Rutgers University Department of Physics & Astronomy

01:750:271 Honors Physics I Fall 2015

Lecture 4

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4. Motion in two and three dimensions

Goals:

- To study position, velocity, and acceleration vectors
- To apply position, velocity, and acceleration insights to projectile motion
- To extend our linear investigations to uniform circular motion
 - To investigate relative velocity

in two and three dimensions.

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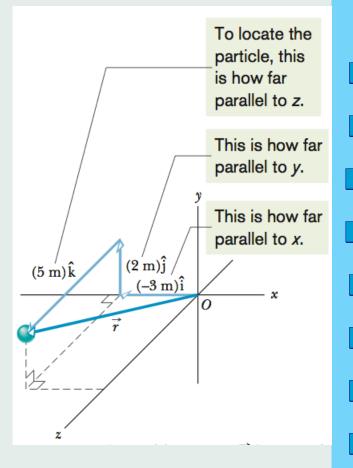
Position and Displacement

 In 3D the position of a particle is given by a position vector

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

starting at the origin O.

- x, y, z are the **components** of \vec{r} , also called the **coordinates** of the particle.
- The path of the particle is generally a **curve**.



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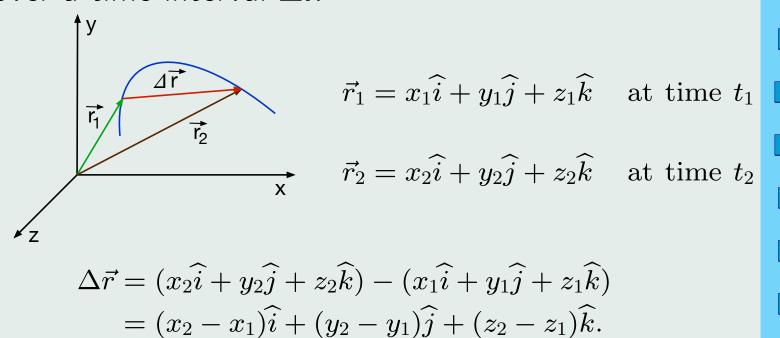
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• **Displacement:** the **change** of the position vector \vec{r} over a time interval Δt .

 $=\Delta x \, \hat{i} + \Delta y \, \hat{j} + \Delta z \, \hat{k}.$



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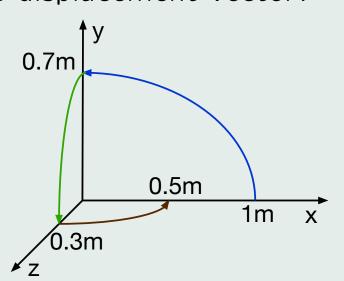
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A particle travels along a 3D path as shown in the figure starting from the initial position $\vec{r}_1 = (1\,\mathrm{m})\hat{i}$ and ending with the final position $\vec{r}_2 = (0.5\,\mathrm{m})\hat{i}$. What is the displacement vector?



A)
$$\Delta \vec{r} = (-1 \,\mathrm{m})\hat{i} + (0.7 \,\mathrm{m})\hat{j}$$

B)
$$\Delta \vec{r} = (0.7 \,\mathrm{m})\hat{j} - (0.3 \,\mathrm{m})\hat{k}$$

$$C) \Delta \vec{r} = (-0.5 \,\mathrm{m})\hat{i}$$

$$D) \Delta \vec{r} = 0$$

$$E) \ \Delta \vec{r} = (0.5 \, \mathrm{m}) \hat{i}$$

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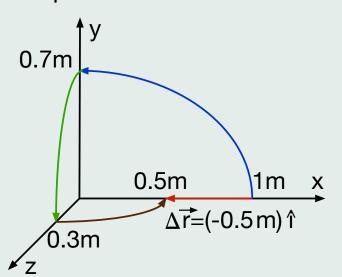
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$$C) \Delta \vec{r} = (-0.5 \,\mathrm{m})\hat{i}$$

