

HW #2 Solutions

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12.2 A Hall Thruster

- (a) We get uniform electron drift in the z -direction if the electric force density $-en_e\mathbf{E}$ exactly cancels the Lorentz magnetic force density $-en_e\mathbf{v}\times\mathbf{B}$. Imposing this condition, $\mathbf{E} = -\mathbf{v}\times\mathbf{B}$, implies that

$$\mathbf{E}\times\mathbf{B} = \mathbf{B}\times(\mathbf{v}\times\mathbf{B}) = \mathbf{v}B^2 - \mathbf{B}(\mathbf{B}\cdot\mathbf{v}).$$

This, in turn, implies the suggested result,

$$\mathbf{v} = \frac{\mathbf{E}\times\mathbf{B}}{B^2}.$$

- (b) Using the equality of the forces in part (a) and $n_i = n_e$, the electric force on the ions is

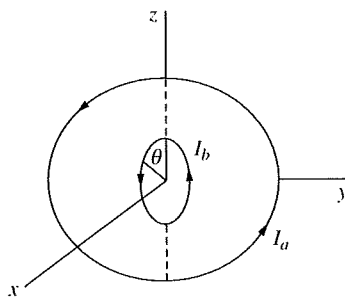
$$\mathbf{F}_i = en_i\mathbf{E} = en_e\mathbf{E} = -en_e\mathbf{v}\times\mathbf{B} = \mathbf{j}_{\text{Hall}}\times\mathbf{B}.$$

By Newton's third law, the reaction thrust on the shells is $\mathbf{T} = -\mathbf{F}_i = \mathbf{B}\times\mathbf{j}_{\text{Hall}}$ if the ions are ejected from V before the magnetic Lorentz force on the ions begins to act. This will be the case because a xenon ion is much more massive than an electron.



12.6 The Torque between Nested Current Rings

We locate the ring I_a in the x - y plane and the ring I_b in the x - z plane as shown below. The magnetic field on the axis of I_a points in the z -direction. The magnetic field of I_b points in the y -direction.



The vector torque which acts on I_b is

$$\mathbf{N} = I_b \oint \mathbf{r} \times (d\boldsymbol{\ell} \times \mathbf{B}),$$

where $\mathbf{r} = b \cos \theta \hat{\mathbf{z}} + b \sin \theta \hat{\boldsymbol{\theta}}$, $d\boldsymbol{\ell} = b d\theta \hat{\boldsymbol{\theta}} = b d\theta (\cos \theta \hat{\mathbf{x}} - \sin \theta \hat{\mathbf{z}})$, and $\mathbf{B} = B_\rho \hat{\boldsymbol{\rho}} + B_z \hat{\mathbf{z}}$ is the magnetic field due to I_a in cylindrical coordinates. Since parallel currents attract and anti-parallel currents repel, the only component of the torque which survives is N_x . Focusing on this component, substituting \mathbf{r} , $d\boldsymbol{\ell}$, and \mathbf{B} into the torque formula gives

$$N_x = I_b b^2 \int_0^{2\pi} d\theta \cos \theta (B_z \cos \theta + B_\rho \sin \theta).$$

Our task now is to write the components of $\mathbf{B}(\rho, z)$ near the origin, where $\rho = b \sin \theta$ and $z = b \cos \theta$. In the text, we used the technique of “going off the axis” to find the exact magnetic scalar potential of a current loop. In polar coordinates, the first two terms of this expansion for $r < a$ were

$$\psi(r, \theta) = -\frac{1}{2} \mu_0 I_a \left[\frac{r}{a} P_0(0) P_1(\cos \theta) + \left(\frac{r}{a}\right)^3 P_2(0) P_3(\cos \theta) \right].$$

Using $P_0 = 1$, $P_1 = \cos \theta$, $P_2 = (1/2)(3 \cos^2 \theta - 1)$, and $P_3 = (1/2)(5 \cos^3 \theta - 3 \cos \theta)$, together with $z = r \cos \theta$ and $\rho = r \sin \theta$, we get

$$\psi(\rho, z) = -\frac{1}{2} \mu_0 I_a \left[\frac{z}{a} - \frac{1}{2} \frac{z^3}{a^3} + \frac{3}{4} \frac{z \rho^2}{a^3} \right].$$

Therefore,

$$B_z = -\frac{\partial \psi}{\partial z} = \frac{\mu_0 I_a}{2a} \left[1 - \frac{3}{2} \frac{z^2}{a^2} + \frac{3}{4} \frac{\rho^2}{a^2} \right] = \frac{\mu_0 I_a}{2a} \left[1 - \frac{3}{2} \frac{b^2 \cos^2 \theta}{a^2} + \frac{3}{4} \frac{b^2 \sin^2 \theta}{a^2} \right]$$

and

$$B_\rho = -\frac{\partial \psi}{\partial \rho} = \frac{3\mu_0 I_a}{4} \frac{z \rho}{a^3} = \frac{3\mu_0 I_a}{4} \frac{b^2}{a^3} \sin \theta \cos \theta.$$

Substituting these fields into the torque formula and collecting terms gives the advertised result:

$$N_x = \frac{1}{2} \mu_0 I_a I_b \frac{b^2}{a} \int_0^{2\pi} d\theta \left[\cos^2 \theta \left(1 - \frac{3b^2}{2a^2} \right) + \frac{15b^2}{16a^2} \sin^2 2\theta \right] = \frac{\pi}{2} \mu_0 I_a I_b \frac{b^2}{a} \left[1 - \left(\frac{3b}{4a} \right)^2 \right].$$

