

$\phi = B_{\perp} A =$  magnetic flux

$$\Phi = \sum B_{\perp} \Delta A$$

$$\mathcal{E} = - \frac{\Delta \phi}{\Delta t}$$

$$\mathcal{E} = - N \frac{\Delta \Phi}{\Delta t}$$

**Lenz's Law** Direction of current **opposes**  $\Delta \phi$  which created it.

$$\left( e^{-\frac{t}{L/R}} \right)$$

$$V_{\max} = I_{\max} Z$$

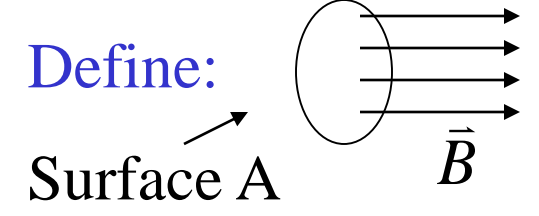
$$Z_R = R$$

$$Z_L = X_L = \omega L$$

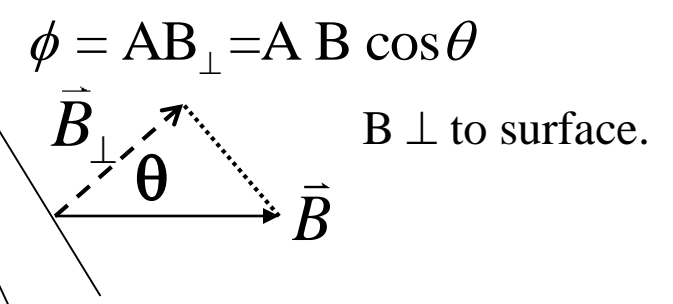
$$Z_C = X_C = \frac{1}{\omega C}$$

$$Z_{RLC} = \sqrt{R^2 + (X_L - X_C)^2}$$

Recall: moving charges (I) in  $\vec{B}$   $\longrightarrow$  force  
 moving charges (I)  $\longrightarrow$  created.  $\vec{B}$   
 Now we consider (B)  $\longrightarrow$  I connection.



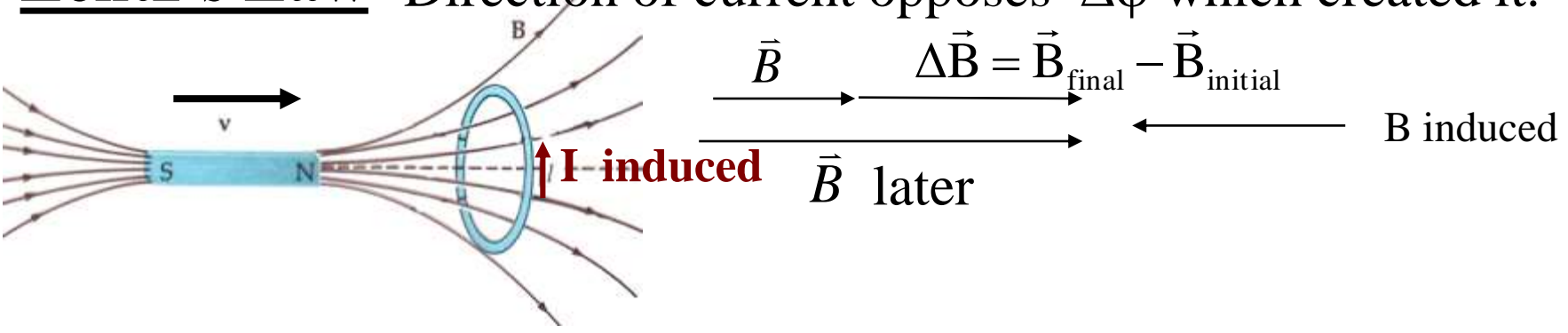
$\phi = \vec{B}_{\perp} A = \text{magnetic flux}$



## Faraday's Law

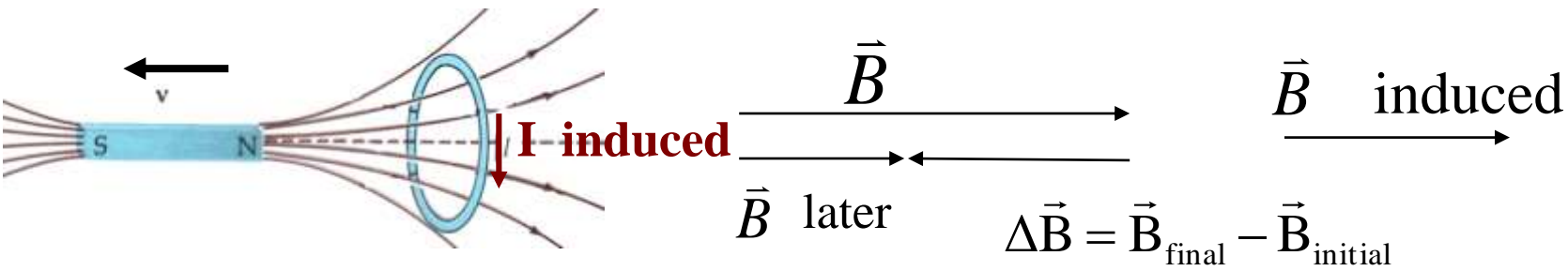
$\mathcal{E} = - \frac{\Delta \phi}{\Delta t}$  EMF created by  $\frac{\Delta \phi}{\Delta t}$

**Lenz's Law** Direction of current opposes  $\Delta\phi$  which created it.



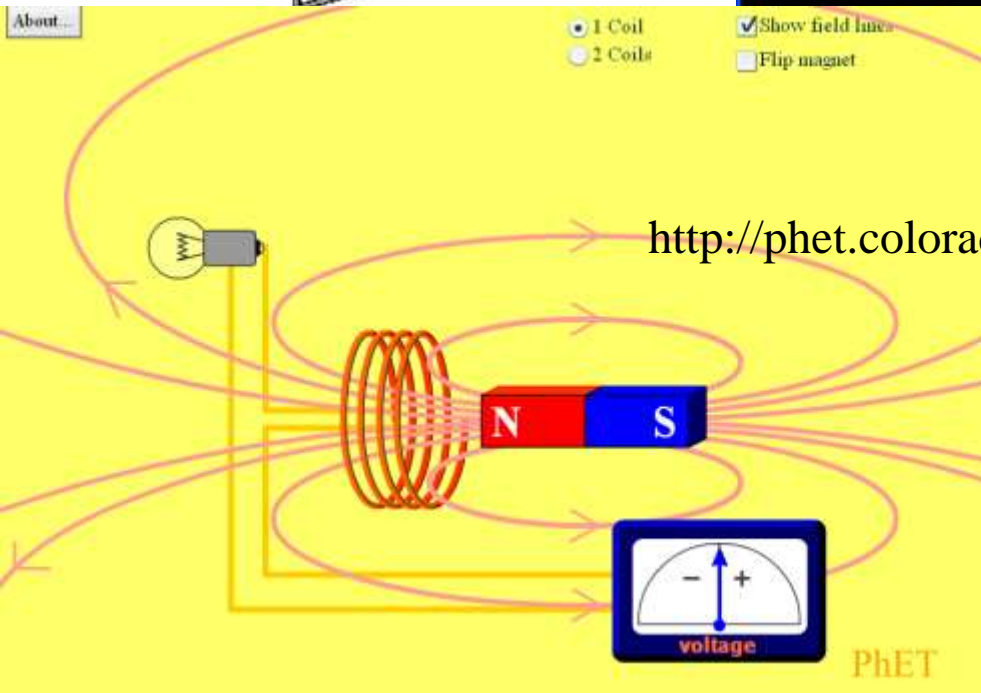
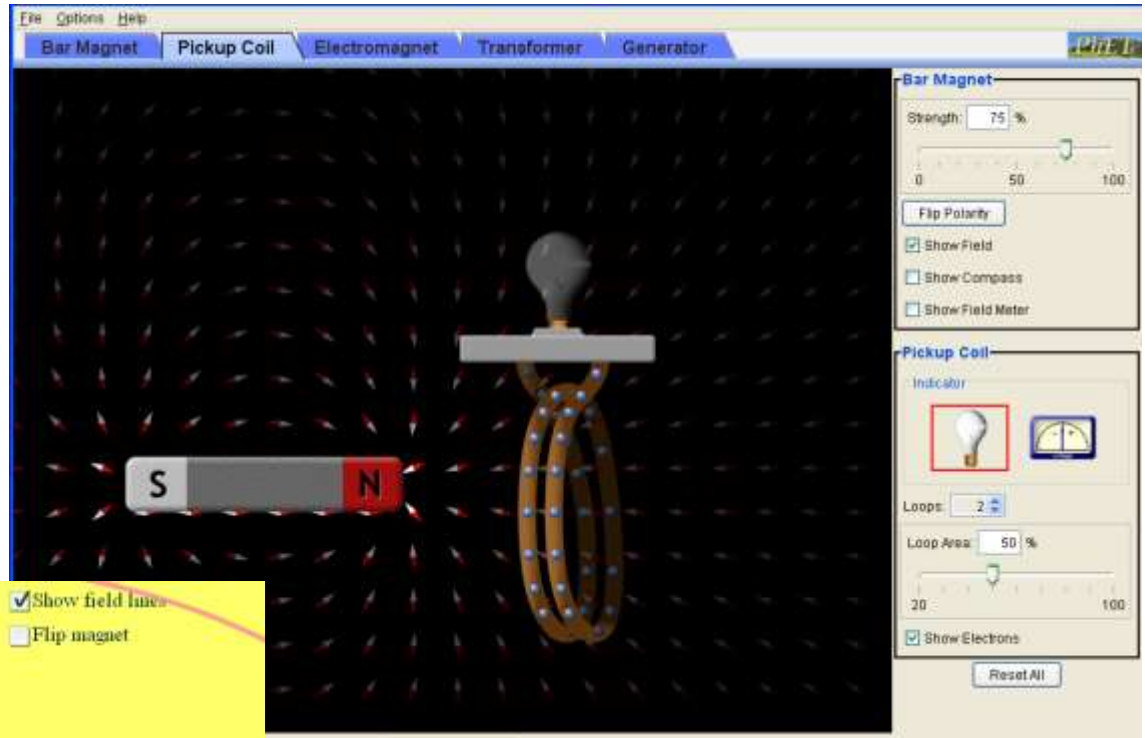
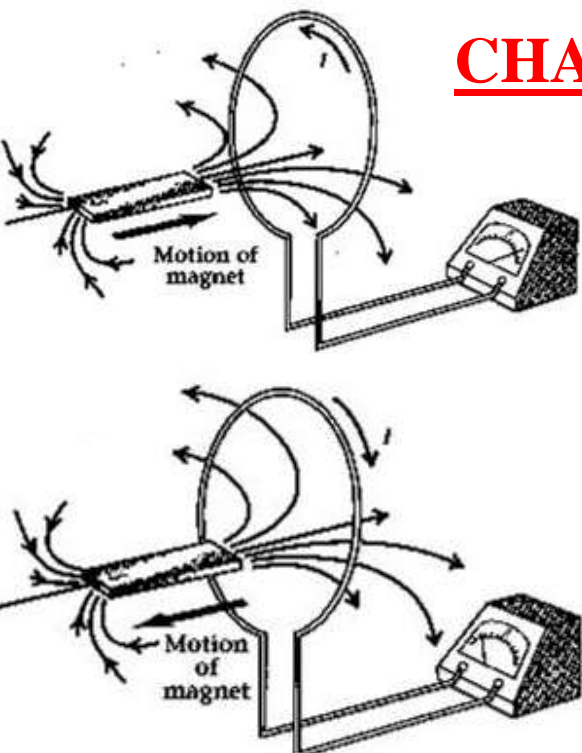
$\Delta\phi = \Delta(AB_{\perp})$  In these examples  $A = \text{constant}$