$$D) \Delta \vec{r} = 0$$

$$E) \ \Delta \vec{r} = (0.5 \,\mathrm{m}) \hat{i}$$

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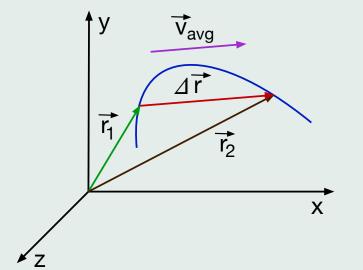
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Average and Instantaneous Velocity

ullet Average velocity over a time interval Δt

$$\vec{v}_{\text{avg}} = \frac{\text{Displacement vector}}{\text{time interval}} = \frac{\Delta \vec{r}}{\Delta t}$$



Note:

Since $\Delta t>0 \Rightarrow \vec{v}_{\rm avg}$ is always parallel with $\Delta \vec{r}$ and points in the same direction.

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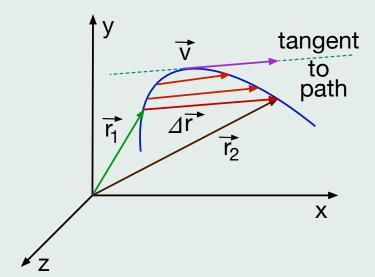
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• Instantaneous velocity at time t

$$\vec{v} = \lim_{\Delta t \to 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d\vec{r}}{dt} = \left(\frac{dx}{dt}\right)\hat{i} + \left(\frac{dy}{dt}\right)\hat{j} + \left(\frac{dz}{dt}\right)\hat{k}$$



Note:

• \vec{v} is always **tangent** to the path of the particle at its current position.

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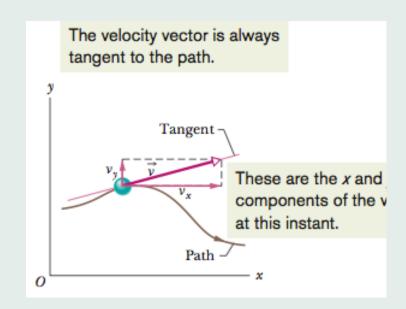
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• Components of \vec{v} :

$$v_x = \frac{dx}{dt}$$
, $v_y = \frac{dy}{dt}$, $v_z = \frac{dz}{dt}$



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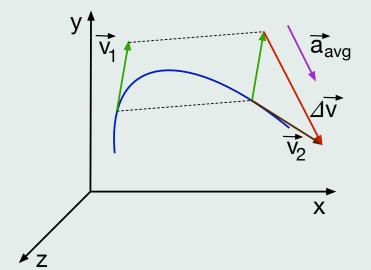
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Average and Instantaneous Acceleration

ullet Average acceleration over a time interval Δt

$$ec{a}_{ extsf{avg}} = rac{\Delta ec{v}}{\Delta t}$$



Note:

Since $\Delta t>0 \Rightarrow \vec{a}_{\rm avg}$ is always parallel with $\Delta \vec{v}$ and points in the same direction.

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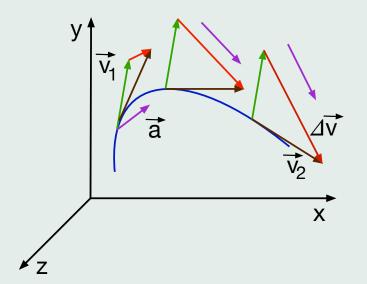
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• Instantaneous acceleration at time t

$$\vec{a} = \lim_{\Delta t \to 0} \frac{\Delta \vec{v}}{\Delta t} = \frac{d\vec{v}}{dt} = \left(\frac{dv_x}{dt}\right)\hat{i} + \left(\frac{dv_y}{dt}\right)\hat{j} + \left(\frac{dv_z}{dt}\right)\hat{k}$$



Acceleration is a vector which measures the change of the velocity vector.

