_1 \dot{x}_1^2 + M \dot{x}_2^2 + m_3 \dot{x}_3^2)$$

$$T_{ij} \rightarrow T = \begin{pmatrix} m & 0 & 0 \\ 0 & M & 0 \\ 0 & 0 & m \end{pmatrix}$$

(Back to generalities)

Usually  $V_{ij}$  (and sometimes  $T_{ij}$ ) end up coupling all coordinates. How do we solve it?

Try oscillatory solutions of the form:

$$\eta_i = c_i e^{i\omega t}$$

$$\{ \text{LHS} = T_{ij} \ddot{\eta}_i + V_{ij} \dot{\eta}_j = 0$$

$$\text{Let } \omega^2 = D - T_{ij} (-\omega^2 c_i a_j) + V_{ij} (c_i a_j) = 0$$

$$\text{or } (V_{ij} - \omega^2 T_{ij}) a_j = 0$$

Matrix version

$$(V_a - \lambda I) a = 0$$

$$\omega^2 = \lambda$$

Generalized eigenvector problem

$$|\underline{V} - \lambda T| = 0$$

allows for non-trivial  $\underline{a}$

If  $T$  was identity  $\lambda$ 's would be real and  $a_k$ 's orthogonal.

$$\underline{V} \underline{a}_k = \lambda_k T \underline{a}_k$$

$$\underline{a}_k^+ \underline{V} = \lambda_k^+ \underline{a}_k^+ \quad \underline{a}_k^+ = \underline{\tilde{a}}_k^*$$

$$\underline{a}_k^+ \underline{V} \underline{a}_k = \lambda_k \underline{a}_k^+ T \underline{a}_k$$

$$\underline{a}_k^+ = \lambda_k^+ \underline{a}_k^+$$

$$\text{If } (\lambda_k^- \lambda_k^+) \underline{a}_k^+ T \underline{a}_k = 0$$

$$l=k \quad \underline{a}_k^+ T \underline{a}_k \text{ is real}$$

Physical K.E. is also positive definite so  $\underline{a}_k \neq 0$

$$\Rightarrow \underline{a}_k^+ T \underline{a}_k > 0$$

$$\Rightarrow \lambda_k^- = \lambda_k^* \Rightarrow \lambda_k \text{ are real}$$

Then  $(\lambda_k - \lambda_l)^+ \underline{a}_k^\top \underline{a}_k = 0$

is the same as  $(\lambda_k - \lambda_l)^+ \underline{a}_l^\top \underline{a}_k = 0$

If  $\lambda_k \neq \lambda_l$   $\underline{a}_l^\top \underline{a}_k = 0$

[When two roots are the same but  $a_k \neq a_l$ , needs more careful discussion.]

Also

$$\lambda_k = \frac{\underline{a}_k^\top V \underline{a}_k}{\underline{a}_k^\top I \underline{a}_k}$$

If  $V$  is positive semi-definite ( $\equiv$  stability)  
 $\underline{a}_k^\top V \underline{a}_k \geq 0$

$$\Rightarrow \lambda_k \geq 0$$

$$V(q) = \begin{cases} \frac{1}{2} v_{11} (q - q_0)^2 & q < q_0 \\ \frac{1}{2} v_{11} (q - q_0)^2 & q \geq q_0 \end{cases}$$

Stable  $v_{11} > 0$  and  $v_{11} < 0$

$$V = [v_{11}]$$

[Note on  $\underline{a}_k^T \nabla a_k$  etc]

$\underline{a}_k$  is complex in general

$$\underline{a}_k = \underline{\alpha}_k + i\underline{\beta}_k \quad \underline{\alpha}_k, \underline{\beta}_k \text{ real and } i\text{m } \underline{\beta} \text{ part}$$

$$\therefore \underline{a}_k^T \nabla a_k = \underline{\alpha}_k^T \nabla \underline{\alpha}_k + (-i\underline{\beta}_k)^T \nabla \underline{\beta}_k$$

$$+ i \left\{ \underline{\alpha}_k^T \nabla \underline{\beta}_k - \underline{\beta}_k^T \nabla \underline{\alpha}_k \right\}$$

↑ Transpose ↑  
of each other  
for a scalar.

$$\underline{a}_k^T \nabla a_k = \underline{\alpha}_k^T \nabla \underline{\alpha}_k + \underline{\beta}_k^T \nabla \underline{\beta}_k$$

Think of  $\underline{\alpha}_k$  &  $\underline{\beta}_k$  as velocity patterns. If any of them are non zero, physical k. E. s would be non zero.]

