## Physics 507 Homework \#6 Due: Thursday, Oct. 14, 2010

6.1 A diamond shaped object is shown in top, front, and side views. It is an octahedron, with 8 triangular flat faces.

It is made of solid aluminum of uniform density, with a total mass $M$. The dimensions, as shown, satisfy $h>b>a$.
(a) Find the moment of inertia tensor about the center of mass, clearly specifying the coordinate system chosen.
(b) About which lines can a stable spinning motion, with fixed $\vec{\omega}$, take place, assuming no external forces act on the body?

6.2 We defined the general rotation as $A=R_{z}(\psi) \cdot R_{y}(\theta) \cdot R_{z}(\phi)$. Work out the full expression for $A(\phi, \theta, \psi)$, and verify the last expression in (4.31). [For this and exercise 6.3, you might want to use a computer algebra program such as mathematica or maple, if one is available.]
6.3 Find the expression for $\vec{\omega}$ in terms of $\phi, \theta, \psi, \dot{\phi}, \dot{\theta}, \dot{\psi}$. [This can be done simply with computer algebra programs. If you want to do this by hand, you might find it easier to use the product form $A=R_{3} R_{2} R_{1}$, and the rather simpler expressions for $R \dot{R}^{T}$. You will still need to bring the result (for $R_{1} \dot{R}_{1}^{T}$, for example) through the other rotations, which is somewhat messy.]