12.19 Equivalence of Force Formulae

U_B must be expressed as a function of the flux variables. \hat{U}_B must be expressed as a function of the current variables. To do this, we use

$$\Phi_k = M_{k\ell} I_\ell \quad \text{and} \quad I_k = M_{k\ell}^{-1} \Phi_\ell. \quad (1)$$

Therefore,

$$U_B = \frac{1}{2} \sum_{k=1}^N I_k \Phi_k = \frac{1}{2} \sum_{k=1}^N \Phi_k M_{k\ell}^{-1} \Phi_\ell$$

$$\hat{U}_B = -\frac{1}{2} \sum_{k=1}^N I_k \Phi_k = -\frac{1}{2} \sum_{k=1}^N I_k M_{k\ell} I_\ell.$$

Substituting these expressions into the force formulae in the statement of the problem shows that the proposition will be proved if we can show that

$$\Phi_k \nabla M_{k\ell}^{-1} \Phi_\ell = -I_k \nabla M_{k\ell} I_\ell. \quad (2)$$

We begin with $\mathbf{M}\mathbf{M}^{-1} = \mathbf{I}$ written in component form:

$$M_{k\ell} M_{\ell p}^{-1} = \delta_{kp}.$$

Using this,

$$(\nabla M_{k\ell}) M_{\ell p}^{-1} + M_{k\ell} (\nabla M_{\ell p}^{-1}) = 0.$$

Multiplying on the right by M_{ps} and summing over p gives

$$(\nabla M_{k\ell}) M_{\ell p}^{-1} M_{ps} = -M_{k\ell} (\nabla M_{\ell p}^{-1}) M_{ps}.$$

Using the definition of the inverse,

$$(\nabla M_{k\ell}) \delta_{\ell s} = -M_{k\ell} (\nabla M_{\ell p}^{-1}) M_{ps}.$$

The left side of this equation is ∇M_{ks} . Therefore, using (1) and the fact that $M_{k\ell} = M_{\ell k}$,

$$\begin{aligned} -I_k \nabla M_{ks} I_s &= -I_k \left[-M_{k\ell} (\nabla M_{\ell p}^{-1}) M_{ps} \right] I_s \\ &= I_k M_{k\ell} \nabla M_{\ell p}^{-1} \Phi_p \\ &= M_{\ell k} I_k \nabla M_{\ell p}^{-1} \Phi_p \\ &= \Phi_\ell \nabla M_{\ell p}^{-1} \Phi_p. \end{aligned}$$

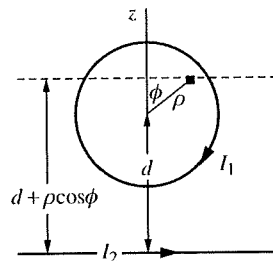
This is (2), as required.

12.20 The Force between a Current Loop and a Wire

(a) Let Φ_1 be the flux through the loop produced by the wire. The force on the loop is

$$\mathbf{F} = -\frac{\partial \hat{V}_B}{\partial d} \hat{\mathbf{z}},$$

where \hat{V}_B is the interaction potential energy $\hat{V}_B = -I_1 \Phi_1$. The black square in the diagram below is an area element $dS = \rho d\rho d\phi$ at a distance $d + \rho \cos \phi$ from the wire.



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The magnetic field at that element points out of the paper in the plane of the loop with magnitude

$$B_2 = \frac{\mu_0 I_2}{2\pi} \frac{1}{d + \rho \cos \phi}.$$

By the right-hand rule, $d\mathbf{S}$ points into the paper. Therefore,

$$\begin{aligned} \Phi_1 &= \int d\mathbf{S} \cdot \mathbf{B}_2 = -\frac{\mu_0 I_2}{2\pi} \int_0^R \int_0^{2\pi} \frac{\rho d\rho d\phi}{d + \rho \cos \phi} = -\mu_0 I_2 \int_0^R \frac{\rho d\rho}{\sqrt{d^2 - \rho^2}} \\ &= -\mu_0 I_2 \left[\sqrt{d^2 - R^2} - d \right]. \end{aligned}$$

This gives the force on the loop as

$$\mathbf{F} = \mu_0 I_1 I_2 \frac{\partial}{\partial d} \left[\sqrt{d^2 - R^2} - d \right] \hat{\mathbf{z}} = \mu_0 I_1 I_2 \left[\frac{d}{\sqrt{d^2 - R^2}} - 1 \right] \hat{\mathbf{z}}.$$

- (b) In the limit $d \gg R$, we use $(1 - R^2/d^2)^{-1/2} \approx 1 + R^2/2d^2$ to get the repulsive force on the loop as

$$\mathbf{F} = \frac{\mu_0 I_1 I_2 R^2}{2d^2} \hat{\mathbf{z}}.$$

The magnetic moment of the loop is $m_1 = I_1 \pi R^2$ and points into the paper. Therefore, since \mathbf{B}_2 points out of the paper, the force on the loop should be

$$\mathbf{F} = \nabla(m_1 \cdot \mathbf{B}_2) = -(I_1 \pi R^2) \frac{\mu_0 I_2}{2\pi} \frac{\partial}{\partial d} \left(\frac{1}{d} \right) \hat{\mathbf{z}} = \frac{\mu_0 I_1 I_2 R^2}{2d^2} \hat{\mathbf{z}}.$$