• Components of \vec{a} :

$$a_x = \frac{dv_x}{dt}$$
, $a_y = \frac{dv_y}{dt}$, $a_z = \frac{dv_z}{dt}$

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• The acceleration is non-zero if

either

the magnitude of \vec{v} changes.

or

the direction of \vec{v} changes.

• The acceleration is 0 if and only if **both** the **magnitude** and the **direction** of \vec{v} are **constant**.

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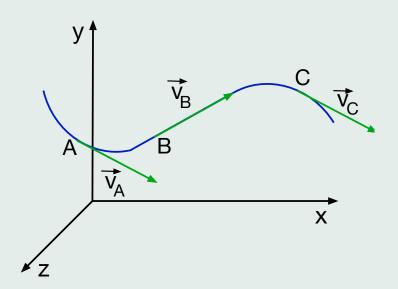
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A particle moves on a path as shown below such that the **magnitude** of its velocity vector is **constant**. Where is the instantaneous acceleration \vec{a} zero?



- A) Everywhere
- B) At A
- C) At C
- D) At B
- E) Nowhere

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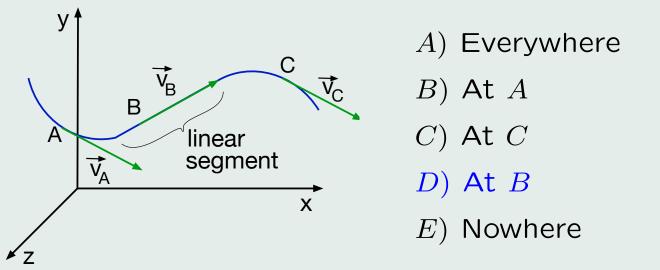
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A particle moves on a path as shown below such that the **magnitude** of its velocity vector is **constant**. Where is the instantaneous acceleration \vec{a} zero?



 $|\vec{v}|$ constant $\Rightarrow \vec{v}$ constant on linear segment; \vec{v} not constant on curved segments; changes direction.

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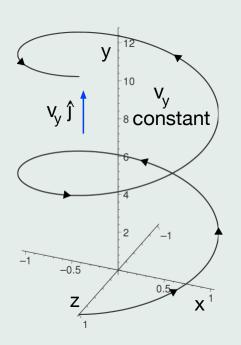
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A particle moves on a helix as shown below such that the y-component of its velocity is constant. Which of the following statements is false?



$$A) a_x \neq 0$$

$$B) \ a_z \neq 0$$

$$C) a_y = 0$$

$$D) \ a_y \neq 0$$

E) None of the above.

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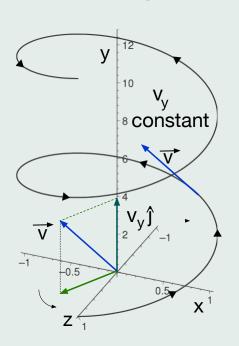
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A particle moves on a helix as shown below such that the y-component of its velocity is constant. Which of the following statements is false?



$$A) a_x \neq 0$$

$$B) \ a_z \neq 0$$

$$C) a_y = 0$$

$$D) \ a_y \neq 0$$

E) None of the above.

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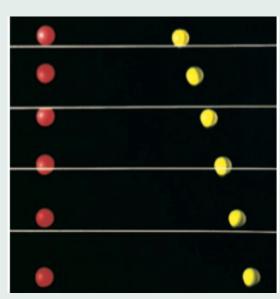
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Projectile Motion

• Projectile Motion: motion in a vertical plane with constant acceleration equal to the free fall acceleration.





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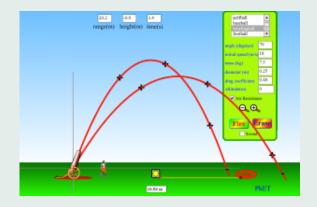
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Examples: tennis, baseball, basketball, football ...



How hard and at what angle should the quarterback throw?



How should the gun shoot in order to hit the target?