(P.S. If  $\underline{\alpha}_k$  &  $\underline{\beta}_k$  are not following the pattern of conjugate, the result will be zero.)

But we can't find out the pattern of  $\underline{\alpha}_k$  &  $\underline{\beta}_k$  from the given information.

We could scale  $a_k$  so that

$$a_k^+ \cdot a_k = 1 \text{ (norm 1)}$$

Organize  $A = [a_1 \ a_2 \ \dots \ a_n]$

column vectors

$$A^+ T A = I$$

identity matrix

Since the eigenvalues and the matrix are real, it turns out  $a_k$  are real.

$$So \ A^+ T A = I$$

Similarity transformation  $C' = BCB^{-1}$

Congruence  $C' = ACA^{-1}$

for orthogonal matrices, they are ~~the same~~.  
the same, i.e.  $C' = ACA^{-1}$  is ~~both~~ congruent

and similarity transformation. In our case, in general,  $A$  is not orthogonal.

Let us introduce a diagonal matrix

$$\underline{\lambda} = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_n \end{pmatrix} \text{ or } \lambda_{ek} = \lambda_k \delta_{ek}$$

(no sum over  $k$ )

$$V_{ij} a_{jk} = T_{ij} a_{jk} \lambda_k$$

(no sum over  $k$ )

Can now be written as

$$V_{ij} a_{jk} = T_{ij} a_{jk} \lambda_k$$

$$\text{Or, } \underline{V} \underline{A} = \underline{T} \underline{A} \underline{\lambda}$$

$$\text{If, } \underline{A}^T \underline{A} = \underline{I}$$

$$\text{then } \underline{\tilde{A}} \underline{V} \underline{A} = \underline{\lambda}$$

Note that

So, we want to find a congruence transformation that reduces  $\underline{T}$  to identity matrix and  $\underline{V}$  to a diagonal matrix.  
Simultaneous diagonalization of two quadratic forms!

Here's the algorithm.

$$\underline{T} = \frac{1}{2} \underline{\eta} \underline{T} \underline{\eta} = \underline{V} = \frac{1}{2} \underline{\eta} \underline{V} \underline{\eta}$$

Diagonalize  $\underline{T}$  by finding orthogonal matrix  $\underline{O}$ , and transformed variables  $\underline{\gamma}$

$$\underline{\gamma} = \underline{O} \underline{\eta} \quad \text{and} \quad \underline{T} = \frac{1}{2} \underline{\eta} \underline{O} \underline{T} \underline{O} \underline{\eta}$$

$$\underline{V} = \frac{1}{2} \underline{\eta} \underline{O} \underline{V} \underline{O} \underline{\eta}$$

$$\text{Let } \underline{\underline{O}} \underline{T} \underline{O} = \begin{pmatrix} m_1 & & & \\ & m_2 & & \\ & & \ddots & \\ & & & m_n \end{pmatrix}$$

$$m_i > 0$$

Choose  $\underline{S} = \left( \frac{1}{\sqrt{m_1}}, \frac{1}{\sqrt{m_2}}, \dots, \frac{1}{\sqrt{m_n}} \right)$

and let  $\underline{y} = \underline{S} \underline{\xi}$

$\blacksquare$  Note that  $\tilde{S} \tilde{O} \tilde{T} \tilde{O}, \tilde{S} = \mathbb{1}$

[Remember  $\tilde{S} = S$ ]

$$\text{So } T = \frac{1}{2} \underbrace{\tilde{\xi} \tilde{S} \tilde{O}, \tilde{T} \tilde{O}, \tilde{S} \tilde{\xi}}_{= \frac{1}{2} \tilde{\xi} \tilde{\xi}^T = \frac{1}{2} \sum \tilde{\xi}_i^2}$$

$$V = \frac{1}{2} \tilde{\xi} \underbrace{\tilde{S} \tilde{O}, V \tilde{O}, \tilde{S} \tilde{\xi}}$$

$$= \frac{1}{2} \tilde{\xi} \tilde{B} \tilde{\xi}^T$$

$\tilde{B}$  is a symmetric matrix. Diagonalize it with an orthogonal matrix  $O_2$ .

