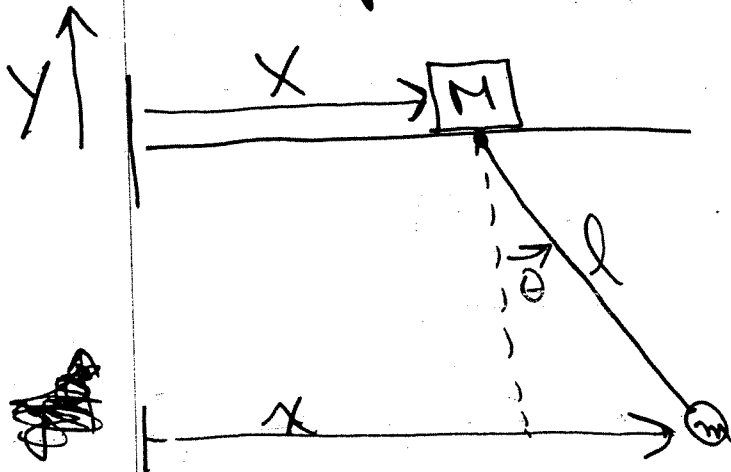


(A1)

1/05

A mass  $M$  is free to slide on a frictionless air track; suspended by a pivot and a light rod of length  $l$  is another mass  $m$ .



- (a) Construct the Lagrangian for this system and derive the equations of motion.
- (b) Determine the angular frequency when the system undergoes small oscillations.

Soln

(a) Constraints are:  $Y=0$   
 $[(x-X)^2 + y^2]^{1/2}$

Choose generalized co-ordinates:  $\theta$  and  $X$

The location of  $m$  is:  $x = X + l \sin \theta$   
 $y = -l \cos \theta$

$$K.E. = \frac{1}{2} M \dot{X}^2 + \frac{1}{2} m [(\dot{X}^2 + l^2 \dot{\theta}^2 \cos^2 \theta) + (l \dot{\theta} \sin \theta)^2]$$
$$U = -mg l \cos \theta, \text{ taking zero at } z$$

$$\text{Thus, } \mathcal{L} = K.E. - U = \frac{1}{2} M \dot{X}^2 + \frac{1}{2} m [(\dot{X}^2 + l^2 \dot{\theta}^2 \cos^2 \theta) + (l \dot{\theta} \sin \theta)^2] + mg l \cos \theta$$

A1 cont

$$\text{Now, } \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) = \frac{\partial L}{\partial q}$$

With  $q = x$ , we get

$$\textcircled{1} \quad \frac{d}{dt} [M\dot{x} + m(\dot{x} + l\dot{\theta} \cos \theta)] = 0$$

With  $q = \theta$ , we get

$$\textcircled{2} \quad \frac{d}{dt} (ml^2 \dot{\theta} + ml\dot{x} \cos \theta) = -mgl \sin \theta - ml\dot{x} \dot{\theta}$$

$\textcircled{b}$  Using  $\textcircled{1}$ , since  $\dot{x}$  and  $\dot{\theta}$  are zero initially (we release  $m$  from rest)

$$\dot{x} = -\frac{ml\dot{\theta} \cos \theta}{m+M}$$

Now, eliminate  $\dot{x}$  in  $\textcircled{2}$ , and we get:

$$\frac{d}{dt} \left( \dot{\theta} - \frac{m}{m+M} \dot{\theta} \cos^2 \theta \right) = -\frac{g}{l} \sin \theta + \frac{m}{m+M} \dot{\theta}^2 \sin \theta \cos \theta$$

For small oscillation,  $\sin \theta \sim \theta$ ,  $\cos \theta \sim 1$  and the second term on right is  $\approx 0$ .

$$\text{Thus, } \frac{d\dot{\theta}}{dt} = -\frac{g}{l} \frac{m+M}{M} \theta$$

$$\text{and } \omega = \sqrt{\frac{g}{l} \frac{m+M}{M}}$$

which approaches  $(g/l)^{1/2}$  as  $M$  increases (as it should, since it becomes a simple pendulum).

