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# Lecture 8

## Regularization

Many methods have been developed to reduce overfitting during training

- General idea: overfitting results from many parameters working together to overfit data

- Some commonly used methods

- Weight regularization / penalty

$$\text{loss} + \epsilon \sum \|w\|^2 \quad \text{"L2 weight regularization"} \quad (\text{biases to})$$

$$\epsilon \sum \|w\| \quad \text{"L1"} \quad \text{" " " " " "}$$


- Dropout - randomly drops activations (nodes) during training.  $\rightarrow$  restored at evaluation time

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# Convolutional Neural Networks

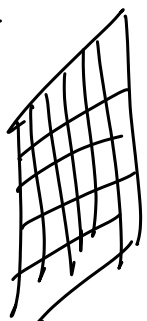
DNN flattens image  $\rightarrow$  vector, doesn't preserve locality.

CNN preserve 2d structure  $\rightarrow$   
rather than learn  
giant matrix

 learn much smaller "filter" matrix  
local feature map

idea: drag filter across image, each filter learns 1 "feature"  
produce 2d maps of features in image

Ex:



$X_{ij}$   $i, j = 1, \dots, N_{\text{pixels}}$



3x3 filter

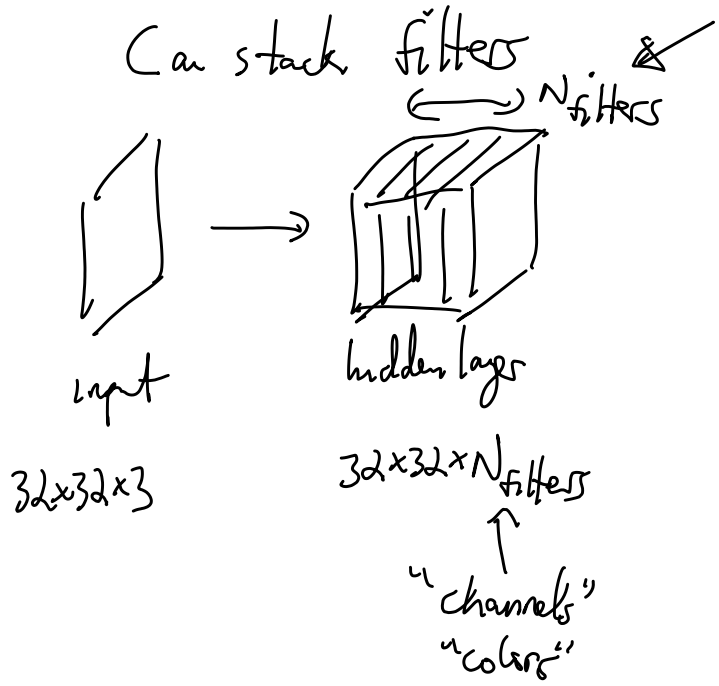
$(w_{ab}, b)$

$a, b = 1, 2, 3$

$$A \left( \sum_{a,b=1}^3 X_{i+a, j+b} w_{ab} + b \right) = X_{i,j}^{(1)}$$

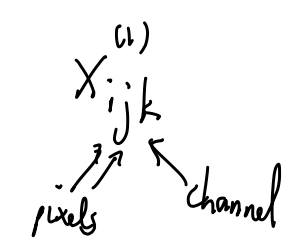
produces hidden layer  
which is an image!

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"convolutional layer"

can stack conv. layers!



$$A \left( \sum_{a,b,c} X_{i+a, j+b, k+c}^{(l)} w_{abc} + b \right)$$

Pooling layer — reduce image size drastically  
 @edi → reduce overfitting  
 help computational overhead

$\max(a, b, c, d)$   
 $\text{avg}(\dots)$

"2x2 max pooling"  
 "avg"

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CNN is a DNN w/ massive weight sharing