$\therefore \Delta\phi = A\Delta(B_{\perp})$



# CHANGE IN FLUX CAUSES CURRENT !!!

<http://phet.colorado.edu/en/simulation/faraday>



[http://phet.colorado.edu/sims/faradays-law/faradays-law\\_en.html](http://phet.colorado.edu/sims/faradays-law/faradays-law_en.html)

# Eddy currents

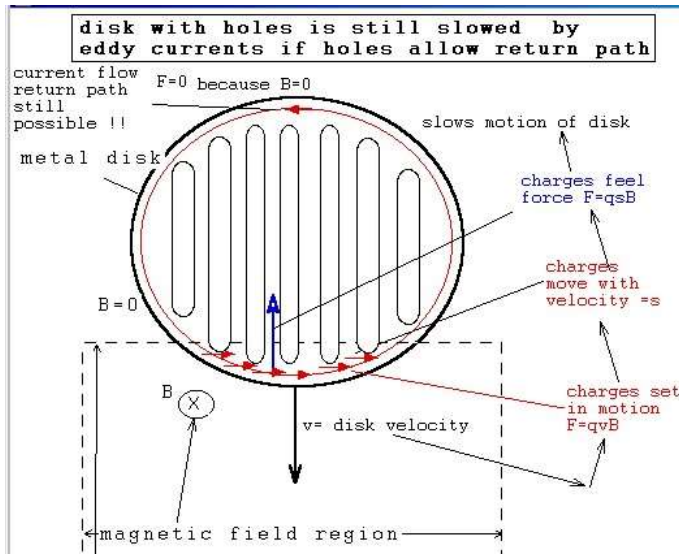
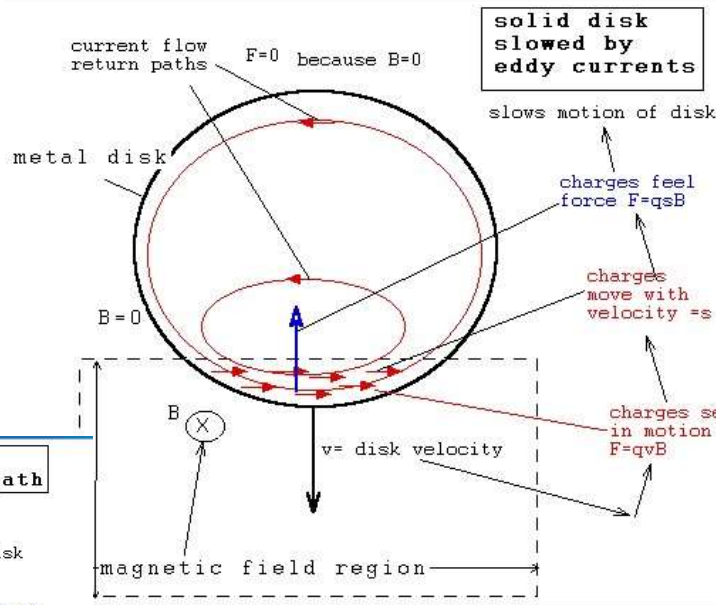
## Falling Magnet Applet

<http://web.mit.edu/jbelcher/www/java/falling/falling.html>

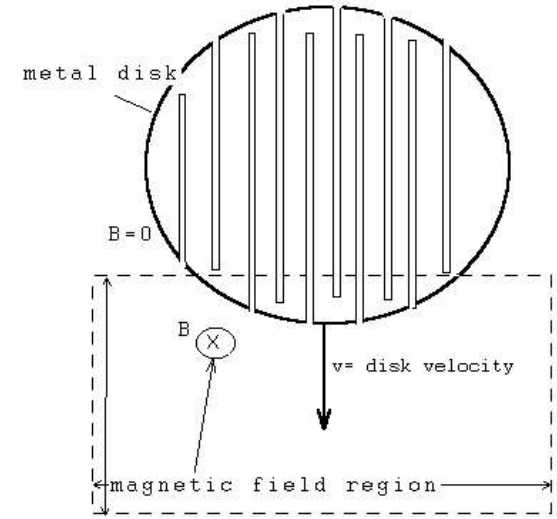
Magnet in Cu tube <http://www.physics.rutgers.edu/~croft/magnetintube.wmv>



Inclined plane



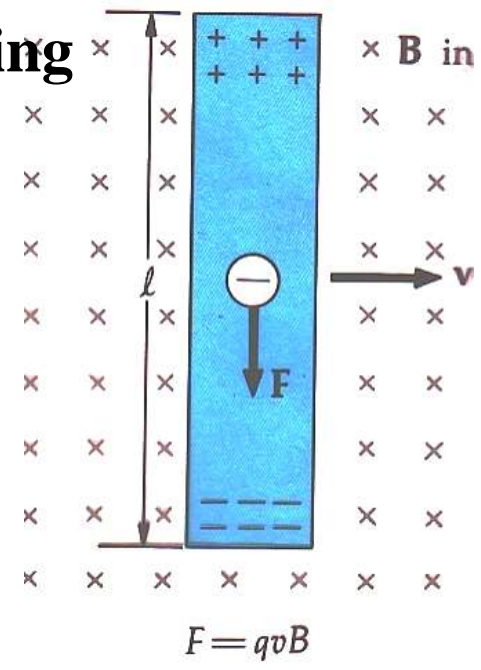
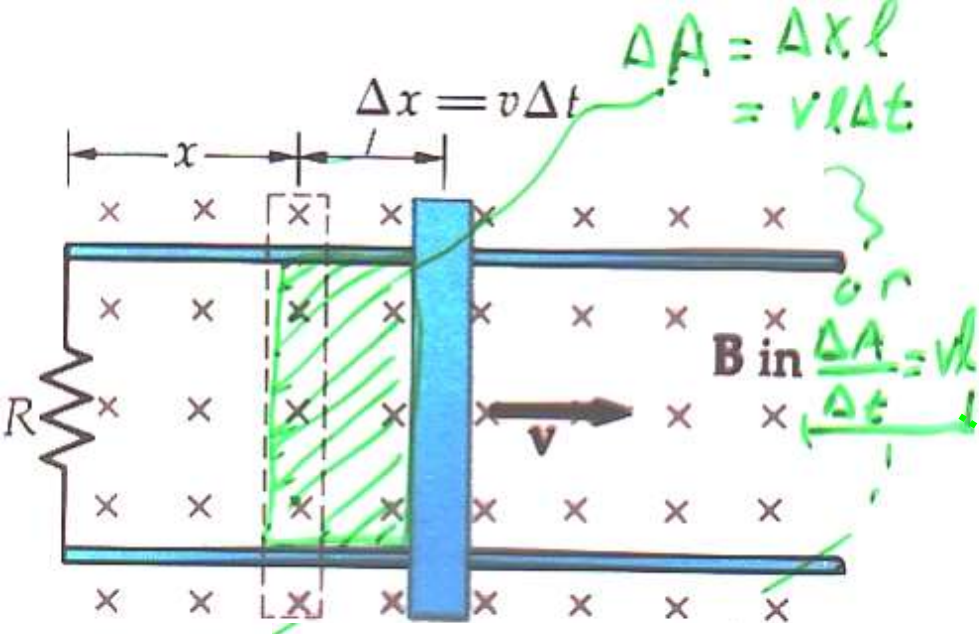
disk slices does not allow circular current flow so no effect