In other words, let  $\tilde{\xi} = O_2 S$

$$V = \frac{1}{2} \tilde{\xi} \underbrace{\tilde{O}_2 \tilde{B} \tilde{O}_2 \tilde{\xi}}_{\text{Diagonal } \lambda} = \frac{1}{2} \tilde{\xi} \tilde{\lambda} \tilde{\xi}^T$$

Note that  $T = \frac{1}{2} \tilde{\xi} \underbrace{\tilde{O}_2 \tilde{T} \tilde{O}_2 \tilde{\xi}}_{\mathbb{1}} = \frac{1}{2} \tilde{\xi} \tilde{\xi}^T$

So  $\underline{\lambda} = \underline{\tilde{S}}^T \underline{\tilde{S}}$ ,  $\underline{V} \underline{\lambda} \underline{V}^{-1}$

Our  $A = \underline{O}_1 \underline{S} \underline{O}_2$

$\underline{O}_1$  is orthogonal  
 $\underline{S}$  is diagonal  
 $\underline{O}_2$  is orthogonal

At the end:  $L = \frac{1}{2} \underline{\tilde{S}}^T \underline{\tilde{S}} - \frac{1}{2} \underline{\tilde{S}} \underline{\lambda} \underline{\tilde{S}}$

$$L = \frac{1}{2} \sum_i \tilde{s}_{ii}^2 - \frac{1}{2} \sum_i \lambda_i s_{ii}^2$$

For stable potential,  $\lambda_i = \omega_i^2 \geq 0$

$$L = \sum_i \left( \frac{1}{2} \tilde{s}_{ii}^2 - \frac{1}{2} \omega_i^2 \tilde{s}_{ii}^2 \right)$$

$\tilde{s}_{ii}$  independent oscillators

$s_i$  Normal modes / coordinates

$\omega_i$  frequencies of free vibration OR Resonant frequencies

Two examples:

1.  $T = \frac{1}{2} m(x_1^2 + x_2^2)$

$$V = \frac{1}{2} V_{ij} x_i x_j$$

$$T = \begin{pmatrix} m & 0 \\ 0 & m \end{pmatrix}$$

No need to diagonalize.

$$V = \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} \Rightarrow v_{21} = v_{12}$$

Diagonalize  $V$

$$\begin{vmatrix} v_{11} - \lambda & v_{12} \\ v_{21} & v_{22} - \lambda \end{vmatrix} = 0$$

$$(\lambda - v_{11})(\lambda - v_{22}) - v_{12}v_{21} = 0$$

$$\lambda^2 - (v_{11} + v_{22})\lambda + (v_{11}v_{22} - v_{12}v_{21}) = 0$$

$$\lambda_{1,2} = \frac{1}{2} \left( V_{11} + V_{22} \pm \sqrt{(V_{11} + V_{22})^2 - 4(V_{12}V_{21})} \right)$$

$$= \frac{1}{2} \left( V_{11} + V_{22} \pm \sqrt{(V_{11} - V_{22})^2 + 4V_{12}V_{21}} \right)$$

$$= \frac{1}{2} (V_{12} + V_{22} \pm \sqrt{(V_{11} - V_{22})^2 + 4V_{12}^2})$$

~~Two interesting cases:~~

a)  $|V_{12}| \ll |V_{11} - V_{22}|$

Let  $\frac{V_{12}}{V_{11} - V_{22}} = \delta$

$$\lambda_{1,2} = \frac{1}{2} \left[ V_{11} + V_{22} \pm (V_{11} - V_{22})(1 + \delta^2)^{1/2} \right]$$

$$\lambda_1 \approx V_{11} + (V_{11} - V_{22}) \cdot \delta^2 = V_{11} + V_{12}\delta$$

$$\lambda_2 \approx V_{22} - (V_{11} - V_{22}) \delta^2 = V_{22} - V_{12}\delta$$