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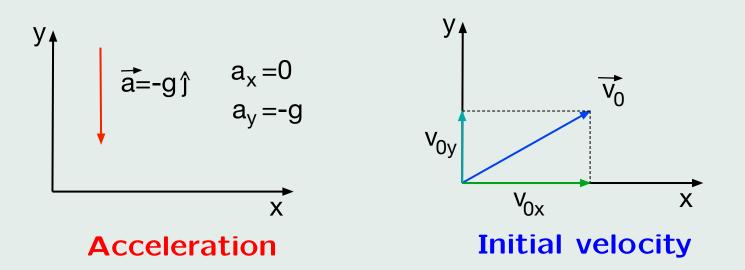
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Set up coordinate system



Note: no correlation between v_{0x}, v_{0y} ; can take any values independently from each other.

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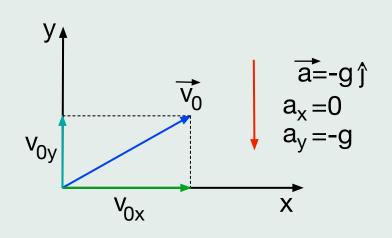
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Recall that

$$\vec{a} = \frac{d\vec{v}}{dt}$$

Then what is the time dependence of v_x ?



A)
$$v_x = 0$$

B)
$$v_x = v_{0x}$$

$$C) v_x = v_{0x} - gt$$

$$D) v_x = v_{0x} + gt$$

$$E) v_x = v_{0y}$$

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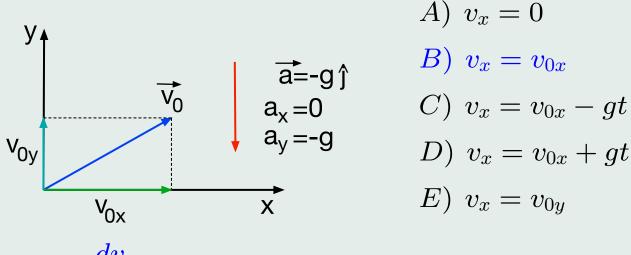
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Recall that

$$\vec{a} = \frac{d\vec{v}}{dt}$$

Then what is the time dependence of v_x ?



$$\frac{dv_x}{dt} = a_x = 0 \implies v_x = \text{constant} = v_{0x}$$

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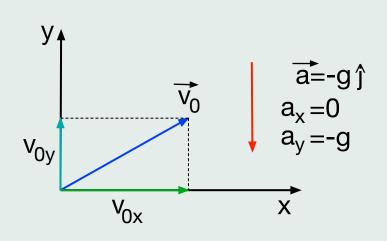
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Recall that

$$\vec{a} = \frac{d\vec{v}}{dt}$$

Then what is the time dependence of v_y ?



$$A) v_y = 0$$

$$B) v_y = v_{0y}$$

$$C) v_y = v_{0y} - gt$$

$$D) v_y = v_{0y} + gt$$

$$E) v_y = v_{0x}$$

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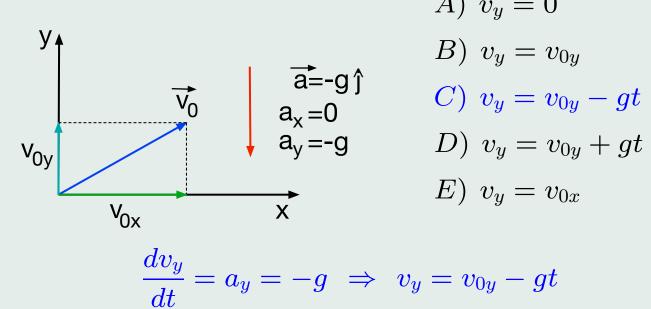
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Recall that

$$\vec{a} = \frac{d\vec{v}}{dt}$$

Then what is the time dependence of v_y ?



A)
$$v_y = 0$$

$$B) v_y = v_{0y}$$

$$C) v_y = v_{0y} - gv$$

$$D) v_y = v_{0y} + gt$$

$$E) v_y = v_{0x}$$

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Is there any correlation between vertical and horizontal motion?