Magnet- on Cu Inclined plane

<http://www.physics.rutgers.edu/~croft/2007magnetonplane.wmv>

**metal rod moving  
on metal rails  
in B field**



Voltage or EMF across rod

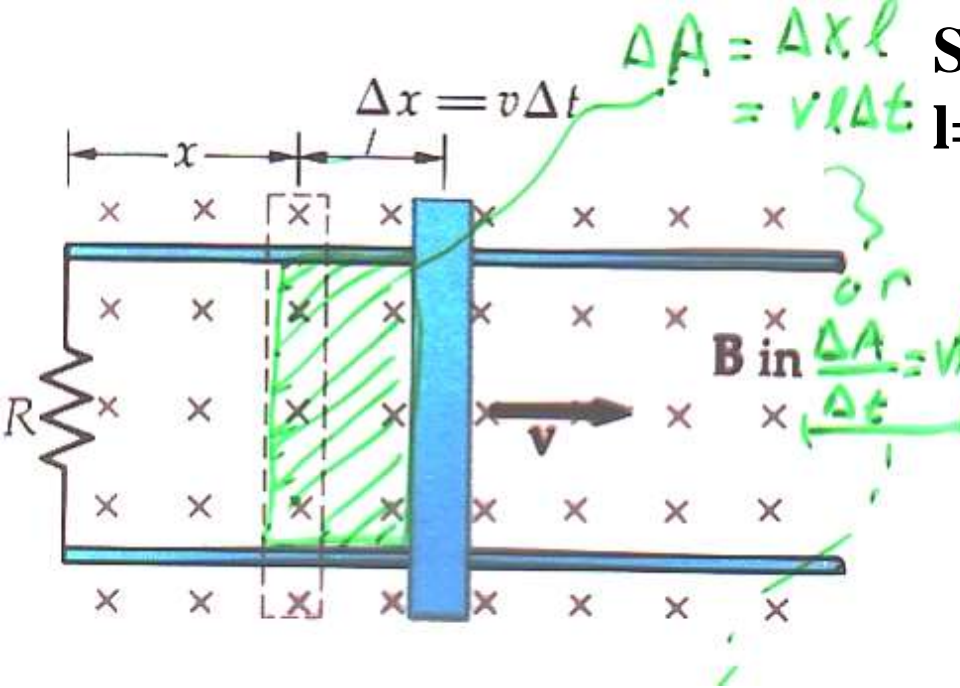
$\therefore |E| = v = \frac{W}{q} = \text{work done / charge moved length of Rod.}$

$\therefore |E| = \frac{W}{q} = \frac{Fl}{q} = \frac{\cancel{q} l v B}{\cancel{q}} = l v B \quad \text{ie } |E| = l v B$

$l v = \frac{\Delta A}{\Delta t}$

$\therefore |E| = \frac{\Delta A}{\Delta t} B \quad \text{or } \phi = BA$

$|E| = \frac{\Delta \phi}{\Delta t}$



What is the  $I$  in the circuit?

$$| \mathcal{E} | = \frac{\Delta \phi}{\Delta t}$$

$$\frac{\Delta \phi}{\Delta t} = \frac{B \Delta A}{\Delta t} = B l \frac{\Delta x}{\Delta t} = B l v$$

$$V = \frac{\Delta \phi}{\Delta t} = B l v = (0.5\ \text{T})(0.2\ \text{m})(0.1\ \text{m/s}) = 0.01\ \text{Tm}^2/\text{s} = 0.01\ \text{V}$$

Units next page

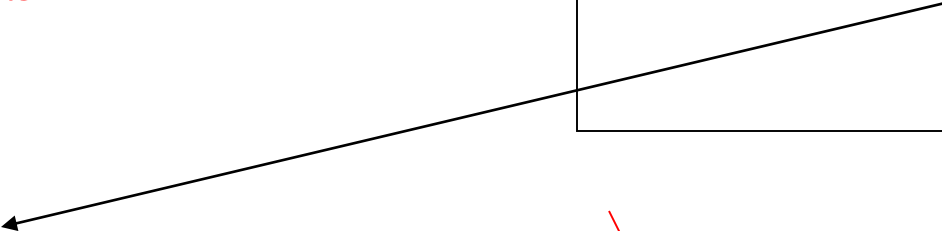
$$V = IR \Rightarrow I = \frac{V}{R} = \frac{0.01\ \text{V}}{3\ \Omega} = .0033\text{A}$$

**recall**  $F = qvB$

**units**  $N = C \frac{\text{m}}{\text{s}} T$

$$\frac{N \text{ s}}{C \text{ m}} = T$$

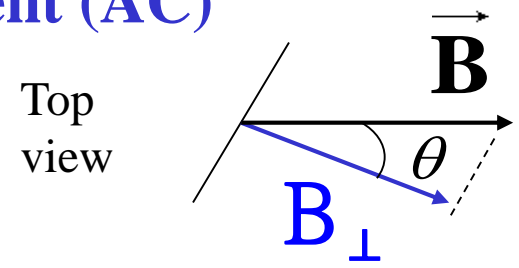
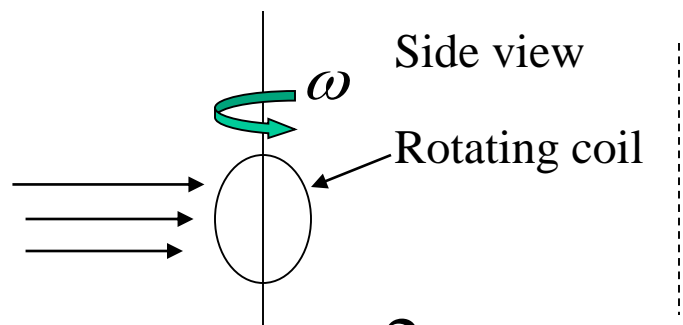
**units**


$$\frac{[T] \text{m}^2}{\text{s}} = \left[ \frac{N \text{ s}}{C \text{ m}} \right] \frac{\text{m}^2}{\text{s}} = \frac{N}{C} \text{m} = \frac{J}{C} = V$$

$$V = \frac{\Delta\phi}{\Delta t}$$



# Generator: creates alternating current (AC)



$$\theta = \omega t = 2\pi ft = \frac{2\pi t}{T}$$

$$\phi = B_{\perp} A = BA \cos \theta$$

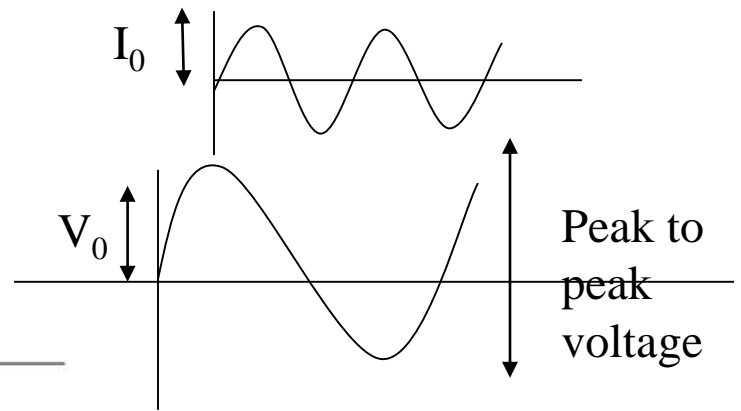
AC current (will discuss later)

$$\mathcal{E} = -\frac{\Delta\phi}{\Delta t} = -BA \frac{\Delta \cos(\omega t)}{\Delta t}$$