~~The eigenvalues are~~

$$V - \lambda_1 \mathbb{I} = \begin{pmatrix} -v_{12}\delta & v_{12} \\ v_{12} & v_{22} - v_{11} + \delta \end{pmatrix} = \begin{pmatrix} v_{12}\delta & v_{12} \\ (v_{11} - v_{22})\delta - (v_{12}^2) & \delta(v_{11} + v_{22}) \end{pmatrix}$$

$$(V - \lambda_1 \mathbb{I}) \underline{q}_1 = 0$$

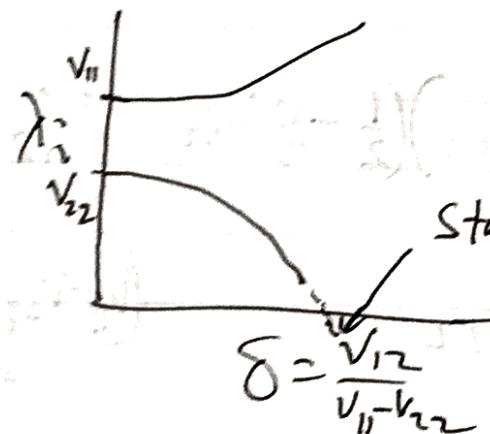
when  $v_{12} = 0$ , this is  $\begin{pmatrix} 0 & 0 \\ 0 & v_{22} - v_{11} \end{pmatrix}$

has eigenvector  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$

Now  $\underline{q}_1 \approx \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  upto order  $\delta^2$

Similar analysis shows  $\underline{q}_2 \approx \begin{pmatrix} -\delta \\ 1 \end{pmatrix}$

Small mixing of modes and  
level repulsion



$$\delta = \frac{v_{12}}{v_{11} - v_{22}}$$

$$b) |V_{12}| \gg |V_1 - V_{22}|$$

$$\varepsilon = \frac{V_{11} - V_{22}}{8V_{12}}$$

$$\lambda_{11,22} = \frac{V_{11} + V_{22}}{2} \pm |V_{12}| \left(1 + \frac{\varepsilon^2}{4}\right)^{1/2}$$

(Assume  $V_{12} > 0$ )

$$\lambda_1 \approx \frac{1}{2}(V_{11} + V_{22}) + V_{12} \cancel{- \varepsilon^2} + 8\varepsilon^2 V_{12}$$

$$= \frac{1}{2}(V_{11} + V_{22}) + V_{12} + (V_1 - V_{12})\varepsilon$$

Similarly

$$\lambda_2 = \frac{1}{2}(V_{11} + V_{22}) - V_{12} - (V_1 - V_{12})\varepsilon$$

$$V - \lambda_1 \underline{1} = \begin{pmatrix} (V_1 - V_{12})(\frac{1}{2} - \varepsilon)V_{12} + V_{12} \\ V_{12} \\ -V_{12} - (V_1 - V_{12})(\frac{1}{2} + \varepsilon)V_{12} \end{pmatrix}$$

$$= (\lambda_1 - \lambda_2) V_{12} \begin{pmatrix} -1 + \epsilon + o(\epsilon^2) \\ 1 - \epsilon + o(\epsilon^2) \end{pmatrix}$$

$$(\lambda - \lambda_1) q_1 = 0$$

If  $\epsilon = 0$   $(\lambda - \lambda_1) = V_{12} \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix}$

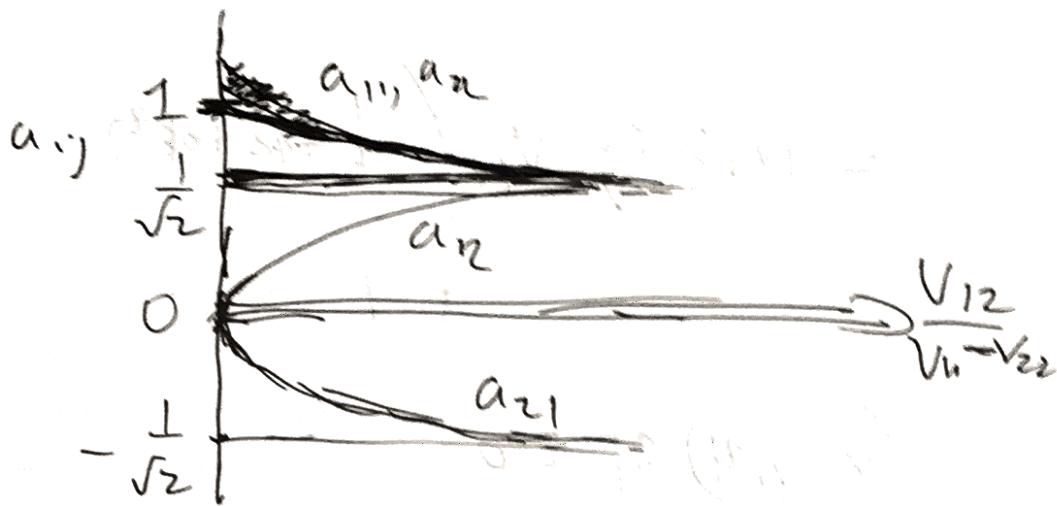
$$q_1 \rightarrow \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Now  $\begin{pmatrix} 1 + \epsilon + o(\epsilon^2) \\ 1 - \epsilon + o(\epsilon^2) \end{pmatrix}$

