

$$\bar{\vec{v}} = \frac{\Delta \vec{r}}{\Delta t} \quad \bar{\vec{a}} = \frac{\Delta \vec{v}}{\Delta t}$$

$$\Delta x = x_f - x_i \quad \text{1D}$$

$$\Delta v = v_f - v_i$$

$$a = \Delta v / \Delta t$$

$$\Delta x = \bar{v} \Delta t$$

$$\mathbf{a} = \text{constant}$$

$$\bar{v} = (v_f + v_i) / 2$$

$$v = v_o + at$$

$$x = x_o + v_o t + \frac{1}{2} at^2$$

$$v^2 - v_o^2 = 2a(x - x_o)$$

$$\text{NL} \quad \vec{F}_{\text{tot}} = m \vec{a}$$

Defining the system

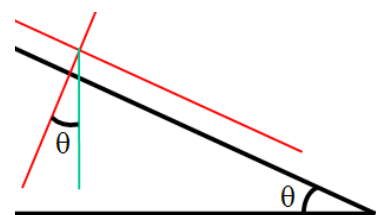


Grouping masses

Identify F – reaction F

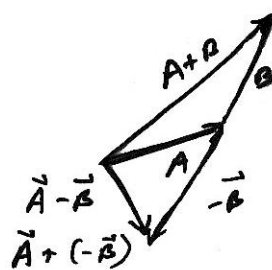


Go around corners consistently



$$\mu N$$

$$a = \frac{v^2}{R}$$



$$v = |\vec{v}| = \sqrt{v_x^2 + v_y^2}$$

$$\theta = \tan^{-1}\left(\frac{v_y}{v_x}\right)$$

$$\theta = \cos^{-1}\left(\frac{v_x}{v}\right)$$

$$\theta = \sin^{-1}\left(\frac{v_y}{v}\right)$$

$$v_x = v \cos(\theta)$$

$$v_y = v \sin(\theta)$$

$$x \rightarrow x, y$$

$$x_o \rightarrow x_o, y_o$$

$$v \rightarrow v_x, v_y$$

$$v_o \rightarrow v_{ox}, v_{oy}$$

$$a \rightarrow a_x, a_y \quad \text{2D}$$

$$\bar{\omega} = \frac{\omega_f + \omega_i}{2}$$

Rotation

$$\omega = \omega_o + \alpha t$$

$$\theta = \theta_o + \omega_o t + \frac{1}{2} \alpha t^2$$

$$\omega^2 - \omega_o^2 = 2\alpha(\theta - \theta_o)$$

$$\omega = \frac{\Delta \theta}{\Delta t}$$

$$\alpha = \frac{\Delta \omega}{\Delta t}$$

$$\omega = 2\pi f \quad f = \frac{1}{T}$$

$$\tau = r_{\perp} F = r F_{\perp}$$

$$I = \sum_i^{\text{all}} m_i r_i^2$$

$$\tau = I \alpha$$

$$KE = \frac{1}{2} I \omega^2$$

$$x = r \theta$$

$$v = \omega r$$

$$a = \alpha r$$

$$L = r_{\perp} p = m v r_{\perp}$$

$$L = I \omega$$

$$\tau = \frac{\Delta L}{\Delta t}$$

$$\tau = 0 \Rightarrow \Delta L = 0$$

Statics

$$\sum_i^{\text{all}} \vec{F}_i = 0$$

$$\sum_i^{\text{all}} \vec{\tau}_i = 0$$

$$KE = \frac{1}{2} m v^2$$

$$W = F d_{\parallel} = F_{\parallel} d$$

$$W_{\text{tot}} = \Delta(KE)$$

$$\Delta U = -W_{\text{if}}$$

$$U = mg(y - y_o)$$

$$E = KE + U$$

$$U = \frac{1}{2} k x^2$$

$$W_{\text{nc}} = \Delta E$$

$$\vec{p} = m \vec{v}$$

$$\vec{P}_{\text{init}} = \vec{P}_{\text{final}}$$

$$\left(\sum_j^{\text{all}} m_j \vec{v}_j \right)_{\text{init}} = \left(\sum_j^{\text{all}} m_j \vec{v}_j \right)_{\text{final}}$$

$\mathbf{F} = \frac{\mathbf{GMm}}{\mathbf{r}^2}$		$\mathbf{G} = 6.67(10)^{-11} \text{ Nm}^2 / \text{kg}^2$
$\mathbf{U} = -\frac{\mathbf{GMm}}{\mathbf{r}}$	$\frac{\mathbf{GM_e}}{\mathbf{R_e}} = \mathbf{gR_e}$	$\mathbf{M_e} = 5.97(10)^{24} \text{ kg}$
		$\mathbf{R_e} = 6.37(10)^6 \text{ m}$