(A2)

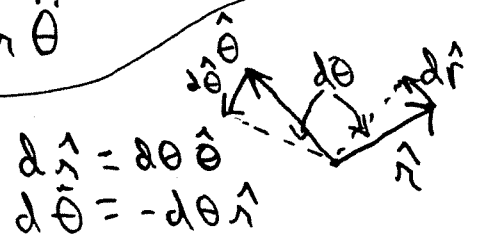
2 pts

3 a Show that for a particle moving in a plane, the components of acceleration are given by:

$$a_r = \ddot{r} - r\dot{\theta}^2$$

and

$$a_\theta = 2\dot{r}\dot{\theta} + r\ddot{\theta}$$



soln a

$$\text{Since } \vec{r} = r \hat{r},$$

$$\vec{v} = \frac{d\vec{r}}{dt} = \dot{r} \hat{r} + r \frac{d\hat{r}}{dt} = \dot{r} \hat{r} + r \dot{\theta} \hat{\theta}$$

$$\begin{aligned} \vec{a} &= \ddot{r} \hat{r} + \dot{r} \frac{d\hat{r}}{dt} + \dot{r} \dot{\theta} \hat{\theta} + r \ddot{\theta} \hat{\theta} + r \dot{\theta} \frac{d\hat{\theta}}{dt} \\ &= (\ddot{r} - r\dot{\theta}^2) \hat{r} + (2\dot{r}\dot{\theta} + r\ddot{\theta}) \hat{\theta} \end{aligned}$$

b Using this, show that for  $\vec{F} = \vec{F}(r)$ ,  $r^2 \dot{\theta} = \text{constant} = h$ .

2 pts  
soln b

$$\frac{F_\theta}{m} = 0 = 2\dot{r}\dot{\theta} + r\ddot{\theta}$$

$$\text{But } \frac{d}{dt}(r^2 \dot{\theta}) = 2r\dot{r}\dot{\theta} + r^2 \ddot{\theta}$$

$$\text{This is } \frac{F_\theta}{m} r \rightarrow 0$$

Thus  $r^2 \dot{\theta} = \text{constant} = h$ , if  $F_\theta = 0$

6 pts

c If  $f(r) = -c r^n$ , show that circular orbits are stable against small perturbations if  $n > -3$ .

$$\text{soln c } f(r) = m\ddot{r} - m r \dot{\theta}^2 = m\ddot{r} - \frac{m h^2}{r^3}$$

For a circular orbit,  $r = a$ , and  $f(a) = -\frac{m h^2}{a^3}$

A2 cont

$$\text{Let } x = r - a.$$

$$\text{Then, } m \ddot{x} - m h^2 (x+a)^{-3} = f(x+a)$$

Expand in a power series:

$$m \ddot{x} - m h^2 a^{-3} \left(1 - 3 \frac{x}{a} + \dots\right) = f(a) + f'(a)x$$

$$\therefore m \ddot{x} + \left[-\frac{3}{a} f(a) - f'(a)\right] x = 0$$

If  $[ ]$  is positive, we have SHM.

$$\text{for } T \text{ linear, for stability, } \frac{3}{a} f(a) + f'(a) < 0$$

$$\text{If } f(r) = -c r^n,$$

$$\text{then } -\frac{3}{a} c a^n - c n a^{n-1} < 0$$

$$\text{or } 3c + cn > 0,$$

$$\text{so } n > -3$$

A3

RAB 1: Jan 05

pg 1 of 2

$$a) \vec{F} = m \dot{\vec{x}} \Rightarrow m \ddot{\vec{x}} = -\frac{e}{c} (\dot{\vec{x}} \times \vec{B}) - e \vec{E} \quad (1)$$

so with  $\vec{B} = B_0 \hat{z}$  we have  $(\dot{\vec{x}} \times \vec{B}) = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \dot{x} & \dot{y} & 0 \\ 0 & 0 & B_z \end{vmatrix}$