With Similarly  $q_2 \rightarrow \begin{pmatrix} -(1-\epsilon) \\ (1+\epsilon) \end{pmatrix}$

With normalization

$$\underline{A} = \begin{bmatrix} \frac{1}{\sqrt{2}}(1+\epsilon) & \frac{1}{\sqrt{2}}(1-\epsilon) \\ \frac{1}{\sqrt{2}}(1-\epsilon) & \frac{1}{\sqrt{2}}(1+\epsilon) \end{bmatrix}$$



Before we move on, let us consider the case of degenerate roots.

Let  $\lambda_K = \lambda_e$  and  $\tilde{a}_K'$  and  $a_e'$  are the corresponding eigenvectors.

Let's say  $\tilde{a}_K' T a_K' \neq 0$ . Consider

$$\textcircled{1} \quad a_e = c_1 a_K + c_2 a_e'$$

$$\tilde{a}_K' T a_K' = c_1 \tilde{a}_K' T a_K + c_2 \tilde{a}_e' T a_K'$$

$$\text{Say, } \tilde{a}_K' T a_K = 1$$

$$\text{choose } \frac{c_1}{c_2} = -\tilde{a}_e' T a_K = -q$$

$$\rightarrow \tilde{a}_e' T a_e' = 0$$

Like Gram-schmidt or orthogonalization.

For higher multiplicity  $a_1 = \text{com} \{ a_1, a_1' \}$ ,  
 $a_2 = \text{com} \{ a_1, a_2' \}$

Example:  $\begin{bmatrix} v_{11} & v_{12} \\ v_{12} & v_{22} \end{bmatrix}$   $T = \begin{pmatrix} m \\ m \end{pmatrix}$

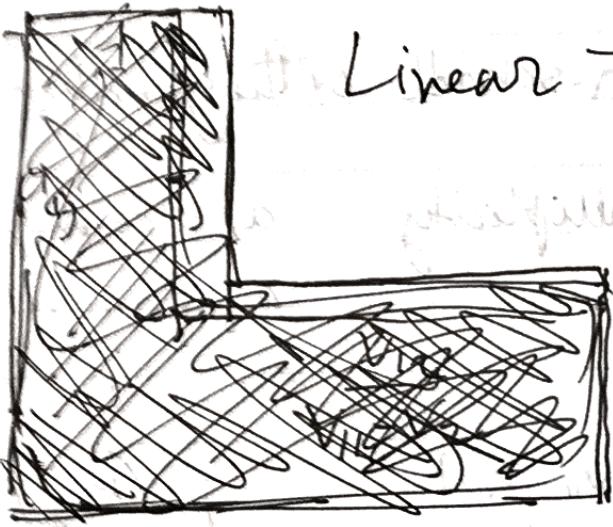
If  ~~$\begin{bmatrix} v_{11} & 0 \\ 0 & v_{11} \end{bmatrix}$~~  has a double root  $\lambda_{1,2} = v_{11}$

If  $v_{12} \rightarrow 0$  first and then  $v_{11} \rightarrow v_{22}$   
we get  $\begin{pmatrix} 1 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

If  $v_{11} \rightarrow v_{22}$  first  $v_{12} \rightarrow 0$  later

$$\frac{1(1)}{\sqrt{2}(1)}, \frac{1(-1)}{\sqrt{2}(1)}$$

Arbitrarily no choice.