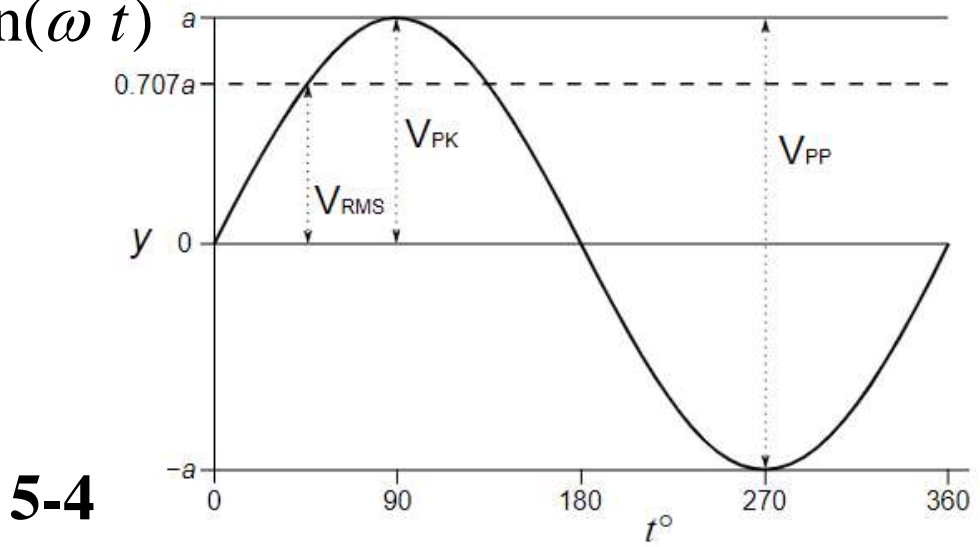
$$\mathcal{E} = BA\omega \sin(\omega t)$$

$$V = V_0 \sin(\omega t)$$

$$\omega = \frac{2\pi}{T}$$



$$V_{\text{Peak to peak}} = 2V_0$$



# Alternating Current (AC)

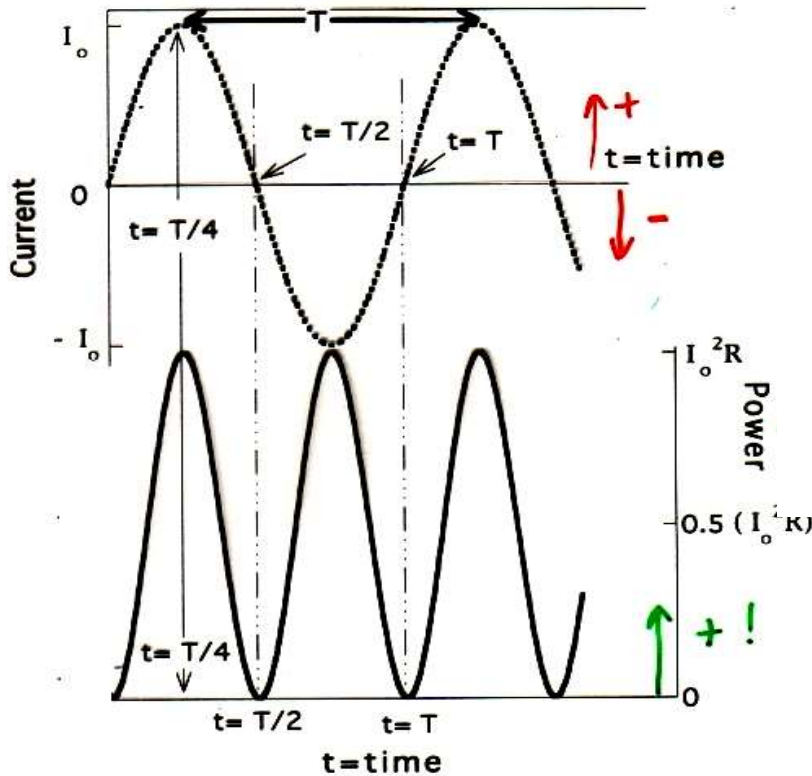
$$I = I_0 \sin(2\pi ft) = I_0 \sin(\omega t)$$

$$V = V_0 \sin(2\pi ft) = V_0 \sin(\omega t)$$

$$T = \text{period (sec.)}$$

$$\frac{1}{T} = f = \text{freq. (cyc. / sec)}$$

$$\omega = 2\pi f = \text{ang. freq. (rad/sec.)}$$



$$V = IR$$

$$P = I^2 R = IV \text{ power}$$

$$P = I_0^2 R \sin^2(\omega t) = I_0 V_0 \sin^2(\omega t)$$

\*  
Average power over time:

$$\bar{P} = \frac{I_0 V_0}{2}$$

$$\overline{\sin^2 2\pi ft} = \frac{1}{2}$$

$$\bar{P} = I_{RMS} V_{RMS}$$

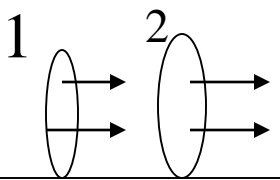
$$\frac{I_0}{\sqrt{2}} = I_{RMS} = .707I_0$$

$$\frac{V_0}{\sqrt{2}} = V_{RMS} = .707V_0$$

Example line voltage

$$V_{RMS} = 120 \text{ Volts}$$

$$V_0 = V_{RMS} (\sqrt{2}) = 170 \text{ Volts}$$

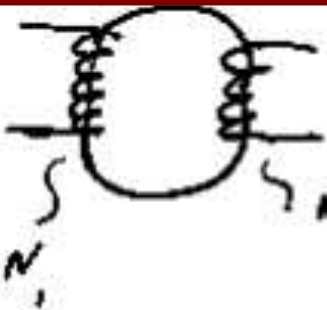


# Magnetic field coupling between coils

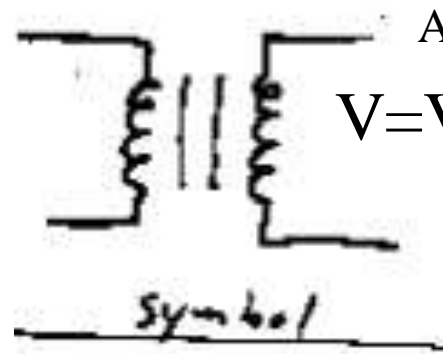
$\Delta I_1$  creates  $\Delta B_1 \rightarrow$  induces  $I_2$

## Principle of transformer

voltage  $\rightarrow V_1$



$V_2$  - voltage  
# windings



AC current

$$V = V_o \sin \omega t$$

$V = -N \frac{\Delta \phi}{\Delta t} \rightarrow \frac{V}{N} = - \frac{\Delta \phi}{\Delta t}$  **Same for both 1 and 2**  $\rightarrow \boxed{\frac{V_1}{N_1} = \frac{V_2}{N_2}}$  More coils more V

**Energy conservation**  $\rightarrow I_1 V_1 = I_2 V_2 \rightarrow \boxed{\frac{I_1}{I_2} = \frac{V_2}{V_1} = \frac{N_2}{N_1}}$  **More coils more V but less I**

# Energy conservation

$$I_1 V_1 = I_2 V_2 \rightarrow \boxed{\frac{I_1}{I_2} = \frac{V_2}{V_1} = \frac{N_2}{N_1}}$$

## Step down transformer ex. Door bell

24V bell voltage

120V line voltage



$$\frac{N_1}{N_2} = \frac{V_1}{V_2} = \frac{120}{24} = 5$$

$$I_1 V_1 = I_2 V_2$$

Long distance power transmission

high V modest current

---

step down transformer to  
120 V & high current

# Inductance (L) {self field coupling}

$$\phi_{\text{solenoid (total)}} = N (AB) = N (A [\mu_0 n I])$$

$\uparrow$  # loops     $\uparrow$   $\phi$ /loop     $n = \frac{\# \text{ loops}}{\text{length}} = \frac{N}{\ell}$

$$\phi = N A \mu_0 \frac{N}{\ell} I = \underbrace{[\mu_0 N^2 A]}_{[L]} I$$

So  $\phi = LI$

$$L = \left[ \frac{\mu_0 N^2 A}{\ell} \right]$$

**L contains**  
 geometry (A,  $\ell$ ) +  $\mu_0$  + N  
 + material

$$\mu_r = \mu / \mu_0$$

Material	$\mu$ (H m <sup>-1</sup> )	$\mu_r$	Application
Ferrite U 60	1.00E-05	8	UHF chokes
Ferrite M33	9.42E-04	750	Resonant circuit RM cores
Nickel (99% pure)	7.54E-04	600	-
Ferrite N41	3.77E-03	3000	Power circuits
Iron (99.8% pure)	6.28E-03	5000	-
Ferrite T38	1.26E-02	10000	Broadband transformers
Silicon GO steel	5.03E-02	40000	Dynamos, mains transformers
supermalloy	1.26	1000000	Recording heads

Approximate maximum permeabilities

How L is used  $\rightarrow$  AC circuits  
 or just time change in I



$\mathcal{E}$  across  $\mathcal{E} = -\frac{\Delta\phi}{\Delta t} = -L \frac{\Delta I}{\Delta t}$

$\mathcal{E} = -L \frac{dI}{dt}$  **L in Henrys (H)**

Units

**L in Henrys**

$$\left[ \phi_{T_{sol}} = L_{sol} I \right] \quad \left[ L_{sol} = \frac{\mu_0 N^2 A}{l} \right]$$

Units

$$T \cdot m^2 = H A$$

Henry's

$$\Rightarrow H = \frac{T \cdot m^2}{A}$$

most basic units

$$\frac{T \cdot m^2}{A} = \left( \frac{N}{Am} \right) \cdot \frac{m^2}{A} = \frac{N \cdot m}{A^2} = \frac{kg \cdot m}{s^2} \frac{m}{C^2/s^2} \rightarrow H = \frac{kg \cdot m^2}{C^2}$$