Let  $\vec{x} = x \hat{x} + y \hat{y}$

$\Rightarrow$

$$m \ddot{x} + \frac{e B_z}{c} \dot{y} + e E_{0x} = 0$$

$$m \ddot{y} - \frac{e B_z}{c} \dot{x} + e E_{0y} = 0$$

$$= B_z \dot{y} \hat{x} - B_z \dot{x} \hat{y}$$

(b) Let  $\vec{x} = x^\pm (\hat{x} \pm i \hat{y}) \Rightarrow \dot{\vec{x}} = \dot{x}^\pm (\hat{x} \pm i \hat{y})$

$$\ddot{\vec{x}} = \ddot{x}^\pm (\hat{x} \pm i \hat{y})$$

$$\Rightarrow (\dot{\vec{x}} \times \vec{B}) = \dot{x}^\pm \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 1 & \pm i & 0 \\ 0 & 0 & B_z \end{vmatrix} = \dot{x}^\pm B_z (\pm i \hat{x} - \hat{y})$$

$$= \pm i \dot{x}^\pm B_z (\hat{x} \pm i \hat{y})$$

so, with  $\vec{E} = E_0 (\hat{x} \pm i \hat{y}) e^{-i\omega t}$  (i.e.  $e \sim 1$ )

$$m \ddot{x}^\pm (\hat{x} \pm i \hat{y}) + \frac{e B_z}{c} \dot{x}^\pm (\hat{x} \pm i \hat{y}) + e E_0 (\hat{x} \pm i \hat{y}) e^{-i\omega t} = 0$$

To solve, let  $x^\pm = x_0^\pm e^{-i\omega t} \Rightarrow \dot{x}^\pm = -i\omega x^\pm, \ddot{x}^\pm = -\omega^2 x^\pm$

$$\Rightarrow -\omega^2 m x_0^\pm \pm i \frac{e B_z}{c} (-i\omega) x_0^\pm + e E_0 = 0 \Rightarrow -m\omega^2 x_0^\pm \pm \frac{e B_z}{c} x_0^\pm = -$$

$$x_0^\pm = \frac{e E_0}{m(\omega \mp e B_z/c)}$$

(C)  $P$  = electric dipole moment / volume

$$\Rightarrow P^{\pm} = -ne\chi^{\pm} \quad \text{where } n = \text{electron density}$$

$-e = \text{electron charge}$

$$\Rightarrow P^{\pm} = \frac{-ne^2 E_0}{\omega(\omega \mp \frac{eB_z}{mc})}$$

Now,  $\vec{D} = E + 4\pi P$ , we have  $P \propto E \Rightarrow P = \chi E$

$$\text{So } (D = E + 4\pi\chi E = (1 + 4\pi\chi)E = \epsilon E$$

$$\Rightarrow \epsilon^{\pm} = 1 - \frac{4\pi ne^2/m}{\omega(\omega \mp \frac{eB_z}{mc})}$$

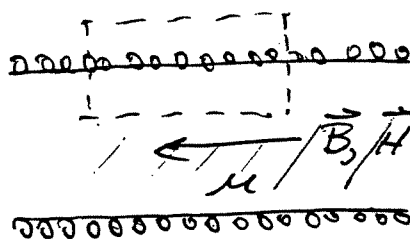
- For low frequencies  $\omega^+ > 0$ ,  $\epsilon^- < 0 \Rightarrow E^+$  propagates in medium while  $E^-$  decays + is evanescent  $\Rightarrow E^-$  component of incident wave is perfectly reflected.
- For high frequencies,  $\epsilon^+ > 0$ ,  $\epsilon^- > 0 \Rightarrow$  both modes propagate.

A4

Pg 1 of 2

RAB2: Jan 05

a) Using Ampere's Law with a loop as shown in the diagram:



$$\int \vec{H} \cdot d\vec{l} = I \Rightarrow$$

$$Hl = lnI. \text{ where } n = \# \text{ turns / length.}$$

$$\text{So } \boxed{H = nI.}$$

$$\text{In medium, } B = \mu H \Rightarrow \boxed{B = \mu n I_0}$$

b) To find fields in gap, use continuity relations:

