

Lecture 6

[Stochastic differential equations] (SDE)

Recall that $\frac{dx}{dt} = a(x, t) + b(x, t) \xi(t)$

is better interpreted as

$$x(t) - x(t_0) = \int_{t_0}^t dt' a[x(t'), t'] + \int_{t_0}^t dW(t') b[x(t'), t'].$$

The corresponding Itô SDE is written as:

$$dx(t) = a[x(t), t]dt + b[x(t), t]dW(t).$$

Using a discretized mesh of time points
 $t_0 < t_1 < t_2 < \dots < t$, [n subintervals]

we can write

$$x_{i+1} = x_i + a(x_i, t_i) \underbrace{\Delta t_i}_{t_{i+1} - t_i} + b(x_i, t_i) \underbrace{\Delta W_i}_{W(t_{i+1}) - W(t_i)}.$$

Note that ΔW_i is an independently sampled increment of the Wiener process.

This is the Cauchy-Euler method for solving SDEs numerically.

One can show that, given a sample function $\tilde{W}(t)$ of the Wiener process $W(t)$, there is a unique solution to the Itô SDE under fairly mild conditions on $a(x, t)$ & $b(x, t)$.

Numerical solutions converge to this unique solution as $n \uparrow$.

Note that $x(t)$ [SDE solution] is a Markov process. Indeed, $x(t)$ for $t > t_0$ depends only on: (i) $x(t_0)$; (ii) the particular sample path $w(t)$ for $t > t_0$, which is independent of $x(t)$ for $t < t_0$. Thus, $x(t)$ is a Markov process.

Change of variables (Itô's formula)

Consider $f[x(t)]$:
 $\uparrow$ arbitrary f 'n

$$\begin{aligned} df[x(t)] &= f[x(t) + dx(t)] - f[x(t)] = \\ &= f'[x(t)] dx(t) + \frac{1}{2} f''[x(t)] dx(t)^2 + \dots = \\ &= f'[x(t)] \{ a[x(t), t] dt + b[x(t), t] dw(t) \} + \\ &\quad + \frac{1}{2} f''[x(t)] b[x(t), t]^2 \underbrace{dw(t)^2}_{=dt} \quad \ominus \\ &\quad \ominus \left\{ a[x(t), t] f'[x(t)] + \frac{1}{2} b[x(t), t]^2 f''[x(t)] \right\} dt + \\ &\quad + b[x(t), t] f'[x(t)] dw(t). \end{aligned}$$

Itô's formula, 1D

Multi-D:

$$\begin{cases} dw_i(t) dw_j(t) = \delta_{ij} dt, \\ dw_i(t)^{N+2} = 0, \quad N > 0 \\ dw_i(t) \times dt = 0, \\ dt^{1+N} = 0, \quad N > 0 \end{cases}$$

Then, if $dx_i = A_i(\vec{x}, t) dt + \underbrace{B_{ij}(\vec{x}, t)}_{\substack{\text{matrix} \\ \text{sum over } j}} dw_j(t) :$

$$df(\vec{x}) = \left\{ A_i \partial_i f(\vec{x}) + \frac{1}{2} \underbrace{B_{ik} B_{jk}}_{[B(\vec{x}, t) B^T(\vec{x}, t)]_{ij}} \partial_i \partial_j f(\vec{x}) \right\} dt + B_{ij} \partial_i f(\vec{x}) dw_j(t).$$

Connection to FP equation:

Consider $\frac{d \langle f[x(t)] \rangle}{dt} = \frac{d}{dt} \langle f[x(t)] \rangle =$

$$= \langle a \partial_x f + \frac{b^2}{2} \partial_x^2 f \rangle.$$

$$\uparrow \langle b \partial_x f dw \rangle = 0$$

Now,

$$\frac{d}{dt} \langle f \rangle = \int dx f(x) \partial_t p(x, t | x_0, t_0) =$$

$$= \int dx \left[a \partial_x f + \frac{b^2}{2} \partial_x^2 f \right] p(x, t | x_0, t_0).$$

Integrate by parts:

$$\int dx f(x) \partial_t p = \int dx f(x) \left\{ -\partial_x [a p] + \frac{1}{2} \partial_x^2 [b^2 p] \right\}.$$

Since $f(x)$ is arbitrary,

$$\partial_t p = -\partial_x \underset{\substack{\uparrow \\ \text{drift} \\ \text{coeff.}}}{[a p]} + \frac{1}{2} \partial_x^2 \underset{\substack{\uparrow \\ \text{diff'n} \\ \text{coeff.}}}{[b^2 p]}.$$

Multi-D:

$$dx_i = A_i dt + B_{ij} dw_j \quad \text{leads to}$$

$$\partial_t p = -\partial_i [A_i p] + \frac{1}{2} \partial_i \partial_j \{ [B B^T]_{ij} p \}$$

Note that replacing B by BS s.t.
 $SS^T = \mathbb{I}$ (i.e., S is orthogonal) does not
 change the FP eq'n.