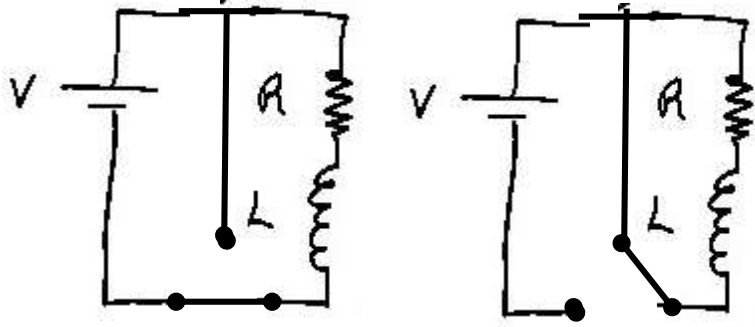
$$\mathcal{E} \equiv - \frac{\Delta \phi}{\Delta t} = - L \frac{\Delta I}{\Delta t}$$

Check units

$$V = H \frac{A}{s} \Rightarrow H = \frac{V \cdot s}{A}$$

$$\frac{V \cdot s}{A} = \frac{N \cdot m \cdot s}{C/s} = \frac{kg \cdot m \cdot m}{s^2 C^2} = \frac{kg \cdot m^2}{C^2}$$

# Collapse magnetic field in L



$t=0$  move switch.

$$L \frac{\Delta I}{\Delta t} + I R = 0$$

$\therefore$  here  $\frac{\Delta I}{\Delta t} + \frac{R}{L} I = 0$

$$I = (I_0) \left( e^{-\frac{t}{L/R}} \right)$$

**Recall:**

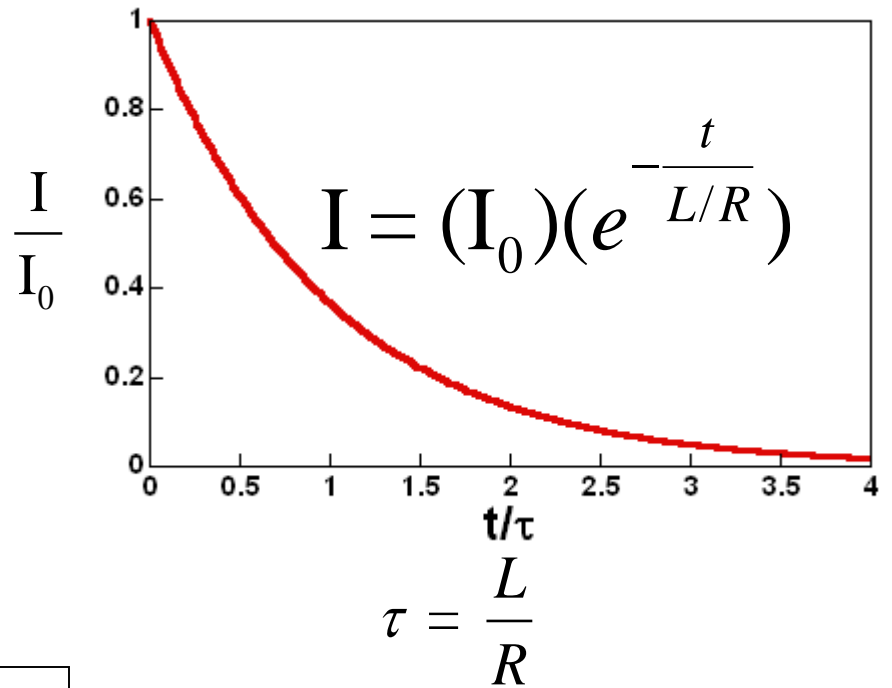
$$\frac{\Delta Q}{\Delta t} + \frac{1}{RC} Q = 0 \Rightarrow Q = Q_0 e^{-\frac{t}{RC}}$$

# Boundary conditions

$$t = 0 \quad V = I_0 R$$

$$I_0 = \frac{V}{R}$$

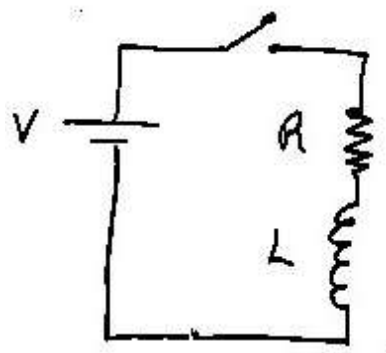
$$t = \infty \quad I = 0 \quad \frac{\Delta I}{\Delta t} = 0$$



5-8

I at  $t = \infty$

# Establishing magnetic field in L



t=0 close switch.

$$V = IR + L \frac{\Delta I}{\Delta t}$$

$$\frac{\Delta I}{\Delta t} + \frac{R}{L} I = \frac{V}{L}$$

# Boundary conditions

$$t = 0 \quad I = 0$$

$$t = \infty$$

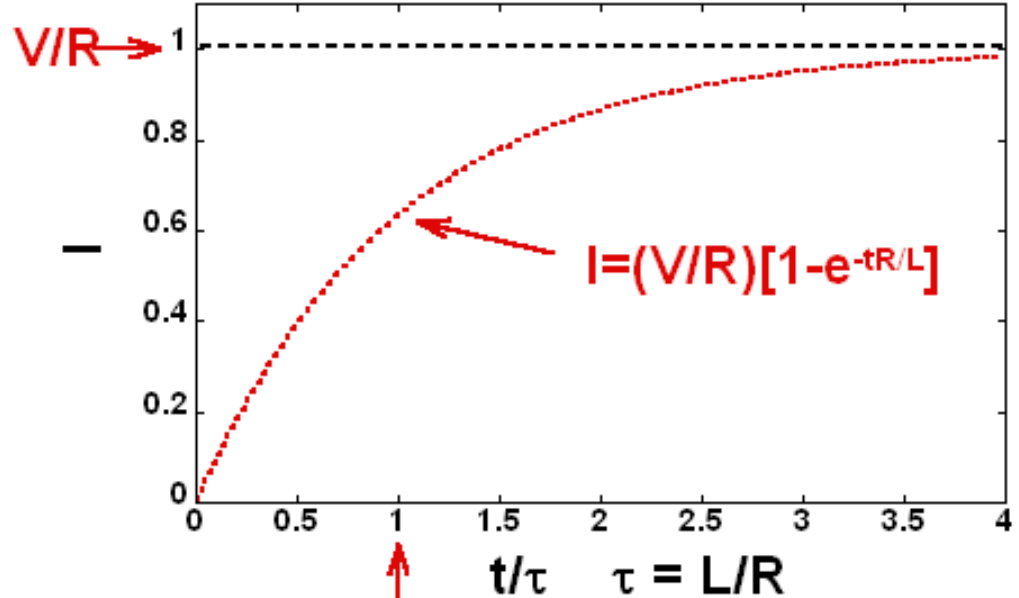
$$I = \text{constant} \quad V = IR$$

$$\frac{\Delta I}{\Delta t} = 0$$

∴ here

$$I = \left( \frac{V}{R} \right) (1 - e^{-\frac{tR}{L}})$$

↙  
I at t=∞



## Recall:

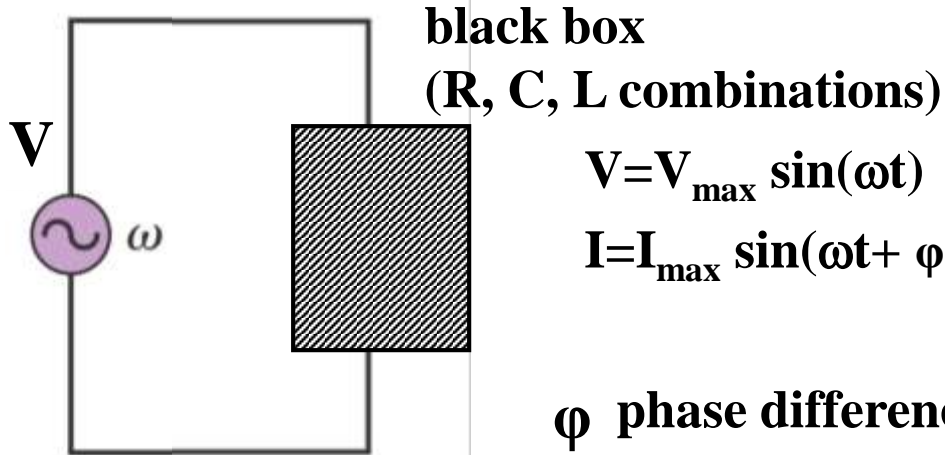
$$\frac{\Delta Q}{\Delta t} + \frac{1}{RC} Q = \frac{V}{R} \Rightarrow Q = VC(1 - e^{-\frac{t}{RC}})$$