No!

$$v_x = v_{0x}, \qquad v_y = v_{0y} - gt$$

 v_{0x}, v_{0y} are completely independent.

Can decompose projectile motion into vertical and horizontal parts.

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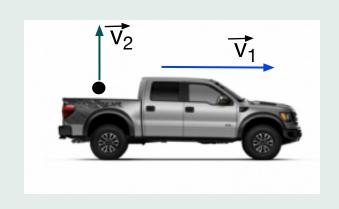
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A ball is thrown straight up with velocity vector \vec{v}_2 from a truck moving with constant velocity \vec{v}_1 . For which values of v_1, v_2 will the ball land back in the truck at a later time?



A)
$$v_1 < v_2$$

B)
$$v_1 > v_2$$

$$(C) v_1 = v_2$$

D) It will not happen for any values of v_1, v_2 .

E) For any values of v_1, v_2

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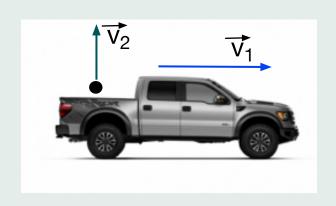
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A ball is thrown straight up with velocity vector \vec{v}_2 from a truck moving with constant velocity \vec{v}_1 . For which values of v_1, v_2 will the ball land back in the truck at a later time?



- A) $v_1 < v_2$
- $(B) v_1 > v_2$
- $(C) v_1 = v_2$
- D) It will not happen for any values of v_1, v_2 .
- E) For any values of v_1, v_2

The horizontal component v_{0x} for the ball is equal to v_1 . Since $a_x=0$, $v_x=v_1$ at any time t>0.

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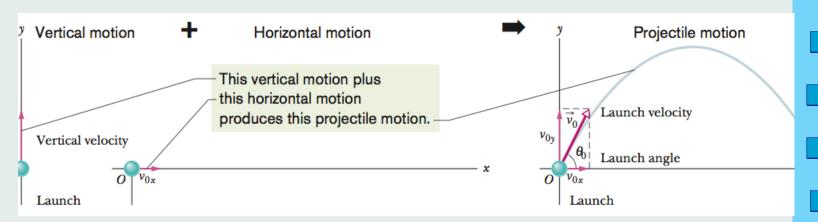
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Projectile motion analysed



Initial velocity

$$\vec{v}_0 = v_{0x}\hat{i} + v_{0y}\hat{j}, \qquad v_{0x} = v_0\cos\theta_0,$$

$$v_{0x} = v_0 \cos \theta_0,$$

$$v_{0y} = v_0 \sin \theta_0$$

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Horizontal motion

Vertical motion

$$a_x = 0$$

$$v_x = v_{0x}$$
$$= v_0 \cos \theta_0$$

$$x - x_0 = v_{0x}t$$
$$= (v_0 \cos \theta_0)t$$

$$a_y = -g$$

$$v_y = v_{0y} - gt$$
$$= v_0 \sin \theta_0 - gt$$

$$y - y_0 = v_{0y}t - gt^2/2$$
$$= (v_0 \sin \theta_0)t - gt^2/2$$

$$v_y^2 = (v_0 \sin \theta_0)^2 - 2g(y - y_0)$$

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• Trajectory $(\theta_0 \neq \pi/2)$

$$(x - x_0) = (v_0 \cos \theta_0)t,$$
 $(y - y_0) = (v_0 \sin \theta_0)t - gt^2/2$

Launch

$$\Downarrow \quad \text{Eliminate } \mathbf{t} : t = \frac{x - x_0}{v_0 \cos \theta_0}$$

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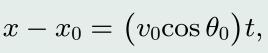
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Projectile motion