Now, consider

$$dV_i = S_{ij} dw_j.$$

$\underbrace{\quad}_{\text{na f'n, orthogonal}}$

$$\langle dV_i \rangle = 0$$

$$\text{Then } \langle dV_i dV_j \rangle = S_{il} S_{jm} \underbrace{\langle dw_l dw_m \rangle}_{S_{lm} dt} =$$

$$= \underbrace{S_{il} S_{jl}}_{\delta_{ij}} dt = \underline{\underline{\delta_{ij} dt}}.$$

Thus $V_i(t)$ is also a Wiener process,

and $dx_i = A_i dt + B_{ik} \underbrace{[S^T S]_{kj}}_{\delta_{kj}} dw_j \quad \textcircled{=}$

$\textcircled{=} A_i dt + B_{ik} S_{kj}^T \underbrace{dw_j}_{\text{wiener process}}$

or, equivalently,

$dx_i = A_i dt + B_{ik} S_{kj}^T dw_j.$

Orthogonal transformations simply mix up different sample paths of the stochastic process.

Stratonovich Stochastic Integral

$$(S) \int_{t_0}^t \underbrace{G[x(t'), t']}_{\text{obs an SDE}} dW(t') = \lim_{n \rightarrow \infty} \sum_{i=1}^n G\left[\frac{x(t_i) + x(t_{i-1})}{2}, t_{i-1}\right] \times [W(t_i) - W(t_{i-1})]$$

Stratonovich SDE

$$x(t) = x(t_0) + \int_{t_0}^t dt' \alpha[x(t'), t'] + (S) \int_{t_0}^t dW(t') \beta[x(t'), t']$$

Change of variables, Stratonovich SDE:

$$(S) df[x(t)] = f'[x(t)] \left\{ \alpha[x(t), t] dt + \underbrace{+ \beta[x(t), t] dW(t)}_{dx(t), \text{ as in regular calculus}} \right\} \quad (*)$$

Consider $dx(t) = \underbrace{B[x(t)]}_{\text{no explicit } t\text{-dep., for simplicity}} dW(t)$

In discretized form,

$$x_{i+1} = x_i + B\left[\frac{x_{i+1} + x_i}{2}\right] (W_{i+1} - W_i)$$

Recall that

$$f(x+a) = f(x-a) + 2 \sum_{n=0}^{\infty} \frac{f^{(2n+1)}(x) a^{2n+1}}{(2n+1)!} \approx$$

$$\approx f(x-a) + 2 f'(x) a.$$

Use $\begin{cases} x+a = x_{i+1}, \\ x-a = x_i \end{cases} \Rightarrow \begin{cases} x = \frac{x_{i+1} + x_i}{2}, \\ a = \frac{x_{i+1} - x_i}{2}. \end{cases}$

Then $f(x_{i+1}) = f(x_i) + f'\left(\frac{x_{i+1} + x_i}{2}\right) \times (x_{i+1} - x_i) =$
 $= f(x_i) + f'\left(\frac{x_{i+1} + x_i}{2}\right) B\left[\frac{x_{i+1} + x_i}{2}\right] (w_{i+1} - w_i).$

This leads to

$$(S) \quad df[x(t)] = f'[x(t)] \underbrace{B[x(t)] dw(t)}_{dx(t), \text{ as in ordinary calculus}}$$

generalization to Eq. (*) follows.

Equivalent Itô SDE:

Consider $dx(t) = \underbrace{a[x(t), t]}_{\text{Itô SDE}} dt + b[x(t), t] dw(t).$

$$(S) \quad \int_{t_0}^t dw(t') \beta[x(t'), t'] = \lim_{n \rightarrow \infty} \sum_{i=1}^n \beta\left[\frac{x(t_i) + x(t_{i-1})}{2}, t_{i-1}\right] \times \underbrace{\Delta w_{i-1}}_{\Delta w(t_{i-1})}$$

Writing $x(t_i) = x(t_{i-1}) + \overbrace{\Delta x(t_{i-1})}^{\approx \Delta x_{i-1}}$, we get
from Itô SDE:

$$\Delta x(t_{i-1}) = a[x(t_{i-1}), t_{i-1}] \overbrace{\Delta t_{i-1}}^{t_i - t_{i-1}} + b[x(t_{i-1}), t_{i-1}] \underbrace{\Delta W(t_{i-1})}_{W_i - W_{i-1} = \Delta W_{i-1}}.$$

Finally, $\beta\left[\frac{x_i + x_{i-1}}{2}, t_{i-1}\right] = \beta\left[x_{i-1} + \frac{\Delta x_{i-1}}{2}, t_{i-1}\right] =$

$$= \overbrace{\beta[x_{i-1}, t_{i-1}]}^{\approx \beta_{i-1}} + \left\{ a_{i-1} \partial_x \beta[x(t_{i-1}), t_{i-1}] + \frac{b_{i-1}^2}{4} \partial_x^2 \beta[x(t_{i-1}), t_{i-1}] \right\} \frac{\Delta t_{i-1}}{2} + \frac{b_{i-1}}{2} \partial_x \beta[x(t_{i-1}), t_{i-1}] \times \Delta W_{i-1}.$$