$$I = \frac{V}{R} e^{-\frac{t}{RC}}$$

5-8a



# General AC circuit

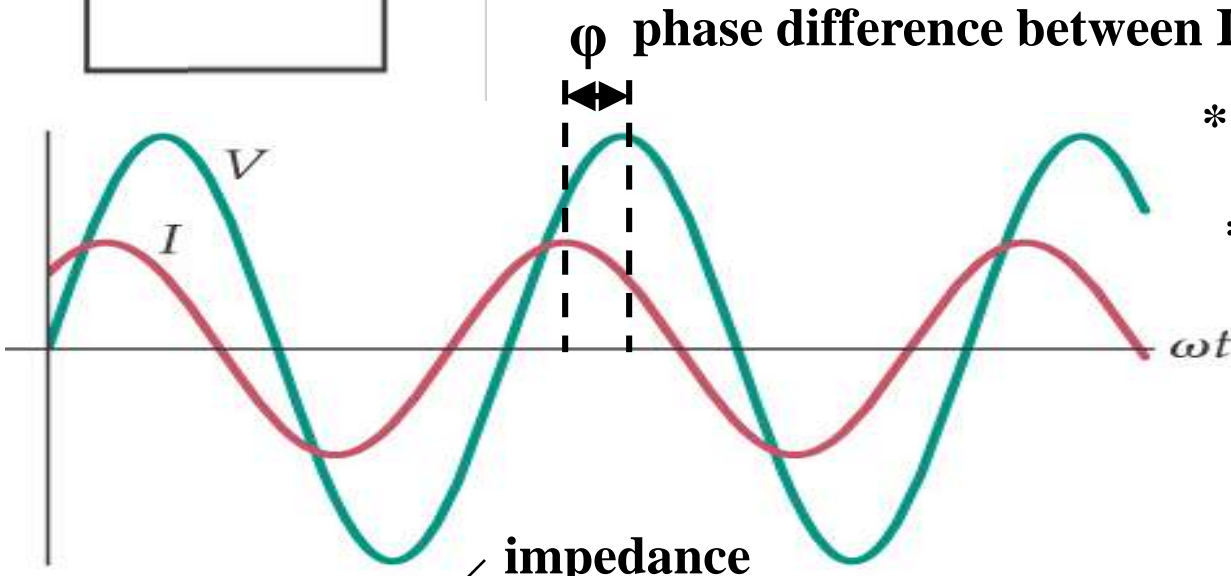


$$V = V_{\max} \sin(\omega t)$$

$$I = I_{\max} \sin(\omega t + \phi)$$

**Note: You can use current as reference for phase (book)**

$$I = I_{\max} \sin(\omega t)$$

$$V = V_{\max} \sin(\omega t - \phi)$$


- \* if R only then  $\phi=0$
- \* if L or C present  $\phi \neq 0$

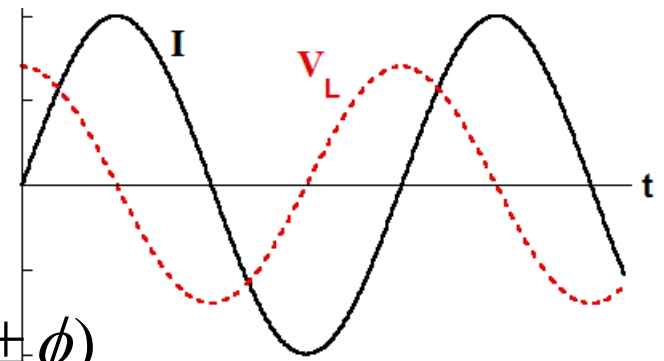
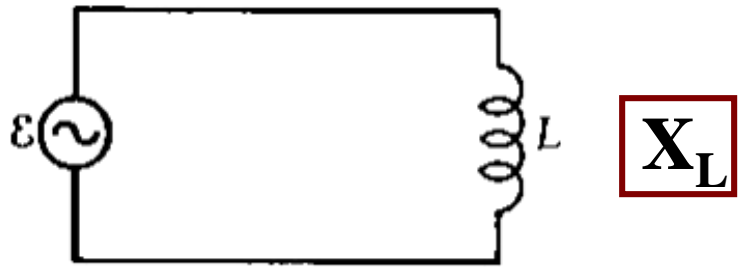
$$V_{\max} = I_{\max} Z$$

(Ohm's Law generalization)

$Z \longrightarrow$   
2 parts

**resistance**  
**R**

**reactance**  
 $X_C \quad X_L$



$$I = I_0 \sin(\omega t) \Rightarrow V = V_0 \sin(\omega t \pm \phi)$$

$$\frac{dI}{dt} = I_0 \omega \cos(\omega t)$$

$$V = L \frac{dI}{dt} = L I_0 \omega \cos(\omega t) = \omega L I_0 \sin(\omega t + \pi/2)$$

$$V = [\omega L] I_0 \sin(\omega t + \pi/2)$$

[V<sub>0</sub>]

$$V_0 = (\omega L) I_0$$

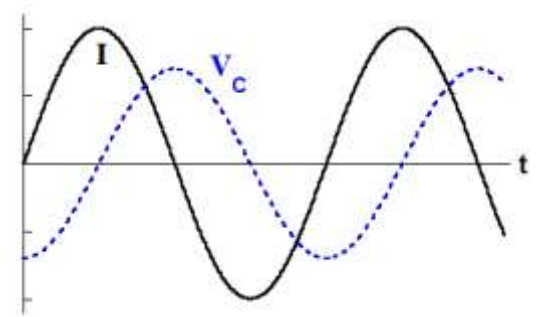
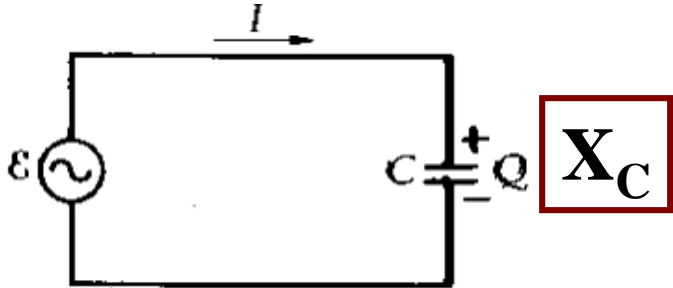
↙ X<sub>L</sub>

$$X_L = \omega L$$

$$I_0 = \frac{V_0}{\omega L}$$

$\omega \rightarrow 0 \quad X_L \rightarrow 0 \quad \text{inductive load} \rightarrow 0$

$\omega \rightarrow \infty \quad X_L \rightarrow \infty \quad \text{inductive load} \rightarrow \infty$



$$X_c = \frac{1}{\omega C} \quad \phi = 90^\circ$$

$$I = I_0 \sin(\omega t) \Rightarrow V = V_0 \sin(\omega t \pm \phi)$$

$$I = \frac{dQ}{dt}$$

$$Q = \int I dt = \int I_0 \sin(\omega t) dt = I_0 \frac{-\cos(\omega t)}{\omega}$$

$$V = \frac{Q}{C}$$

$$V = \frac{1}{\omega C} I_0 [-\cos(\omega t)] = \left[ \frac{1}{\omega C} \right] I_0 \sin(\omega t - \pi/2)$$

$\downarrow$   
 $V_0$

$$V_0 = \left[ \frac{1}{\omega C} \right] I_0$$

Note!  $\omega t$  usually measured in radians use degrees for simplicity

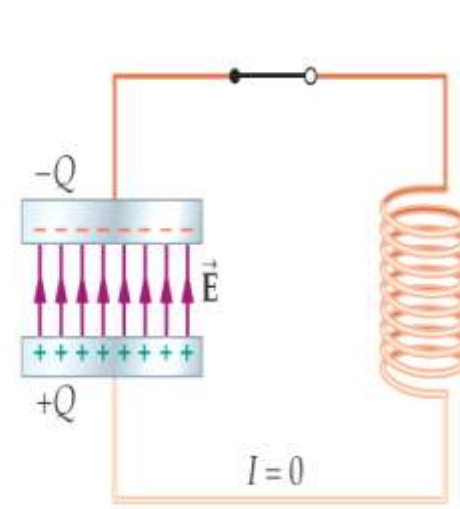
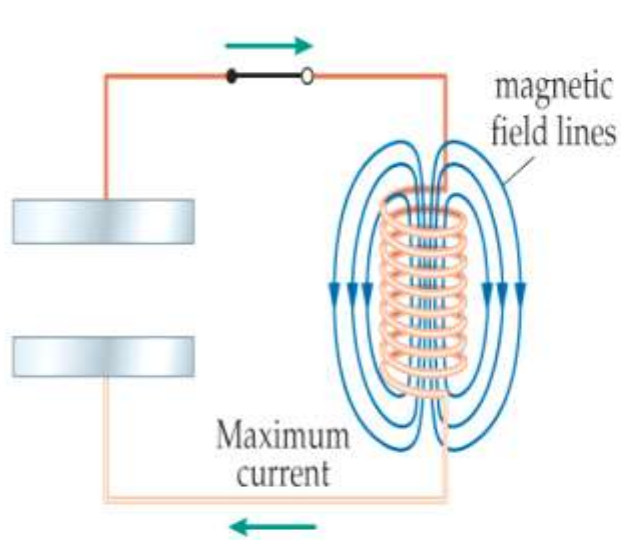
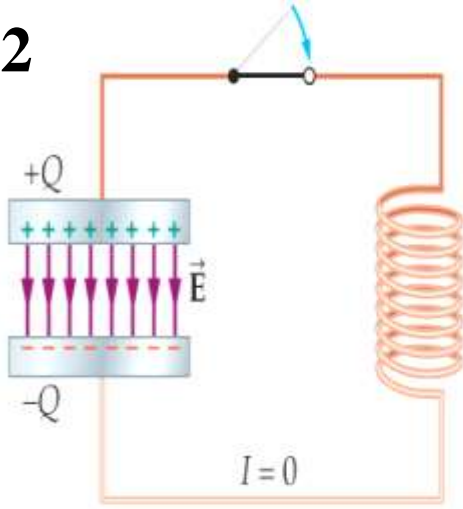
$$X_c = \frac{1}{\omega C}$$