$B_{\text{norm}}$  continuous,  $H_{\text{tan}}$  continuous } at interface

$$\text{Since } B \perp \text{ surface } \Rightarrow B_{\text{gap}} = B_{\text{in}} = \boxed{\mu n I_0 = B_{\text{gap}}}$$

moreover, in vacuum  $B = \mu_0 H$

$$\Rightarrow \boxed{H_{\text{gap}} = \frac{B_{\text{gap}}}{\mu_0} = \frac{\mu}{\mu_0} n I_0}$$

$$\text{c) Energy density} = \frac{1}{2} \vec{B} \cdot \vec{H}$$

$$\Rightarrow \text{in gap } u = \frac{1}{2} (\mu n I_0) \cdot \left( \frac{\mu}{\mu_0} n I_0 \right) = \frac{\mu}{\mu_0} \left( \frac{1}{2} \mu n^2 I_0^2 \right)$$

$$\text{in material } u_{\text{in}} = \frac{1}{2} (\mu n I_0) (n I_0) = \frac{1}{2} \mu n^2 I_0^2$$

$$\Rightarrow \boxed{\mu > \mu_0}$$

A4 cont

RAB2: Janos (2 of 2)

d) Since  $U_{\text{gap}} > U_{\text{in}}$ , requires work done by external agent to increase size of gap.

$$\begin{aligned} \Delta E &= (U - U_{\text{gap material}}) \cdot A \cdot \Delta x \\ &= \left(\frac{\mu}{\mu_0} - 1\right) \left(\frac{1}{2} \mu n^2 I_0^2\right) \pi R^2 \Delta x \end{aligned}$$

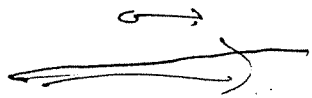
$$\text{Force} = \frac{\Delta E}{\Delta x} = \left(\frac{\mu}{\mu_0} - 1\right) \left(\frac{1}{2} \mu n^2 I_0^2\right) \pi R^2$$

Tensile force applied by external agent.

(note, independent of  $w$  if fringe fields neglected)

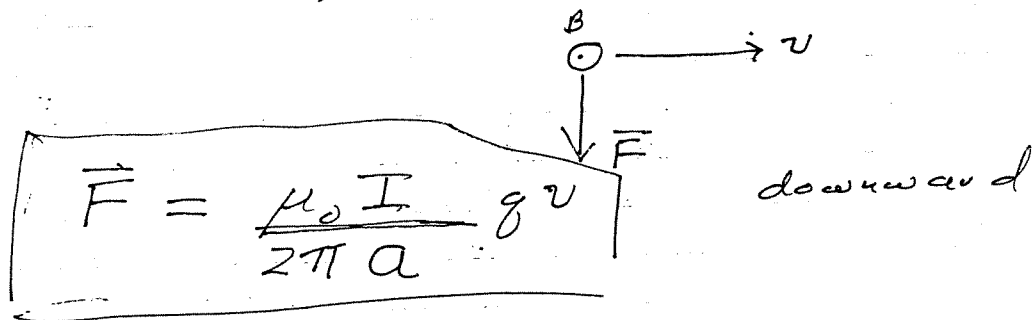


A5



(a)  $B = \frac{\mu_0 I}{2\pi R}$  out of ampere's law

$$\vec{F} = q\vec{E} + \gamma \vec{v} \times \vec{B}$$



(b) In this frame  $\vec{v}' = 0$

$$\vec{F} = \gamma \vec{E}'$$

must be an electric field,

so a charge

$(\rho c, \vec{j})$  is a 4-vector

$$\text{so } A(\rho c, \vec{j}) = [\lambda c, I]$$

$\lambda = \text{charge/area}$

In the original frame  $\lambda = 0$

a usual Lorentz transform

$$\lambda' c = -\gamma \beta I$$

$$\lambda' = -\gamma \frac{v}{c^2} I$$

cr.  $\frac{1}{\mu_0}$

$$E' = \frac{1}{2\pi R \epsilon_0} \frac{\lambda'}{R} = \frac{\gamma v}{2\pi \epsilon_0 c^2} \frac{I}{R}$$

$$= \gamma \frac{\mu_0 v I}{R}$$

$$\vec{F}' = \gamma \vec{F}$$

This could also be obtained by field trans. (Jackson)  $E'_{\perp} = \gamma \vec{v} \times \vec{B}$  or force transformation: see French pg 4.

## A5 cont

(c) If the wire is neutral by carries a current in the original frame it will carry a negative charge in the rest frame of  $\gamma$ . This produces a electric field pointing toward the wire  $\circ$  thus an inward force on  $q$ .  $\vec{F}' = \gamma \vec{F}$  so non-rel. the force on  $q$  is the same.

( By field transformation the pure magnetic field in the original frame become a mix of magnetic field and electric field in the 2nd frame )