Linear triatomic Molecule



$$\eta_{i+1} - \eta_i = x_{i+1} - x_i - b$$

$$T = \frac{m}{2} (\dot{\eta}_1^2 + \dot{\eta}_3^2) + \frac{M}{2} \dot{\eta}_2^2$$

$$\underline{T} = \begin{pmatrix} m & & \\ & m & \\ & & m \end{pmatrix}$$

$$V = \frac{k}{2} (\eta_1^2 + 2\eta_2^2 + \eta_3^2 - 2\eta_1\eta_2 - 2\eta_2\eta_3)$$

$$\underline{V} = \begin{pmatrix} k & -k & 0 \\ -k & 2k & -k \\ 0 & -k & k \end{pmatrix}$$

Try soln with symm  $\underline{V}\underline{a} = \omega^2 \underline{I} \underline{a}$

Blind way forward:

$$\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

$$|V - \omega^2 T| = \begin{vmatrix} k - \omega^2 m & -k & \\ -k & 2k - \omega^2 M & -k \\ & -k & k - \omega^2 m \end{vmatrix}$$

$$= (k - \omega^2 m) \begin{vmatrix} 2k - \omega^2 M & -k \\ -k & k - \omega^2 m \end{vmatrix}$$

$$+ k \begin{vmatrix} -k & -k \\ 0 & k - \omega^2 m \end{vmatrix}$$

$$= (k - \omega^2 m) [(2k - \omega^2 M)(k - \omega^2 m) - k^2]$$

$$- k^2 (k - \omega^2 m)$$

$$= (k - \omega^2 m) [(2k - \omega^2 M)(k - \omega^2 m) - 2k^2]$$

$$= (k - \omega^2 m) \left[ \frac{\omega^4 m M}{\omega^2 (k - \omega^2 m)} - \omega (m + M) k \right]$$

$$= [k(m + 2m) - \omega^2 M m]$$

So  $\omega^2 (k - \omega^2 m) [k(m + 2m) - \omega^2 M m] = 0$

$$\omega = 0, \frac{k}{m}, \frac{k(m + 2m)}{Mm}$$

First mode with  $\omega = 0$

$\Rightarrow S = 0$  That is just rigid translation

of the System: C. M. moving  
with relative positions fixed.

$$\begin{pmatrix} (k - \omega^2 m) & -k & \\ -k & 2k - \omega^2 M & -k \\ & -k & k - \omega^2 m \end{pmatrix} \begin{pmatrix} a_{11} \\ a_{21} \\ a_{31} \end{pmatrix} = 0$$

$$\omega_1 = 0 \text{ allows } a_{11} = a_{21} = a_{31}$$

[as a solution]

$$\text{With } \hat{a}^T a = 1 \quad m(a_{11}^2 + a_{31}^2) + Ma_2^2$$

$$\begin{pmatrix} a_{11} \\ a_{21} \\ a_{31} \end{pmatrix} = \frac{1}{\sqrt{m+M}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\omega_2 = \frac{k}{m} \Rightarrow \begin{pmatrix} 0 & -k & 0 \\ -k & 2k - \frac{\omega^2 M}{m} & -k \\ 0 & -k + \omega^2 & 0 \end{pmatrix} \begin{pmatrix} a_{12} \\ a_{22} \\ a_{32} \end{pmatrix} = 0$$

$$a_{12} = 0 \quad a_{12} = -a_{32}$$

$$\begin{pmatrix} a_{12} \\ a_{22} \\ a_{32} \end{pmatrix} = \frac{1}{\sqrt{m}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

The center atom is at rest and the two others are going in opposite directions.

$$\omega_3^2 = k \left( \frac{M+2m}{mM} \right)$$

$$\begin{pmatrix} -k\frac{2m}{M} & -k & \\ -k & -k\frac{M}{m} & k \\ -k & -k\frac{2m}{M} & \end{pmatrix}$$

Seems  $a_{13} : a_{23} : a_{33}$

$$= 1 : \pm \frac{2m}{M} : 1$$

will work. Normalizing

$$\begin{pmatrix} a_{13} \\ a_{23} \\ a_{33} \end{pmatrix} = \frac{1}{\sqrt{2m(1 + \frac{2m}{M})}} \begin{pmatrix} 1 \\ \pm \frac{2m}{M} \\ 1 \end{pmatrix}$$