$$V_0 = X_C I_0$$

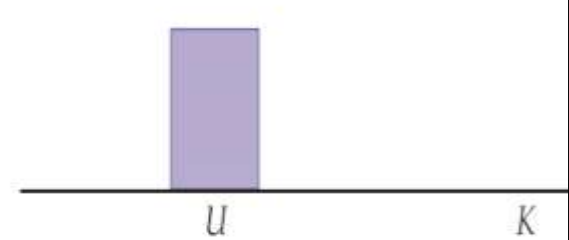
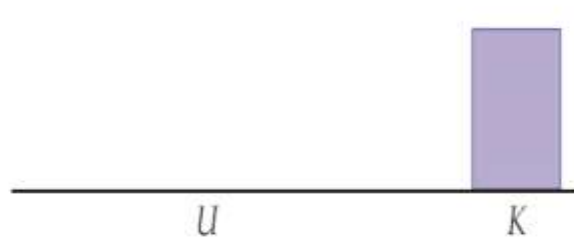
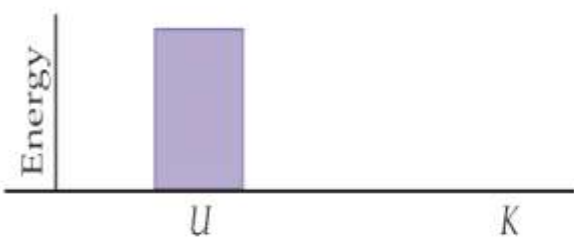
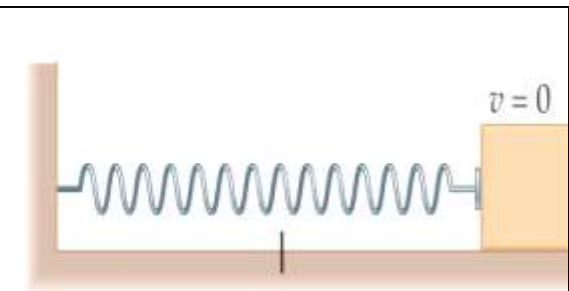
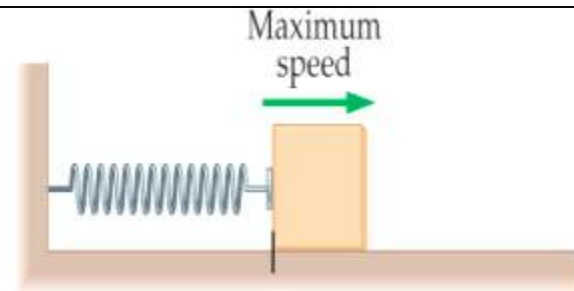
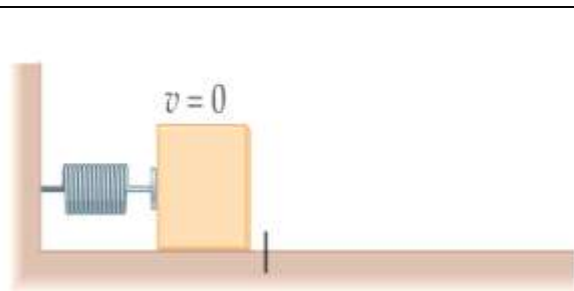
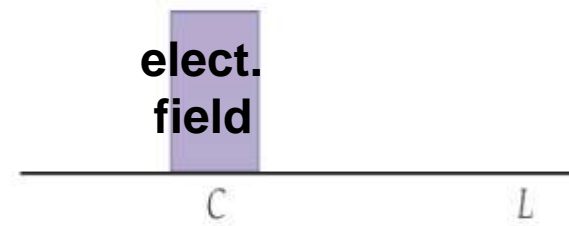
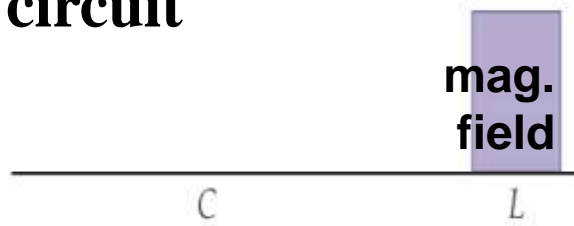
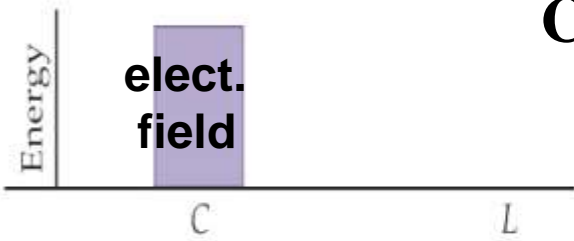
**Note:**  $\omega \rightarrow \infty \quad X_c \rightarrow 0$   
 High frequency looks like short circuit

$\omega \rightarrow 0 \quad X_c \rightarrow \infty$   
 0 frequency no AC current

5-12



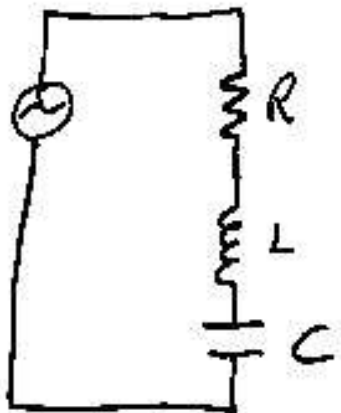
**C-L circuit**



## Analogies Between a Mass on a Spring and an $LC$ Circuit

Mass-spring system		$LC$ circuit	
position	$x$	charge	$q$
velocity	$v = \Delta x / \Delta t$	current	$I = \Delta q / \Delta t$
mass	$m$	inductance	$L$
force constant	$k$	inverse capacitance	$1/C$
natural frequency	$\omega = \sqrt{k/m}$	natural frequency	$\omega = \sqrt{1/LC}$

# RLC series circuit – Current resonance



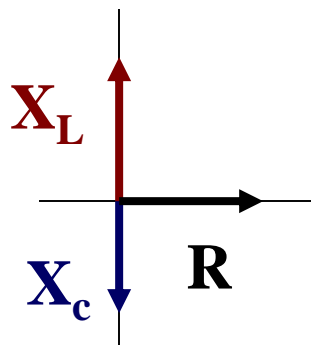
$$V = V_R + V_L + V_C$$

$$\frac{AC}{V = V_0 \sin(\omega t)}$$

$V=IR$  worked well so  
look for relation

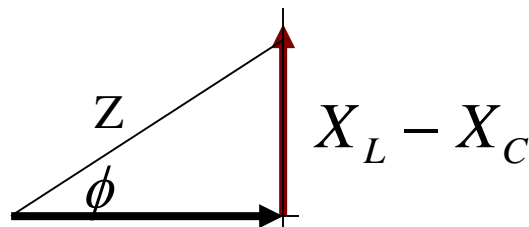
$$V_0 = I_0 Z$$

phase  
 $I = I_0 \sin(\omega t + \phi)$



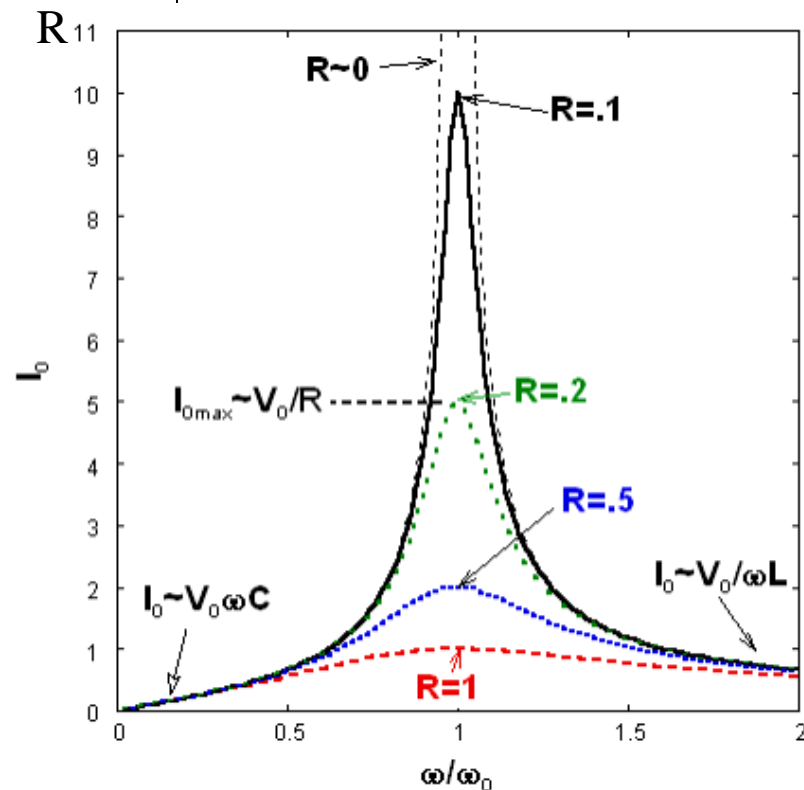
$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$