Parabola

Quit



 $y=y_0+\left(an heta_0
ight)(x-x_0) -rac{g(x-x_0)^2}{2ig(v_0\cos heta_0ig)^2}$ Launch velocity

$$y - y_0 = (v_0 s_1)$$

$$y-y_0=(v_0)$$

$$y - y_0 = (v_0 \sin x)$$

Horizontal range

The **horizontal** distance R travelled until returning to initial height.

$$y - y_0 = (\tan \theta_0)(x - x_0) - \frac{g(x - x_0)^2}{2(v_0 \cos \theta_0)^2}$$
$$y = y_0 \implies (\tan \theta_0)R - \frac{gR^2}{2(v_0 \cos \theta_0)^2}$$

$$R = \frac{v_0^2}{g} \sin(2\theta_0) \qquad \left(\text{using } 2\sin\theta_0 \cos\theta_0 = \sin(2\theta_0) \right)$$

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Maximum horizontal range

For fixed v_0 , when is R maximum?

$$0 \le \sin(2\theta_0) \le 1$$
, $\sin(2\theta_0) = 1 \Leftrightarrow 2\theta_0 = \pi/2$

Hence R is maximum for $\theta_0 = \pi/4$ and

$$R_{max} = \frac{v_0^2}{g}$$

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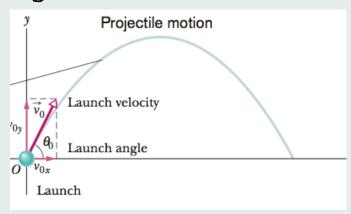
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A projectile is launched from the origin as shown below. How long will it take for it to reach maximum height?



A)
$$(v_0/g)\sin\theta_0$$

$$B) (v_0/g) \cos \theta_0$$

$$C) v_0/g$$

$$D (v_0/g) \tan \theta_0$$

E) None of the above.

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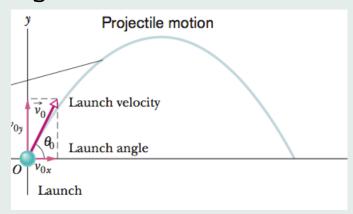
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A projectile is launched from the origin as shown below. How long will it take for it to reach maximum height?



A)
$$(v_0/g)\sin\theta_0$$

$$B) (v_0/g) \cos \theta_0$$

$$C) v_0/g$$

$$D (v_0/g) \tan \theta_0$$

E) None of the above.

$$v_y = v_0 \sin \theta_0 - gt$$
. Max height: $v_y = 0 \Rightarrow t = (v_0/g) \sin \theta_0$

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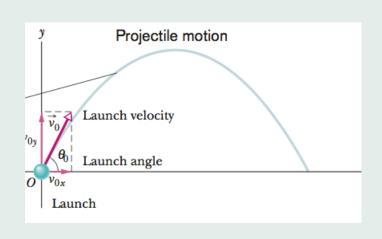
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A projectile is launched from the origin as shown below. What is its maximum height?



A)
$$(v_0^2/g)\sin\theta_0$$

B)
$$(v_0^2/2g)\cos\theta_0$$

$$C) v_0^2/2g$$

$$D \left(v_0 \sin \theta_0 \right)^2 / 2g$$

E) None of the above.

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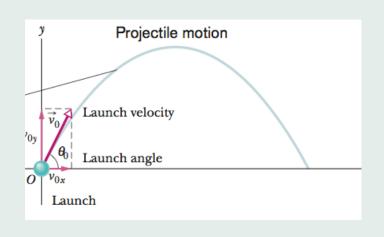
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A projectile is launched from the origin as shown below. What is its maximum height?



A)
$$(v_0^2/g)\sin\theta_0$$

B)
$$(v_0^2/2g)\cos\theta_0$$

$$(C) v_0^2/2g$$

$$D \left(v_0 \sin \theta_0\right)^2 / 2g$$

E) None of the above.

$$v_y^2 = (v_0 \sin \theta_0)^2 - 2gy; \ v_y = 0 \Rightarrow y = (v_0 \sin \theta_0)^2 / 2g$$

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