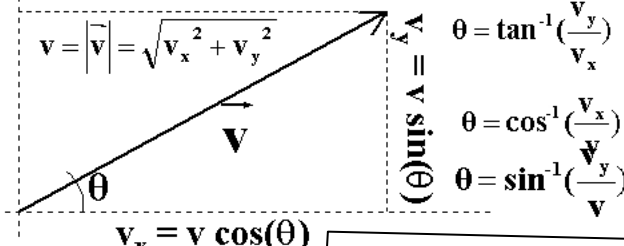
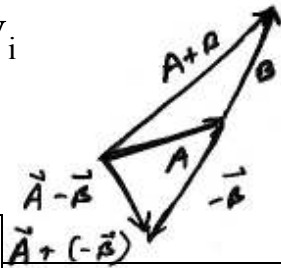


$$\Delta \mathbf{x} = \mathbf{x}_f - \mathbf{x}_i \quad \Delta \mathbf{v} = \mathbf{v}_f - \mathbf{v}_i$$

$$\bar{\mathbf{v}} = \frac{\Delta \mathbf{r}}{\Delta t}$$

$$\bar{\mathbf{a}} = \frac{\Delta \bar{\mathbf{v}}}{\Delta t}$$



$$\omega = \frac{\Delta \theta}{\Delta t} \quad \alpha = \frac{\Delta \omega}{\Delta t}$$

$$\omega = 2\pi f \quad f = \frac{1}{T}$$

$$\begin{aligned} \mathbf{v} &= \mathbf{v}_o + \mathbf{a}t \\ \mathbf{x} &= \mathbf{x}_o + \mathbf{v}_o t + \frac{1}{2} \mathbf{a}t^2 \quad \text{1D} \\ \mathbf{v}^2 - \mathbf{v}_o^2 &= 2 \mathbf{a} (\mathbf{x} - \mathbf{x}_o) \\ \bar{\mathbf{v}} &= \frac{\mathbf{v}_f + \mathbf{v}_i}{2} \quad \Delta \mathbf{x} = \bar{\mathbf{v}} \Delta t \end{aligned}$$

$$\begin{aligned} \mathbf{x} &\rightarrow x, y & \mathbf{x}_o &\rightarrow x_o, y_o \\ \mathbf{v} &\rightarrow v_x, v_y & \mathbf{v}_o &\rightarrow v_{ox}, v_{oy} \\ \mathbf{a} &\rightarrow a_x, a_y \end{aligned} \quad \text{2D}$$

$$\begin{aligned} \mathbf{x} &= r\theta \\ \mathbf{v} &= \omega r \\ \mathbf{a} &= \alpha r \end{aligned}$$

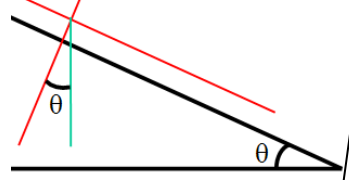
$$\begin{aligned} \omega &= \omega_o + \alpha t \\ \theta &= \theta_o + \omega_o t + \frac{1}{2} \alpha t^2 \\ \omega^2 - \omega_o^2 &= 2\alpha(\theta - \theta_o) \end{aligned}$$

$$I = \sum_i^{\text{all}} m_i r_i^2$$

$$K = \frac{1}{2} I \omega^2$$

$$\begin{aligned} \tau &= r_{\perp} F = r F_{\perp} \\ \tau &= I \alpha \end{aligned}$$

$$\vec{F}_{\text{tot}} = m \vec{a}$$



$$W = F d_{\parallel} = F_{\parallel} d \quad a = \frac{v^2}{R} \quad \mu N$$

$$W_{\text{tot}} = \Delta(\text{KE}) \quad \text{KE} = \frac{1}{2} m v^2 \quad \Delta U = -W_{\text{if}}$$

$$\vec{p} = m \vec{v} \quad \vec{P}_{\text{init}} = \vec{P}_{\text{final}} \quad \left( \sum_j^{\text{all}} m_j \vec{v}_j \right)_{\text{init}} = \left( \sum_j^{\text{all}} m_j \vec{v}_j \right)_{\text{final}}$$

$$\begin{aligned} \rho &= m / V \\ \mathbf{P} &= \mathbf{F} / \mathbf{A} \\ \Delta \mathbf{P} &= \rho g h \\ \mathbf{B} &= \rho_{\text{liq}} \mathbf{V}_{\text{disp}} \mathbf{g} \\ \mathbf{A} \mathbf{v} &= \text{const.} \\ \mathbf{P} + \frac{1}{2} \rho v^2 &= \text{const.} \end{aligned}$$

$$\begin{aligned} \tau = 0 &\Rightarrow \Delta L = 0 \\ L = r_{\perp} p = m v r_{\perp} &\quad \tau = \frac{\Delta L}{\Delta t} \end{aligned}$$

$$L = I \omega$$

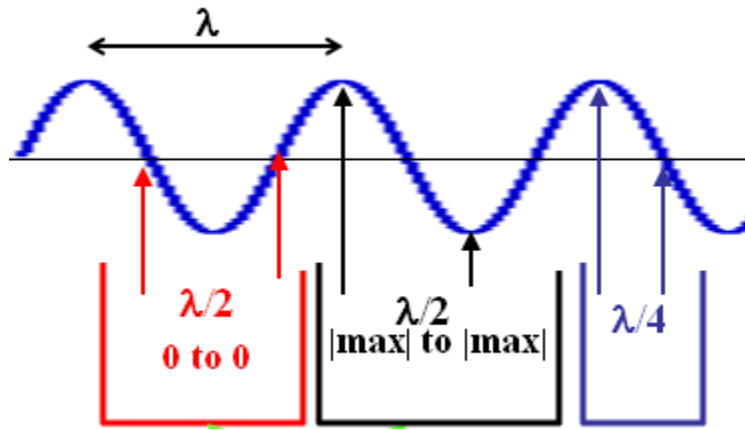
$$\begin{aligned} \sum_i^{\text{all}} \vec{F}_i &= 0 \\ \sum_i^{\text{all}} \vec{\tau}_i &= 0 \end{aligned}$$

$$\mathbf{x} = A \sin(\omega t + \delta)$$

$$\mathbf{v} = A\omega \cos(\omega t + \delta)$$

$$\mathbf{a} = -A\omega^2 \sin(\omega t + \delta)$$

$$\omega = \sqrt{k / m}$$



$$v = \lambda f$$

$$v = \sqrt{\frac{T}{\mu}}$$

$$\frac{GMm}{r^2}$$

$$\frac{GMm}{r}$$

$$\frac{GM_e}{R_e} = gR_e$$

$$M_e = 5.97(10)^{24} \text{ kg}$$

$$R_e = 6.37(10)^6 \text{ m}$$

$$G = 6.67(10)^{-11} \text{ Nm}^2 / \text{kg}^2$$

$$\Delta Q = \ell \Delta(\text{quant.})$$

$$\Delta Q_{\text{into}} = \Delta W_{\text{by}} + \Delta U$$

$$\Delta Q = (\text{quant.})C_{\text{cond}} \Delta T$$

For IG

$$\left\{ \begin{array}{l} \Delta W_{\text{by}} = P\Delta V \\ \Delta U \propto \Delta T \\ C_p = C_v + R \\ R = 8.31 \text{ J / (mole K)} \end{array} \right.$$

$$\frac{RT}{2} \text{ |deg. freedom}$$

$$e = \frac{\Delta W}{Q_H}$$

$$e = 1 - \frac{T_L}{T_H}$$

$$\Delta S \geq 0$$