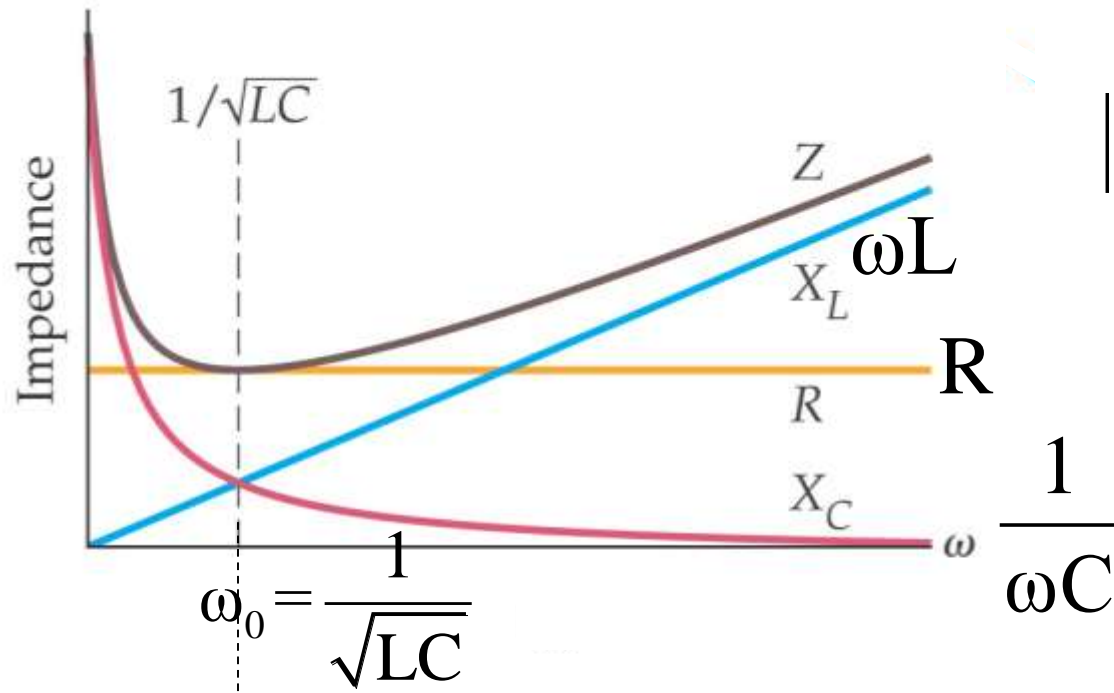
$$I_0 = \frac{V_0}{Z} = \frac{V_0}{\sqrt{R^2 + (\omega L - \frac{1}{\omega C})^2}}$$



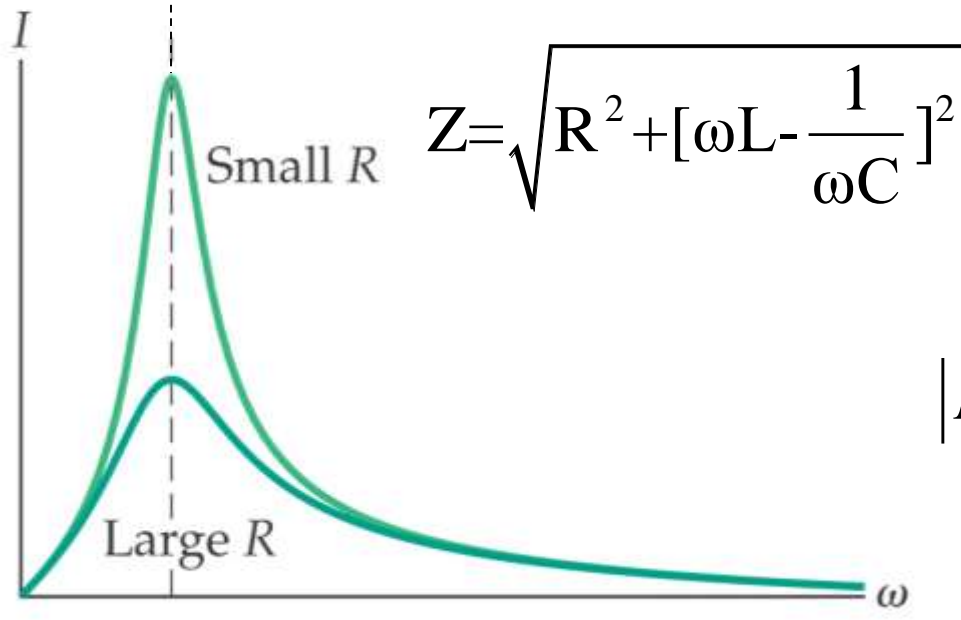
Resonance where  $X_L - X_C \Rightarrow 0$

$$\omega_0 = \frac{1}{\sqrt{LC}}$$





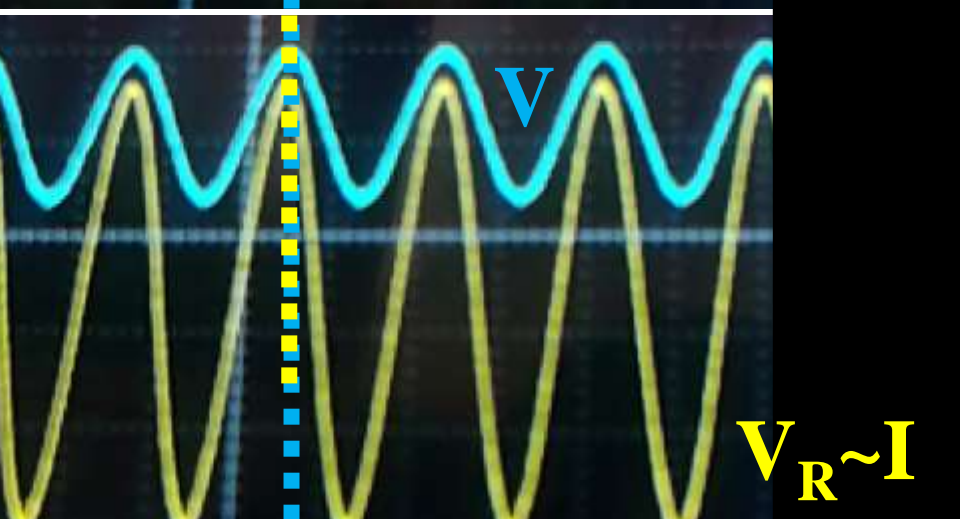
$$|Z| = \sqrt{R^2 + \left[\omega L - \frac{1}{\omega C}\right]^2}$$



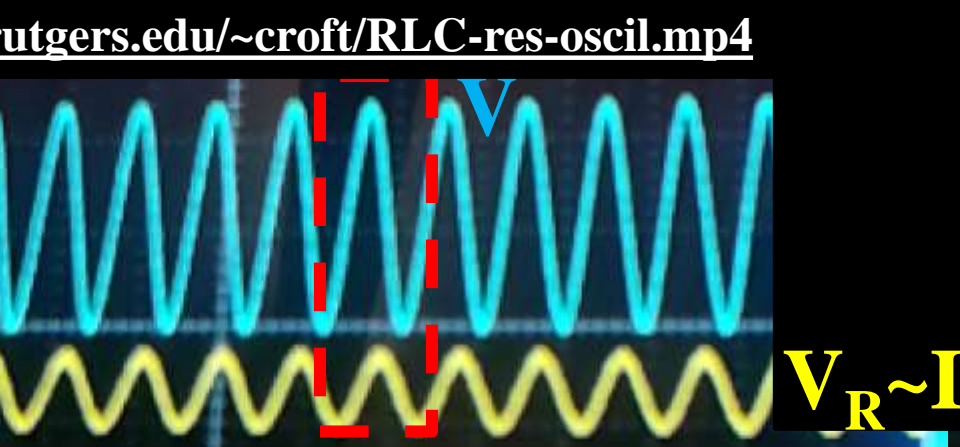
$$|I| = \frac{|V|}{|Z|} = \frac{|V|}{\sqrt{R^2 + \left[\omega L - \frac{1}{\omega C}\right]^2}}$$



$\omega \ll \omega_0$   
**I small**  $Z \sim \sqrt{\left[-\frac{1}{\omega C}\right]^2}$   
**phase C-like**



$\omega = \omega_0$  **phase R-like**  
 $Z \sim \sqrt{R^2}$  **(0)**



$\omega \gg \omega_0$   
 $Z \sim \sqrt{[\omega L]^2}$   
**phase L-like**

[utgers.edu/~croft/RLC-res-oscil.mp4](http://utgers.edu/~croft/RLC-res-oscil.mp4)