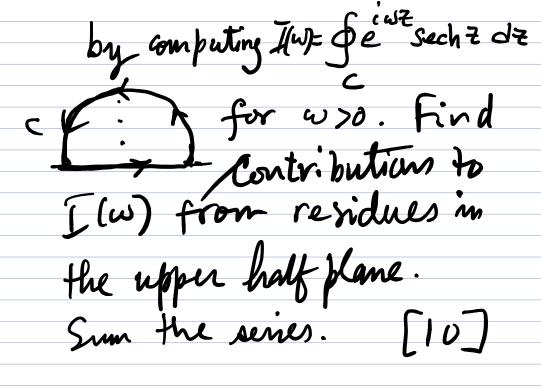
Mathematical Physics 464/511 Final Exam, Dec 2019 [Istal 100]

- 1. Consider the analytic function f defined on $R = \frac{1}{2} \in \mathbb{Z} \left[\cosh \frac{\pi}{4} \right]^2$ Via $f(z) = \operatorname{Sech} z = \frac{1}{\cosh z} = \frac{2}{e^2 + e^{-2}}$ for $z \in \mathbb{R}$.
 - a) Find the singularities of f in and comment on them.
 - b) Consider f defined by $g(z) = 11 \sum_{n=0}^{\infty} \frac{(-1)^n (2n+1)}{z^2 + (n+\frac{1}{2})^2 \pi^2}$

Show that I and g have the same singularities. [10]

C) Let us evaluate $\hat{f}(\omega) = \int_{-\infty}^{\infty} e^{i\omega t} secht dt$ $\omega \in \mathbb{R}$



2. We have seen the geodoic equation derived from minimizing

S[x] = S gi(x) di di' di (Summittion)

So[x] = S gi(x) di di' di (Convention)

in use!

but we needed to deal with reparametrization invariance by fixing $g(x) \frac{dx}{dx} \frac{dx}{dx} = constant$.

Alternatively, ne would derive
the geodesic equation from
minimizing $S[x] = \frac{1}{2} \int_{3}^{3} (x) dx dx^{2} dx$

giving rise to
$$\frac{d}{d}\left(g, \frac{dx^2}{dx}\right) - \frac{1}{2} \frac{\partial g_{x1}}{\partial x^2} \frac{dx^2}{\partial x^2} \frac{dx}{dx} = 0$$

$$\frac{d}{dx}\left(g, \frac{dx^2}{dx}\right) - \frac{1}{2} \frac{\partial g_{x1}}{\partial x^2} \frac{dx^2}{dx} \frac{dx}{dx} = 0$$

as the Enler-Lagrange equations.

a) Consider the halfspace

$$H = \{(x', x') \in \mathbb{R}^2 | x' > 0 \}$$

The metric tensor is
$$g(x) = \begin{pmatrix} g_{11}(x) & g_{12}(x) \\ g_{12}(x) & g_{22}(x) \end{pmatrix} = \begin{pmatrix} \frac{1}{(\lambda^2)^2} & 0 \\ 0 & (\frac{1}{(\lambda^2)^2}) \end{pmatrix}$$

Write down the geodesic equations.

$$S_{1}[x] = \frac{1}{2}\left[\frac{1}{2}\left(\frac{2x}{2x}\right)^{2}\left(\frac{2x}{2x}\right)^{2}\left(\frac{2x}{2x}\right)^{2}\right]dx$$

how symmetries $2' \rightarrow 2' + a$ and $\lambda \rightarrow \lambda + c$, giving us conservation laws

3.a) Solve the differential equation
$$\frac{d}{dt} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} -1 \\ 0 - 1 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix}, t \in [0, \infty)$$

$$\frac{d}{dt} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 - 1 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} u_{t}(t) \\ u_{t}(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0$$

with initial condition
$$\binom{h(0)}{n_2(0)} = \binom{0}{1}$$

b) What in the maximum value
of U,4) for
$$\pm \in [0,\infty)$$
?

4. The diffusion equation for the time-dependent density of partides f(x,y,z,t) in given by $\frac{\partial f}{\partial t} = D \left(\frac{\partial}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) f.$

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The boundary undition
on the walls of the box.
5/ 100 000000000000000000000000000000000
With such boundary Conditions, the Hotal number of particles
Conditions, the
total number
of particles can change.
can vising.
a) We start with No particles
t=0.
P(x,y,z,0)=A Sin [x Sin [y Sin []z
Ruate A to No, using No SP(x,na,0) dxdyda.
solve for goery, 2,t). Remember
that D is a constant (the diffusion constant).

b) The time-dependent number

of particles in the box $N(t) = \int_{0}^{t} dx \int_{0}^{t} dx \int_{0}^{t} R^{[k,\eta,2,1)}$ keeps decreasing with time t. At what t does N(1) become No /2 .