Recall that $df[x(t)] = f\left[x + \frac{dx}{2}\right] - f[x] =$

$$= f'[x] \frac{1}{2} \underbrace{\{a dt + b dW\}}_{\text{"}dx\text{"}} + \frac{f''[x]}{2!} \frac{1}{4} \underbrace{dx^2}_{\substack{\downarrow \\ b^2 dW^2 = b^2 dt}} =$$

$$= \left\{ f'[x] \frac{a}{2} + \frac{f''[x]}{2} \frac{b^2}{4} \right\} dt + f'[x] \frac{b}{2} dW.$$

↑ use the discrete version of this above

Now,

$$(S) \int_{t_0}^t dW(t') \beta[x(t'), t'] = \lim_{n \rightarrow \infty} \sum_i \beta_{i-1} \Delta W_{i-1} + \lim_{n \rightarrow \infty} \frac{1}{2} \sum_i b_{i-1} \partial_x \beta[x(t_{i-1}), t_{i-1}] \underbrace{\Delta t_{i-1}}_{\Delta W_{i-1}^2} \quad \textcircled{=}$$

$$\textcircled{=} \underbrace{\int_{t_0}^t dt' \beta[x(t'), t']}_{\text{Itô}} + \underbrace{\frac{1}{2} \int_{t_0}^t dt' b[x(t'), t'] \times \partial_x \beta[x(t'), t']}_{\text{regular } \int} =$$

If we choose

$$\begin{cases} \beta(x, t) = b(x, t), \\ \alpha(x, t) = a(x, t) - \frac{1}{2} b(x, t) \partial_x b(x, t), \end{cases}$$

we obtain:

$$\left[\begin{aligned} (S) \, dx(t) &= \underbrace{\alpha[x(t), t] dt + \beta[x(t), t] dW(t)}_{\text{Stratonovich SDE}} = \\ &= \left(a - \frac{b}{2} \partial_x b \right) dt + b dW(t) \quad \text{is the same as} \\ dx(t) &= \underbrace{a dt + b dW(t)}_{\text{Itô SDE}}. \end{aligned} \right]$$

Indeed, $x(t) = x(t_0) + \int_{t_0}^t dt' \alpha[x(t'), t'] +$ ↙ Stratonovich solution

$$\begin{aligned} &+ (S) \int_{t_0}^t dt' \beta[x(t'), t'] = \\ &= x(t_0) + \int_{t_0}^t dt' a - \frac{1}{2} \int_{t_0}^t dt' \cancel{b \partial_x b} + \int_{t_0}^t dt' b + \\ &\quad + \frac{1}{2} \int_{t_0}^t dt' \cancel{b \partial_x b} = x(t_0) + \int_{t_0}^t dt' a + \int_{t_0}^t dt' b \end{aligned}$$

↗ Itô solution

$x(t)$ is the same in both methods

Likewise, Stratonovich SDE

$$(\mathcal{S}) dx = \alpha dt + \beta dw$$

is equivalent to Itô SDE:

$$dx = \underbrace{\left(\alpha + \frac{1}{2} \beta \partial_x \beta \right)}_{\text{"a"}} dt + \underbrace{\beta}_{\text{"b"}} dw.$$

Multi-D

$$\begin{cases} A_i^S = A_i - \frac{1}{2} B_{kj} \underbrace{\partial_k}_{\text{" } \frac{\partial}{\partial x_k} \text{ "}} B_{ij}, \\ B_{ij}^S = B_{ij}. \end{cases} \quad \vec{x} = (x_1, x_2, \dots, x_n) \quad \begin{matrix} \uparrow \\ \text{\# DoF} \end{matrix}$$

$$\text{Itô: } dx_i = A_i(\vec{x}, t) dt + B_{ij}(\vec{x}, t) dw_j(t).$$

The corresponding FP eq'n is:

$$\partial_t p = - \partial_i [A_i p] + \frac{1}{2} \partial_i \partial_j \underbrace{\{ B_{ik} B_{jk} p \}}_{[BB^T]_{ij}} =$$

$$= - \partial_i \left\{ \left[A_i^S + \frac{1}{2} B_{kj}^S (\partial_k B_{ij}^S) \right] p \right\} +$$

$$+ \frac{1}{2} \partial_i \partial_j \underbrace{\{ B_{ik}^S B_{jk}^S p \}}_{\diamond} =$$

$$B_{ik}^S \times \partial_j (B_{jk}^S p) + (B_{jk}^S p) \times \partial_j B_{ik}^S \quad \begin{matrix} \leftarrow \leftrightarrow \rightarrow \\ k \leftrightarrow j \end{matrix}$$

$$= \dots + B_{kj}^S (\partial_k B_{ij}^S) p$$

$$\diamondsuit - \partial_i \{A_i^s p\} + \frac{1}{2} \partial_i \{B_{ik}^s \partial_j (B_{jk}^s p)\}.$$

"Stratonovich form" of
FP equation