The three modes are

$\sigma \rightarrow \sigma \rightarrow \sigma$  stretching

$\sigma \rightarrow \sigma \leftarrow \sigma$  bending

$$\begin{pmatrix} \eta_1 \\ \eta_2 \\ \eta_3 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2m+M}} & \frac{1}{\sqrt{2m}} & \frac{1}{\sqrt{2m(1+\frac{m}{M})}} \\ \frac{1}{\sqrt{2m+M}} & 0 & \frac{1}{\sqrt{2m(\frac{M}{m}+1)}} \\ \frac{1}{\sqrt{2m+M}} & -\frac{1}{\sqrt{2m}} & \frac{1}{\sqrt{2m(1+\frac{m}{M})}} \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{pmatrix}$$

$$\xi_1 = \frac{m(\eta_1 + \eta_3) + M\eta_2}{\sqrt{2m+M}}$$

$$\xi_2 = \sqrt{\frac{m}{2}} (\eta_1 - \eta_3)$$

$$\xi_3 = \sqrt{\frac{m}{1+2m/M}} (\eta_1 + \eta_3 - 2\eta_2)$$

## Forced vibrations and effect of dissipation

$$T\ddot{\eta} + V\dot{\eta} = F \quad \text{external force}$$

$$T\ddot{\eta} + V\dot{\eta} = F$$

$$TA\ddot{\xi} + VA\dot{\xi} = F$$

$$\text{multiply by } \hat{A}^{-1} \quad \hat{A}F = Q$$

$$\hat{A}TA\ddot{\xi} + \hat{A}VA\dot{\xi} = \hat{Q}$$

$$\ddot{\xi} + \Delta\xi = \underline{Q}$$

Component by component

$$\xi_i + \lambda_i \xi_i = \underline{Q}_i$$

$$\text{or } \xi_i + \omega_i^2 \xi_i = \underline{Q}_i$$

$$\text{Let } Q_i(t) = Q_{0i} \cos(\omega t + \delta_i)$$

Try

$$S_i = B_i \cos(\omega t + \delta_i)$$

Response  
function ( $\eta_j$ )

$$B_i = \frac{Q_{oi}}{\omega_i^2 - \omega^2}$$

$$\eta_j = a_{ji} S_i = \frac{a_{ji} Q_{oi} \cos(\omega t + \delta_i)}{\omega_i^2 - \omega^2}$$

- 1) First  $Q_{oi} \neq 0$
- 2) Also  $\omega \rightarrow \omega_i$  produces large response (Resonance!)
- 3) Phase change as  $\omega$  crosses  $\omega_i$ .

Push slowly and the particle moves with force

Jiggle fast and acceleration matches force

## Effect of dissipation

If we have  $\ddot{s}_j + F_j \dot{s}_j + \omega_j^2 s_j = 0$   
 drag coeff.

$$s_j = g e^{-i\omega_j t}$$

$$\omega_j'^2 + i\omega_j F_j - \omega_j^2 = 0$$

$$\omega_j' = \pm \sqrt{\omega_j^2 - \frac{F_j^2}{4} - iF_j}$$

damping rate

$$s_j C.e^{-2\omega_j' t} = g e^{i\sqrt{\omega_j^2 - F_j^2/4}t - F_j t/2} \\ = g e^{i\pi/2 - i\omega_j' t - \eta t}$$

$$\text{In general } \eta_j = \omega_j e^{-i\omega_j t}$$

General Rayleigh dissipation function  $\mathcal{F} = \frac{1}{2} \sum_i \gamma_i \dot{\eta}_i \eta_i$

$$\sum_k \alpha_k \dot{\eta}_k - i\omega \sum_k \tilde{F}_k \eta_k - \omega^2 \sum_k \beta_k \eta_k = 0$$

$$(\underbrace{\sum_k \gamma_k \eta_k}_{\gamma} + i\omega \sum_k \tilde{F}_k \eta_k - \omega^2 \sum_k \beta_k \eta_k) = 0$$

$$\gamma = -i\omega = -\omega - 2\pi i\Delta$$

Note that in  $\delta$ ,  
 in a soln  $\delta^*$ ,  
 a solution too

Also note that  $\alpha^2 \tau a + \gamma^2 F_0 + \gamma^2 \alpha^2 m = 0$   
 is a real quadratic equation. If  $\gamma$  is complex  
 $\gamma R(\gamma) = \gamma + \gamma^* = -\frac{\alpha^2 F_0}{\alpha^2 m} < 0 \Rightarrow K \neq 0$

For forced motion

$$V_k \eta_k + F_{jk} \dot{\eta}_k + \underline{f}_{jk} \ddot{\eta}_k = F_0 e^{-i\omega t}$$

$$\eta = A_j e^{-i\omega t} = F_0$$

$$(V - i\omega F - \omega^2 I) A = F_0$$

$$A = (V - i\omega F - \omega^2 I)^{-1} F_0$$

$$A_j = \frac{D_j(\omega)}{D(\omega)}$$

Using Cramer's rule

Ask when  $D(\omega)$  gets small (resonance)

$$D(\omega) = 6 \prod_j (\omega - \omega_j)(\omega + \omega_j^*)$$

Using  $\omega_j = 2\pi f_j - i\zeta_j$  and  $\omega = \omega_0$

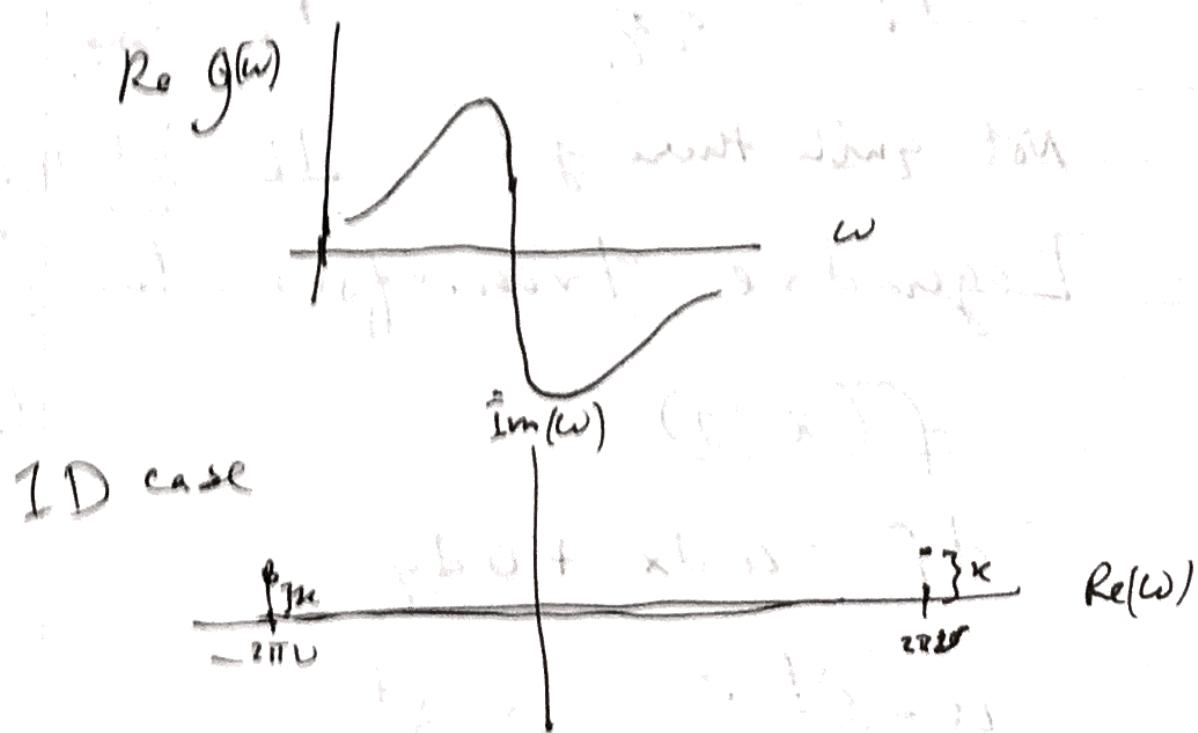
$$D(\omega) D(\omega)^* = \prod_j (4\pi^2 (2\omega_j)^2 + \zeta_j^2) (4\pi^2 (\omega_0 - \omega_j)^2 + \zeta_j^2)$$

So as  $v$  passes  $\omega_j$ , and as long as  $\omega_j \ll |\nu_j - v_j|$ , we will see a resonant peak.

### One variable $\square$ case

$$(\omega_0^2 - i\omega F - \omega^2) A = F_0$$

$$A = \frac{1}{\omega_0^2 - \omega^2 - i\omega F} F_0 = g(\omega) F_0$$



General

